

United Nations/Latvia Workshop on the Applications of Global Navigation Satellite Systems, Riga, Latvia (May 14-19, 2012)



GNSS Positioning in Support of Surface Soil Moisture Retrieval and Flood Delineation in Near Real Time

Michael Hornáček^{1,2}, Wolfgang Wagner¹, Daniel Sabel¹

Vienna University of Technology

¹Institute of Photogrammetry and Remote Sensing

²Institute of Software Technology and Interactive Systems

michael.hornacek@tuwien.ac.at

www.ipf.tuwien.ac.at/radar

Outline

- **Context: Climate Change and Water**
- **Gentle Look at Remote Sensing of Water Using Spaceborne Active C-band Radar Instruments**
- **Surface Soil Moisture Retrieval and Flood Delineation at TU Wien**
- **Forthcoming Sentinel-1 Constellation**
- **GNSS and Near Real Time Timeliness, Data Volume Handling**
- **Outlook: GNSS for Crowdsourced Flood Map Augmentation**

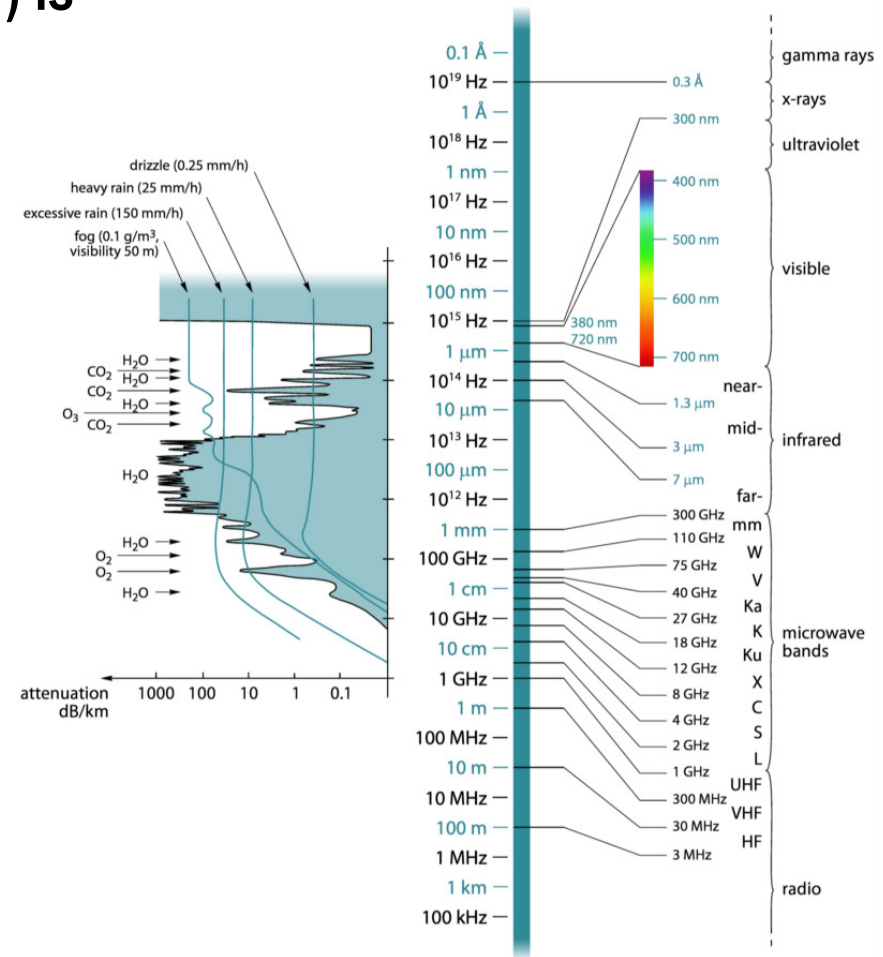
Climate Change and Water (IPCC Techn. Paper)

- “Changes in [freshwater] quantity and quality due to climate change are expected to affect **food availability, stability, access and utilisation**”
- “Climate model simulations for the 21st century are consistent in projecting **precipitation increases in high latitudes** [...] and decreases in some sub-tropical and lower mid-latitude regions”
- “Climate change **challenges the traditional assumption** that past hydrological experience provides a good guide to future conditions”
- “**Several gaps in knowledge** exist in terms of observations and research needs related to climate change and water”

Active Microwave Remote Sensing at C-band

Backscatter from active microwave instruments operating at C-band (e.g., ENVISAT ASAR, MetOp ASCAT, Sentinel-1) is

- effectively **invariant to weather conditions** or the presence of incident sunlight
- to some extent able to penetrate vegetation; **penetrates soil to ca. 2 cm**
- sensitive to the **dielectric contrast** between wet and dry soil
- subject to **specular effects** over smooth water

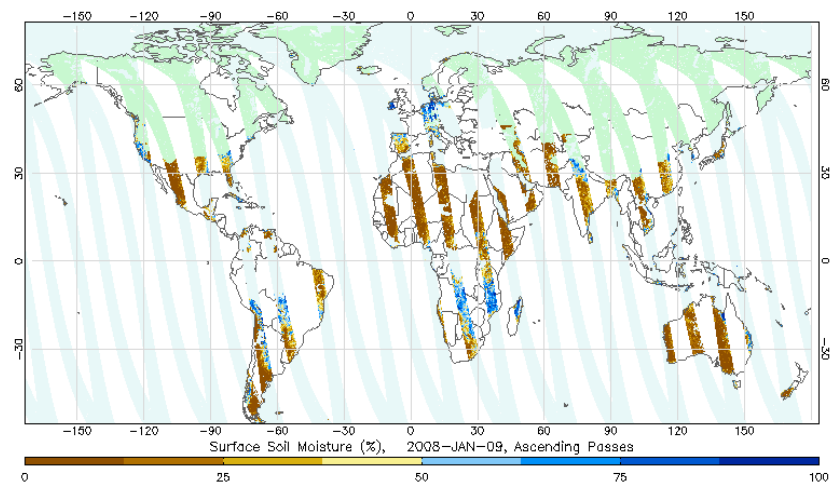


Surface Soil Moisture

- Key parameter in global water, energy and carbon cycles
- Ranges from so-called **wilting point** to **saturation of the soil's pores**
- Can be measured accurately at **point scale** using *in situ* techniques; however, few *in situ* networks exist worldwide, cross-calibration issues between networks, etc.
- Alternatively, can be measured at a **variety of spatial and temporal scales** using **remote sensing techniques**
- Applications include **numerical weather prediction, climate monitoring and flood forecasting**

Surface Soil Moisture via TU Wien Method

- Technique originally developed for **ERS scatterometer** (50 km res.)
- Later adapted to **MetOp ASCAT** (25 km res.); distributed operationally in **near real time (NRT)** within 130 minutes of acquisition
- Third adaptation to **ENVISAT ASAR** (1 km res.)
- For ERS and ASCAT, precise geocoding non-issue; with ASAR, geocoding via **computationally expensive Range-Doppler** with support of DORIS orbit files



ASCAT surface soil moisture NRT daily composite (showing ascending passes only)

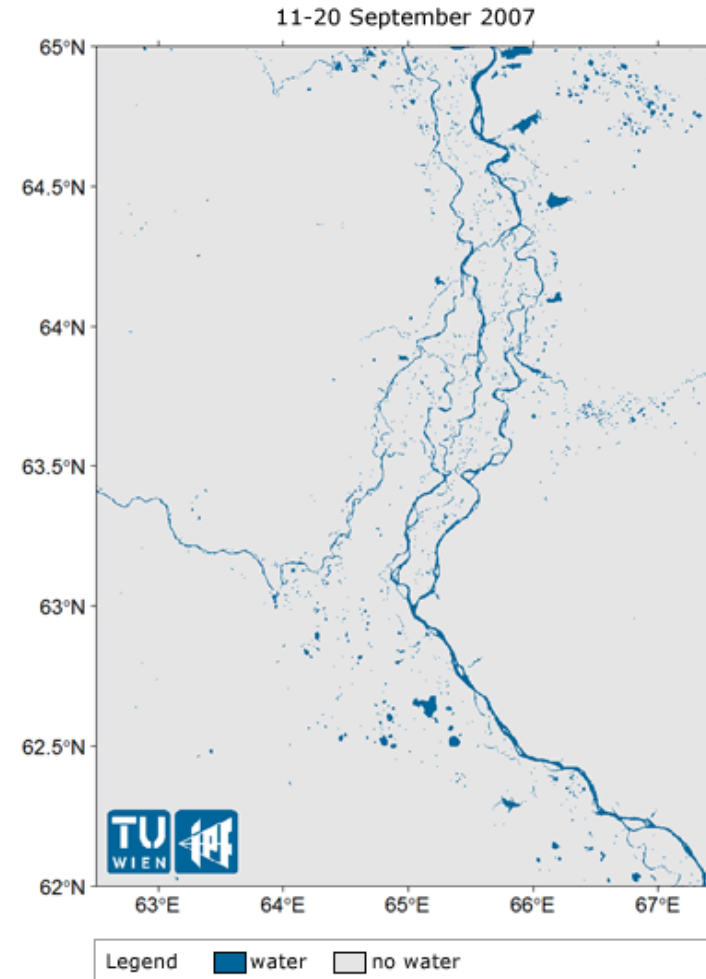
Flood Delineation

- Variety of (semi-)automatic techniques, including thresholding, change detection, probabilistic approaches, etc.
- Useful in support of **damage mitigation and assessment**
- In conjunction with adequate terrain model, can be used for derivation of **water level**
- More recently, has been used for **calibration of hydraulic models** in support of flood hazard estimation



Flood Delineation on the Ob River

- ESA-funded ALANIS project: **monitoring of floodplains and wetlands in northern Eurasia**
- Extent of open water surfaces is **critical for modeling methane emissions from high latitude**
- ENVISAT ASAR Wide Swath (WS) mode data used for 10-day composites of **flood extent**



Ob river inundation

(cf. http://www.esa.int/esaEO/SEM1MGRRJHG_index_0.html)

User Wish List (Non-Exhaustive)

SSM

- **High spatial (1 km and finer) and temporal resolution**
- **Ground penetration to at least 1 meter**
- **Product available as soon as possible from acquisition**

Flood Delineation

- **High spatial resolution (50 m and finer)**
- **Flood maps for floods as they occur**

Sentinel-1 Constellation

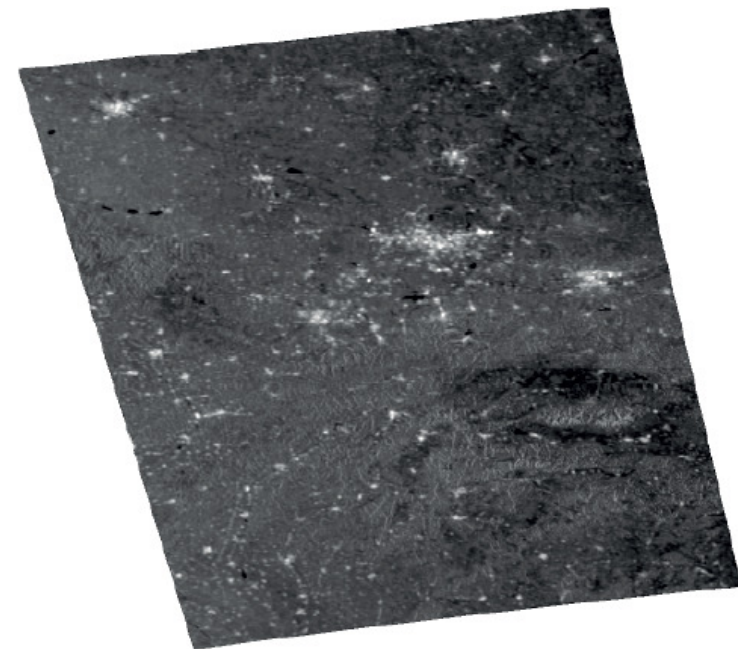
Forthcoming Sentinel-1 constellation expected to come **closest so far** to satisfying wishes of user community for large-scale operational applications

- **C-band** SAR (center frequency of 5.405 GHz)
- Coverage over land global ca. every 6 days, **nearly daily over Europe** and Canada
- Operational concept supports possibility of **NRT (up to 3 hours from acquisition)**
- Exclusive (non-conflicting) acquisition mode over land in the baseline



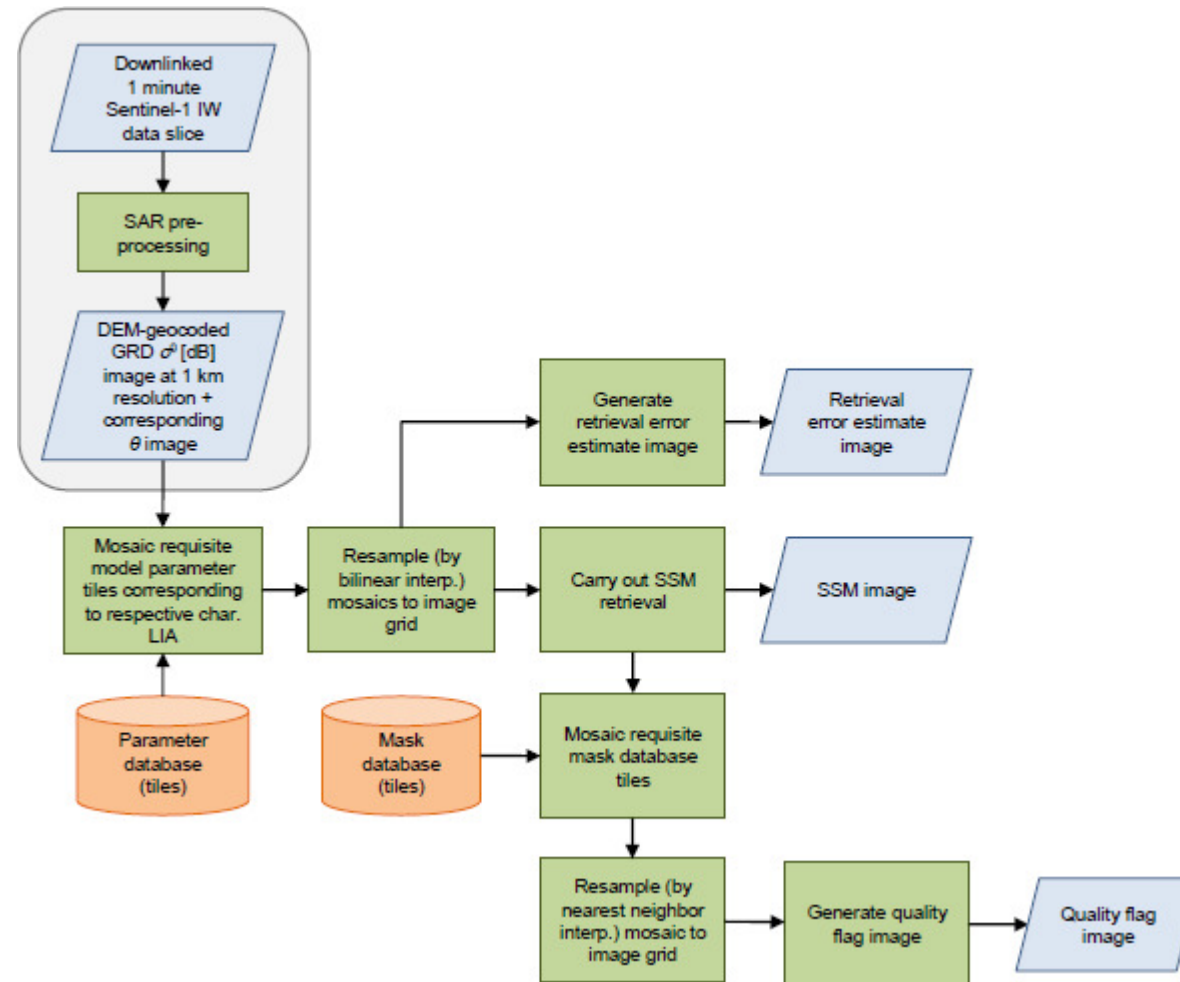
Near Real Time (NRT) Processing for Sentinel-1

- NRT in direct downlink: **within 15 min** (in support of emergency services)
- NRT in general: **within 3 hrs**
- Data provided in **partially overlapping slices** of configurable length; expected to be 1 min → amounts to ca. 408 km in the along track, 250 km in the across track
- **But: Sentinel-1 Precise Orbit Determination** center generates orbit state vectors (10 cm 3D accuracy **within 3 hours**, 5 cm **within 3 weeks**) using onboard GPS data downlinked once per orbit

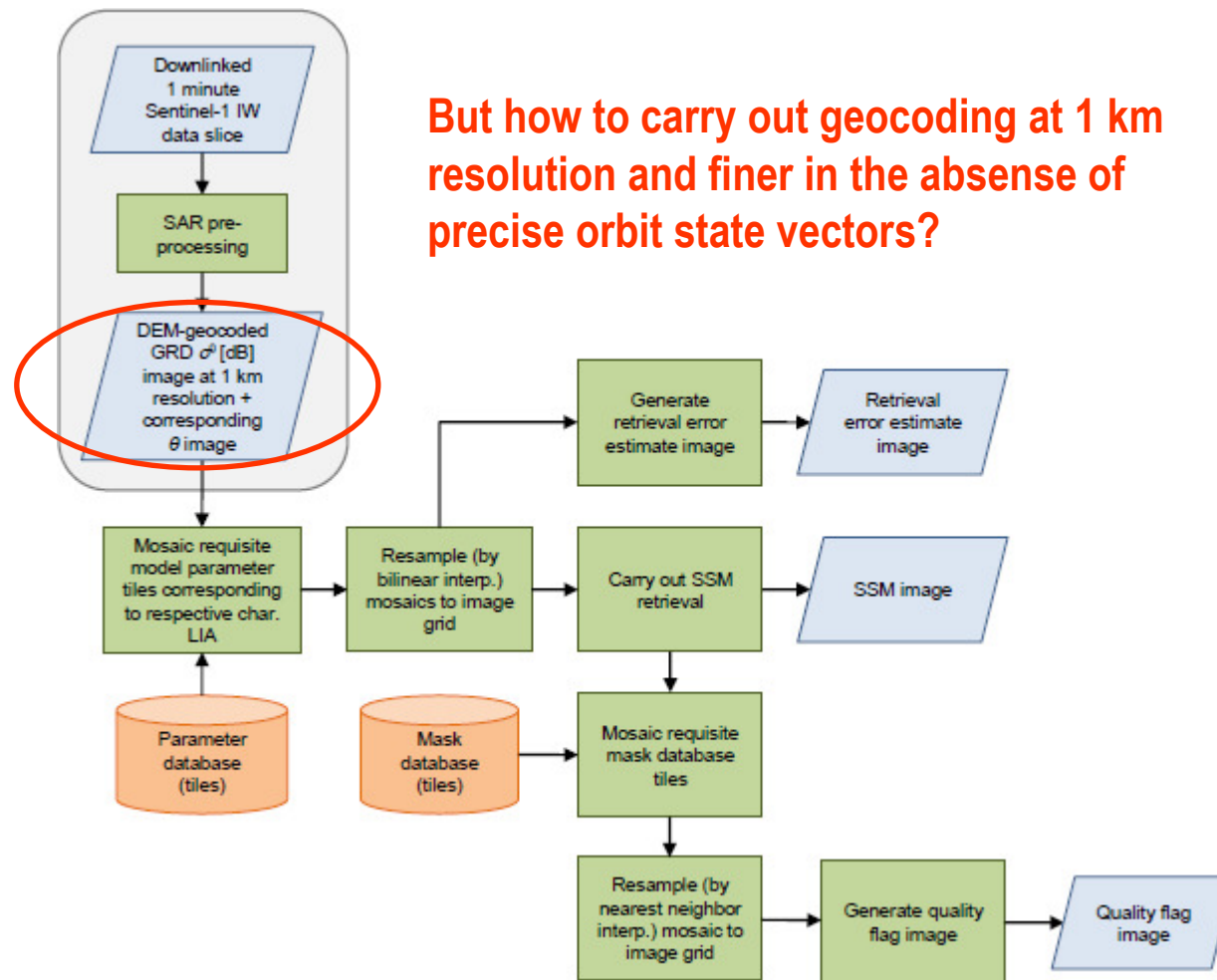


Simulated 1 minute DEM-geocoded Sentinel-1 IW mode GRD slice at 1 km resolution over central Europe, provided in plate carrée projection

Foreseen NRT SSM Processing Chain

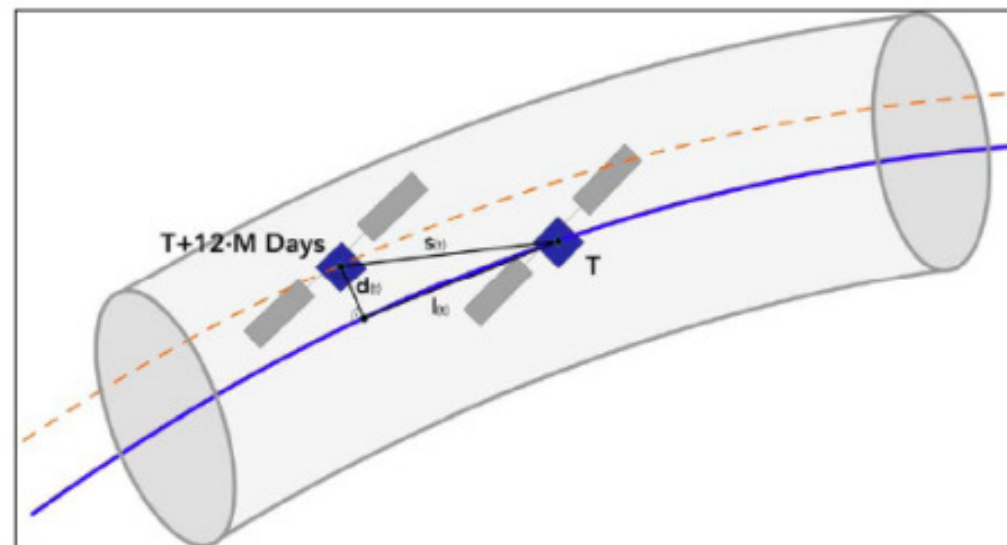


Foreseen NRT SSM Processing Chain



GPS-driven Reference Orbit Stability

Reference orbit of both satellites to be maintained within the same **Earth-fixed orbital tube radius of 50 meter-rms** along grid of predefined orbit tie points, achieved with support of **GPS positioning**

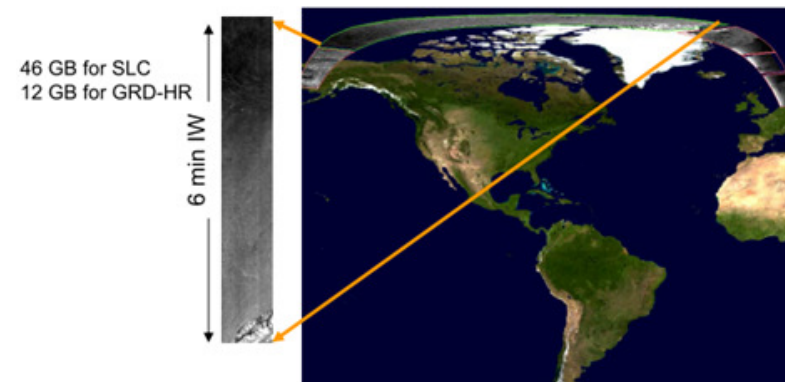


LUT Geocoding for NRT Processing

- Approximate **orbit state vectors can be predicted** owing to the stability of the acquisition geometry
- Renders **fast lookup table (LUT) geocoding** possible in support of **NRT applications**
- In non-NRT, latest available revised orbit state vectors can be used for refined Level 2 product generation

Data Volumes

- Data volumes for only Level 0 data across all acquisition regions for a **single Sentinel-1 satellite** expected to reach **ca. 320 TB per annum**, amounting to ca. 2.3 PB in the course of the mission's nominal lifetime
- Total Level 1 data volumes for baseline products expected to be **4-5 times larger** than for Level 0
- Data volumes such that **only Level 0 raw data is to be stored**
- LUT geocoding concept renders fast on-the-fly processing of Level-0 raw data up to Level 1/2 possible—in case of need—for supporting datasets in NRT, **using latest available orbit state vectors**



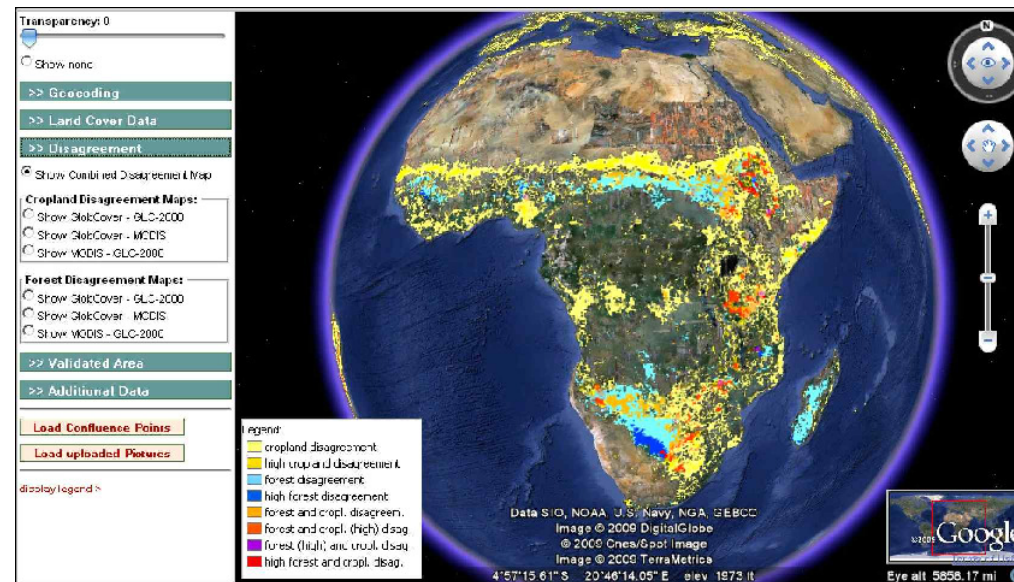
Outlook to Crowdsourcing for Flood Mapping

- **Automatic flood maps not perfect in general**
- Crowdsourcing provides outlook to **correction/augmentation of NRT flood maps** via user interaction on, e.g., tablet computers
- User can modify flood map (e.g., as **cubic spline curve**) to take into account what is seen on the ground
- Corrected NRT flood maps can be made available online, following a **collaborative wiki-like** philosophy

Calls for adequately accurate positioning of the user!

Geospatial Crowdsourcing Today: Geo-Wiki.org

- Voluntary global **land cover validation tool**, built on top of Google Earth
- Inputs: land cover data sets (GLC-2000, MODIS and GlobCover) and supporting photographic data sets (Degrees of Confluence project, user uploaded photographs with **geolocation annotations**)
- Notion of **disagreement analysis**



Conclusion

- Sentinel-1 **reference orbit stability** rendered possible using regular GPS positioning, which in turn renders possible **predictable LUT geocoding** in support of **NRT applications**
- LUT geocoding used in support of handling **data volumes** in the Sentinel-1 baseline; makes **supporting data sets** available in support of NRT applications
- Crowdsourcing for **correction/augmentation of flood maps** a potential collaborative GNSS application

Further Reading

- M. Hornáček *et al.*, “Potential for High Resolution Systematic Global Surface Soil Moisture Retrieval via Change Detection Using Sentinel-1,” *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing*, 2012.
- Y. H. Kerr *et al.*, “Soil Moisture Retrieval from Space: the Soil Moisture and Ocean Salinity (SMOS) Mission,” *IEEE Transactions on Geoscience and Remote Sensing*, 2001.
- A. Bartsch *et al.*, “Detection of Open Water Dynamics with ENVISAT ASAR in Support of Land Surface Modelling at High Latitudes,” *Biogeosciences*, 2012.
- G. Schumann and G. Di Baldassarre, “The Direct use of Radar Satellites for Event-Specific Flood Risk Mapping,” *Remote Sensing Letters*, 2010.
- R. Torres *et al.*, “GMES Sentinel-1 Mission,” *Remote Sensing of Environment*, 2012.
- “GMES Space Component Sentinel-1 Payload Data Ground Segment Operations Concept Document,” European Space Agency, Tech. Rep. GMES-GSEG-EOPG-TN-08-0012, 2009.
- S. Fritz *et al.*, “Geo-Wiki.org: The Use of Crowdsourcing to Improve Global Land Cover,” *Remote Sensing*, 2009

Thank you for your attention