

Augmentation Systems and Safety of Life Applications of GNSS

TODD WALTER

December, 2022



Introduction

- The Global Navigation Satellite System (GNSS) provides accurate, world-wide, all-weather, 3-D positioning and time
- However, there are many challenges to using GNSS for safety of life
 - › Integrity – is it safe to use?
 - › Continuity – will there be interruptions?
 - › Availability – can you count on it when you need it?
- GPS L1 signals already widely in use in aviation
 - › New signals and constellations are being incorporated into future avionics

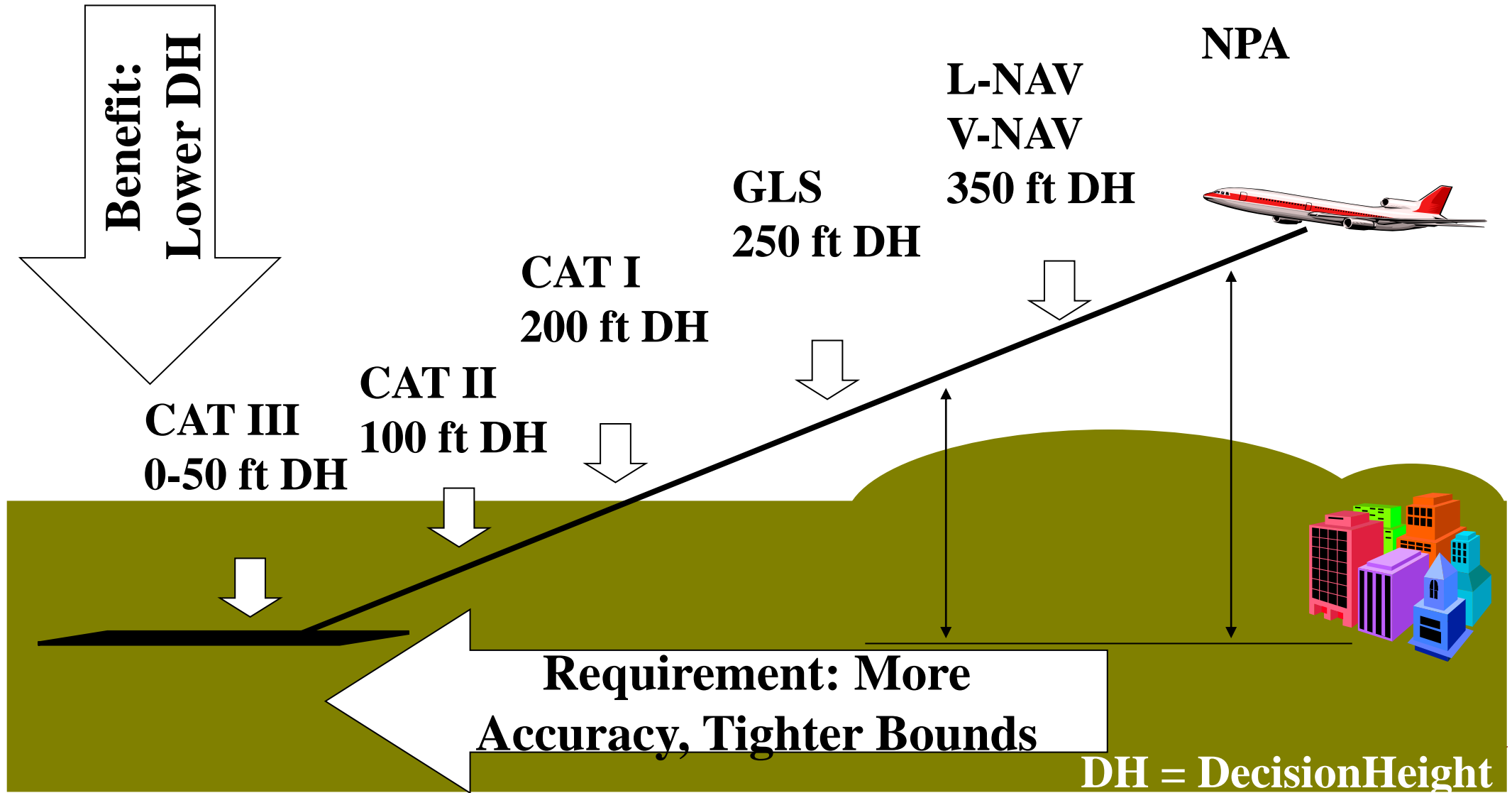


Parameters Used to Evaluate Aviation Performance

- **Accuracy:** characterize typical behavior of the system in the presence of nominal errors
- **Integrity:** limit risk from abnormal behavior affecting the system
 - › Integrity risk
 - › Maximum tolerable error
 - › Time to alert (TTA)
- **Continuity:** limit risk of losing the service unexpectedly
- **Availability:** fraction of time that one has the accuracy, integrity, and continuity required to perform the desired operation



Vertical Guidance



Example Requirements for a 200 Foot Decision Height

- **Accuracy:** < 4 m 95% horizontal and vertical positioning error
- **Integrity:**
 - › Less than 10^{-7} probability of true error larger than 40 m horizontally or 35 m vertically
 - › 6 second time-to-alert
- **Continuity:** < 10^{-5} chance of aborting a procedure once it is initiated
- **Availability:** > 99% of time



What is Augmentation?

- Add to GNSS to enhance service
 - › Improve integrity via real time monitoring
 - › Improve availability and continuity
 - › Improve accuracy via corrections
- Aircraft Based Augmentations (ABAS)
 - › e. g. Receiver Autonomous Integrity Monitoring (RAIM), inertials, barometric altimeter
- Ground Based Augmentations (GBAS)
 - › e. g. LAAS
- Satellite Based Augmentations (SBAS)
 - › e. g. WAAS, EGNOS, MSAS, GAGAN



Why Augmentation?

- Current GNSS constellations cannot support requirements for all phases of flight
 - › Integrity is not guaranteed
 - Not all satellites are necessarily monitored at all times
 - Time-to-alert is from minutes to hours
 - Faults may occur with unacceptably high probabilities
 - › Accuracy is not sufficient
 - Vertical accuracy > 5 m
 - › Availability and continuity must meet requirements

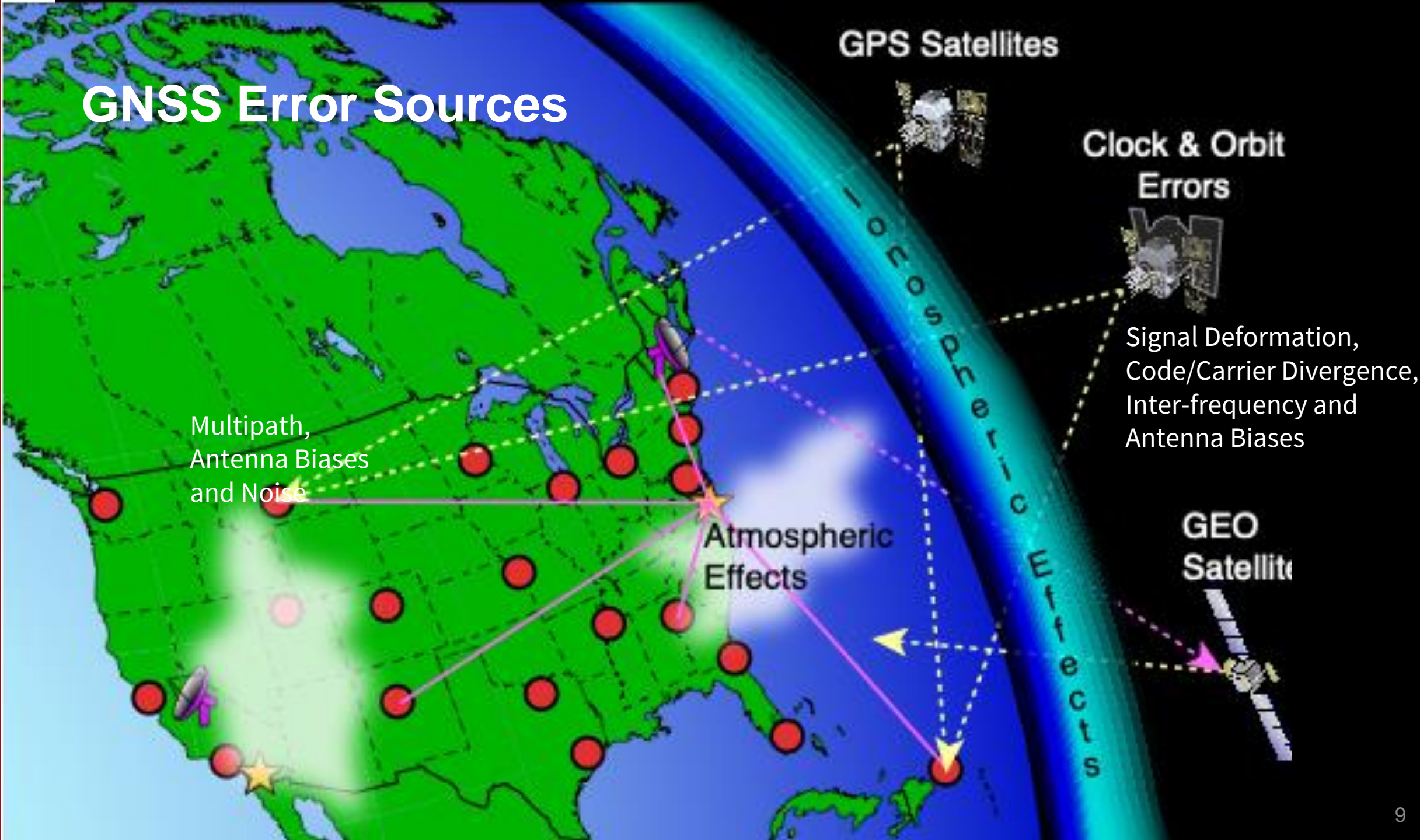


Augmentation Systems for Aviation

- **Aircraft Based Augmentation System (ABAS)**
 - › RAIM, inertials, baro-altimeter, Advanced RAIM (ARAIM)
 - › First receiver approved for use in 1995
- **Satellite Based Augmentation Systems (SBAS)**
 - › WAAS, MSAS, EGNOS, GAGAN, ...
 - › Initial operation in 2003
- **Ground Based Augmentation Systems (GBAS)**
 - › Local-Area Augmentation System (LAAS)
 - › Design approval in 2009, full operation in 2012



GNSS Error Sources



GPS Satellites

Clock & Orbit Errors

Signal Deformation, Code/Carrier Divergence, Inter-frequency and Antenna Biases

GEO Satellite

Multipath, Antenna Biases and Noise

Atmospheric Effects

IONOSPHERIC EFFECTS



Threat Models Are Used to Evaluate Performance

- Threat models describe the feared events
 - › What does nominal performance look like?
 - › What can go wrong?
 - › How likely are threats to occur (and at what magnitude)?
 - › How do threats manifest over time?
- Mitigations describe how threats are addressed
 - › What magnitude of threat can be detected to what probability?
 - › How long to detect?
 - › What is the distribution of the residual errors?
 - › What is the residual risk?

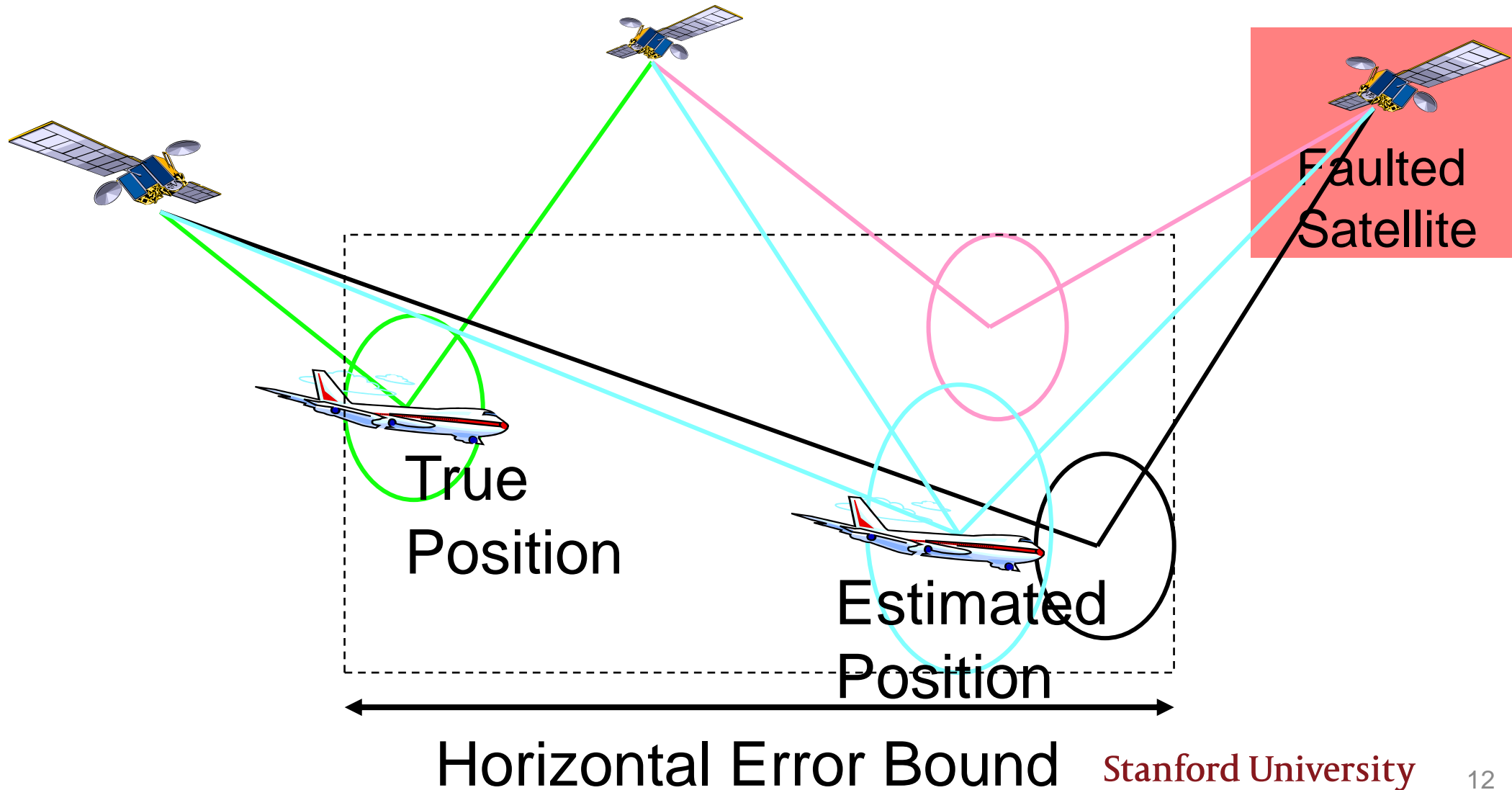


Aircraft Based Augmentation System (ABAS)

- Exploits redundancy in satellite ranging signals to identify faults
 - › May integrate other sensors to improve performance
- Receiver Autonomous Integrity Monitoring (RAIM) is the mostly widely used form of augmentation in aviation
 - › Global coverage without a need for additional ground infrastructure
 - › Largely based on L1-only GPS-only
 - GPS GLONASS standards also developed
- Advanced RAIM (ARAIM) under investigation as a possible method to support vertical guidance for aircraft
 - › Supports use of two frequencies and at least two constellations



RAIM Protection

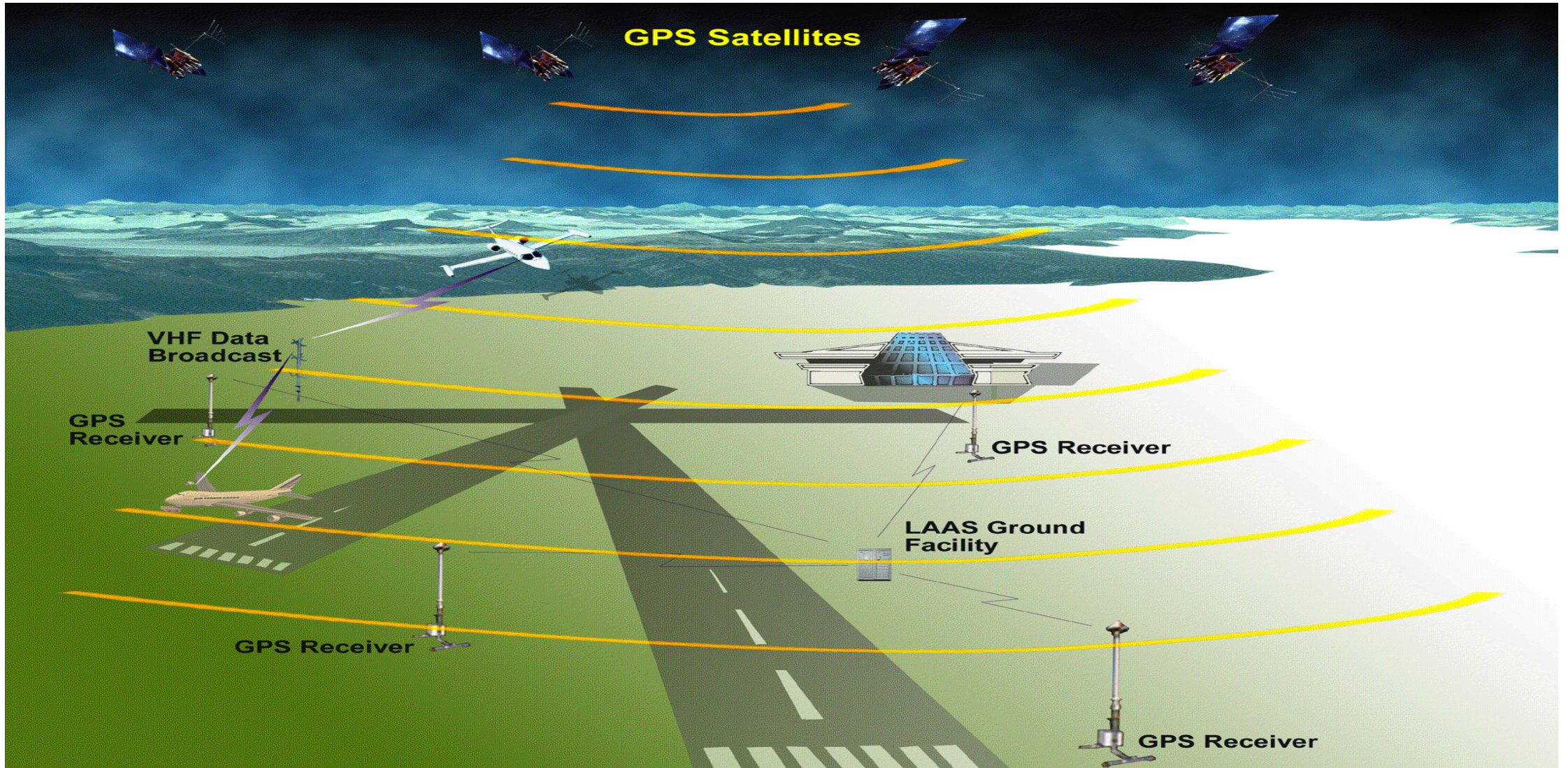


ABAS Mitigation of Threats

- Does not need to distinguish threats by source
- Requires that at least one subset be sufficiently described by specified nominal error bounds
 - › Probability of each range containing a fault must be limited
 - Independent faults affecting each satellite range measurement
 - Faults that can affect multiple satellite range measurements
 - › Unfaulted error bounds
- If the above descriptions are accurate, ABAS will properly bound any positioning error
 - › Threats are evaluated off-line, before any operation
 - › When errors are sufficiently large, they can be isolated and removed



Pictorial Depiction of GBAS/LAAS



GBAS Mitigation of Threats

- Ground receivers monitor and correct errors that originate on the satellites or in the atmosphere
 - › Single correction and bound for each satellite
 - › Monitoring accuracy limited by the effects multipath, noise, and reference station antenna bias
- Airborne receiver must limit the effects of local multipath, noise, and user antenna bias
 - › May supplement monitoring by performing checks for local ionospheric and/or tropospheric variations
- Capable of achieving the smallest time-to-alert, the best accuracy, and the smallest integrity bounds



GBAS for Newark



Thumbtacks show ILS elements that support precision approach to runways 22L, 22R, 04L, 04R & 11.

- Compared to ILS, GBAS footprint is small
- One GBAS for all runway ends
- GBAS totally on airport property
- GBAS approaches are programmable
- Smaller critical & sensitive areas
- No beam bends
- No snow or tidal effects



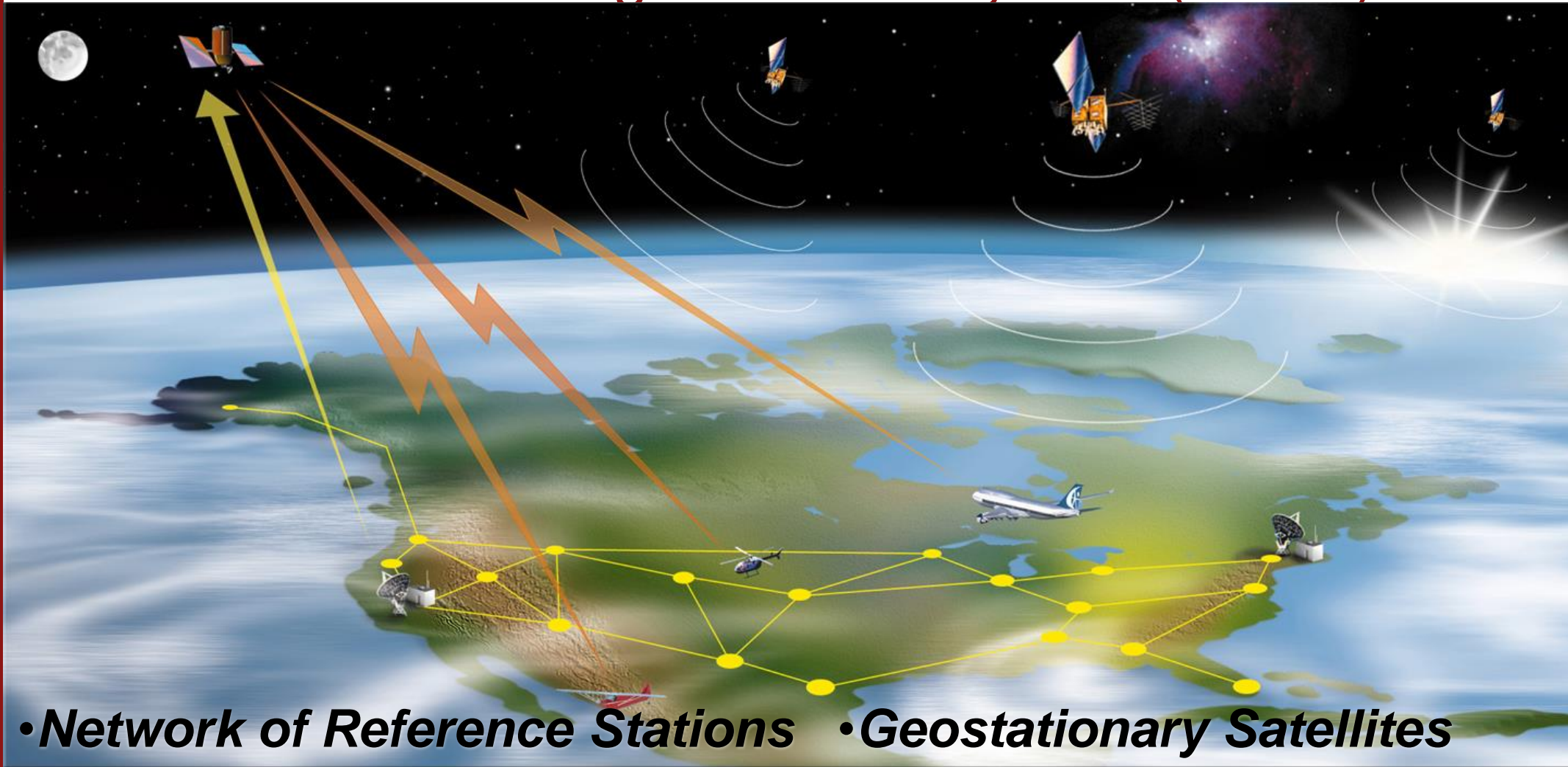
Runway 29 at Newark



Terminal Area with GNSS Enabled Curved Approach



Satellite Based Augmentation System (SBAS)



• **Network of Reference Stations**

• **Geostationary Satellites**

• **Master Stations**

• **Geo Uplink Stations**

Courtesy: FAA

Stanford University

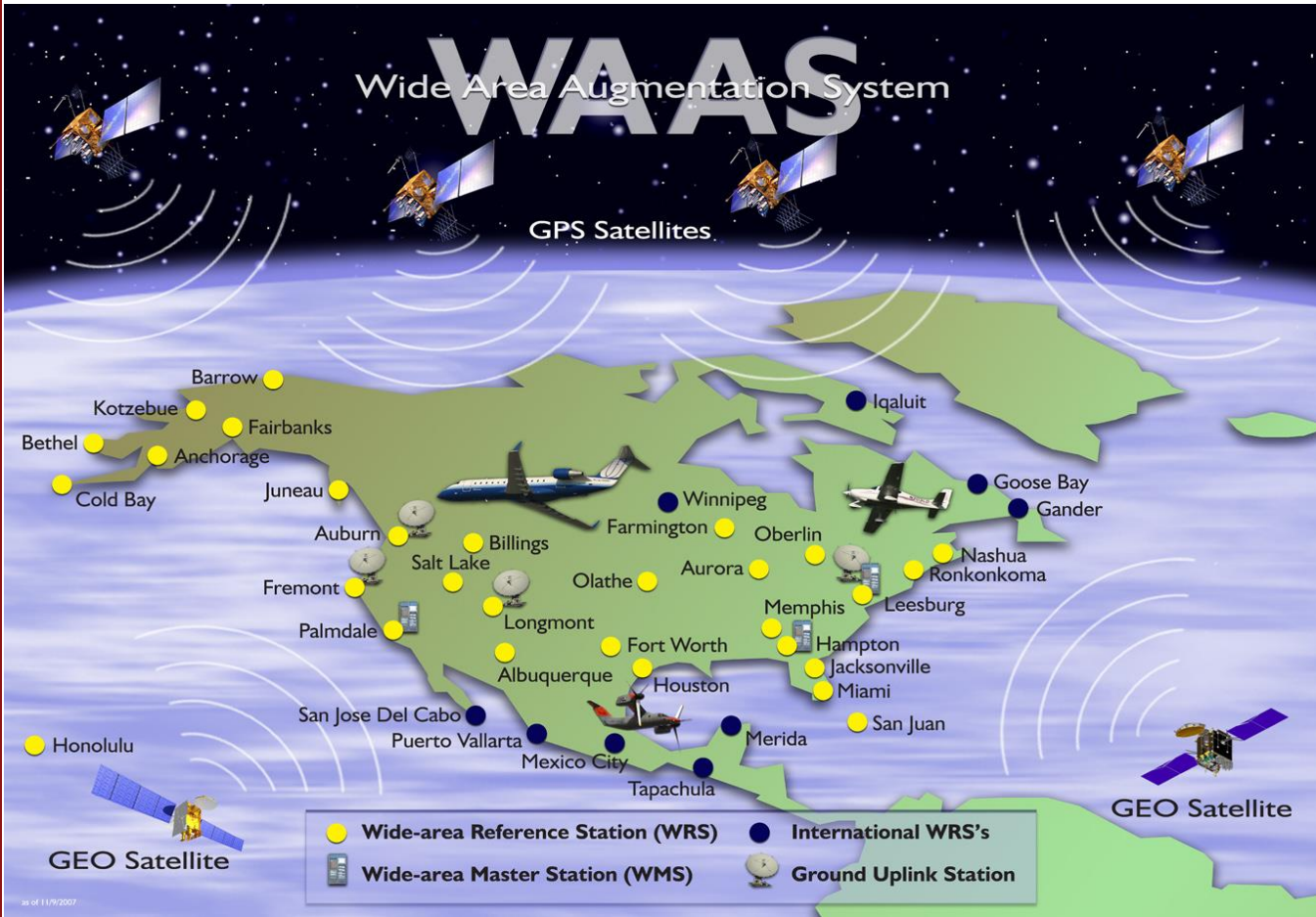


SBAS Mitigation of Threats

- Ground receivers monitor and correct errors that originate on the satellites and in the ionosphere
 - › Satellite clock and ephemeris errors separately corrected
 - › A grid of ionospheric corrections is provided
 - › Confidence bounds sent for each satellite and each grid point
 - › Monitoring accuracy limited by the effects multipath, noise, and reference station antenna bias
- Airborne receiver must limit the effects of local multipath, noise, and user antenna bias
- Capable of covering continental regions and thousands of aircraft approach procedures



WAAS Architecture



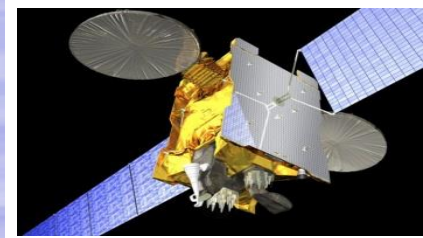
38 Reference Stations



3 Master Stations



6 Ground Earth Stations



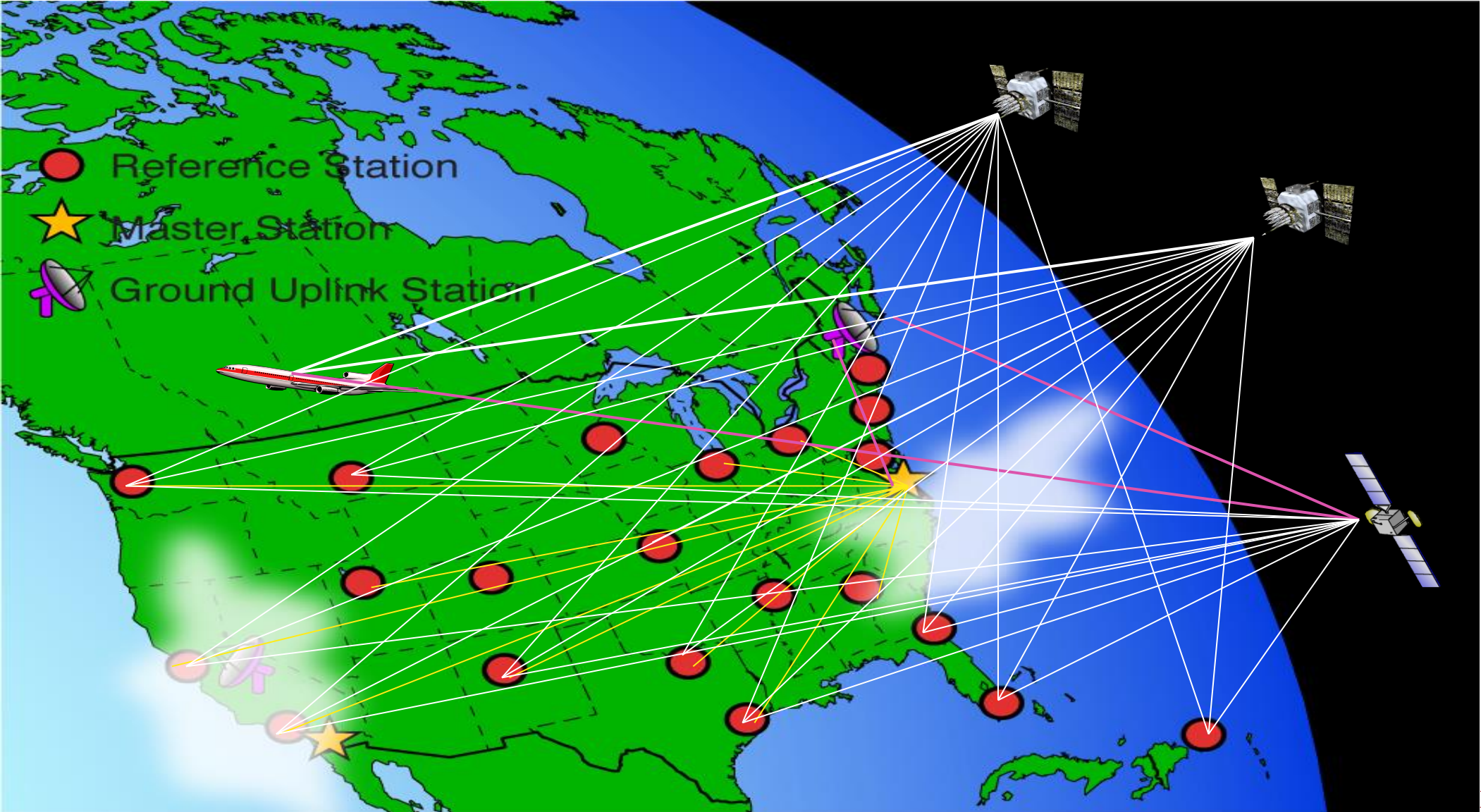
3 Geostationary Satellite Links



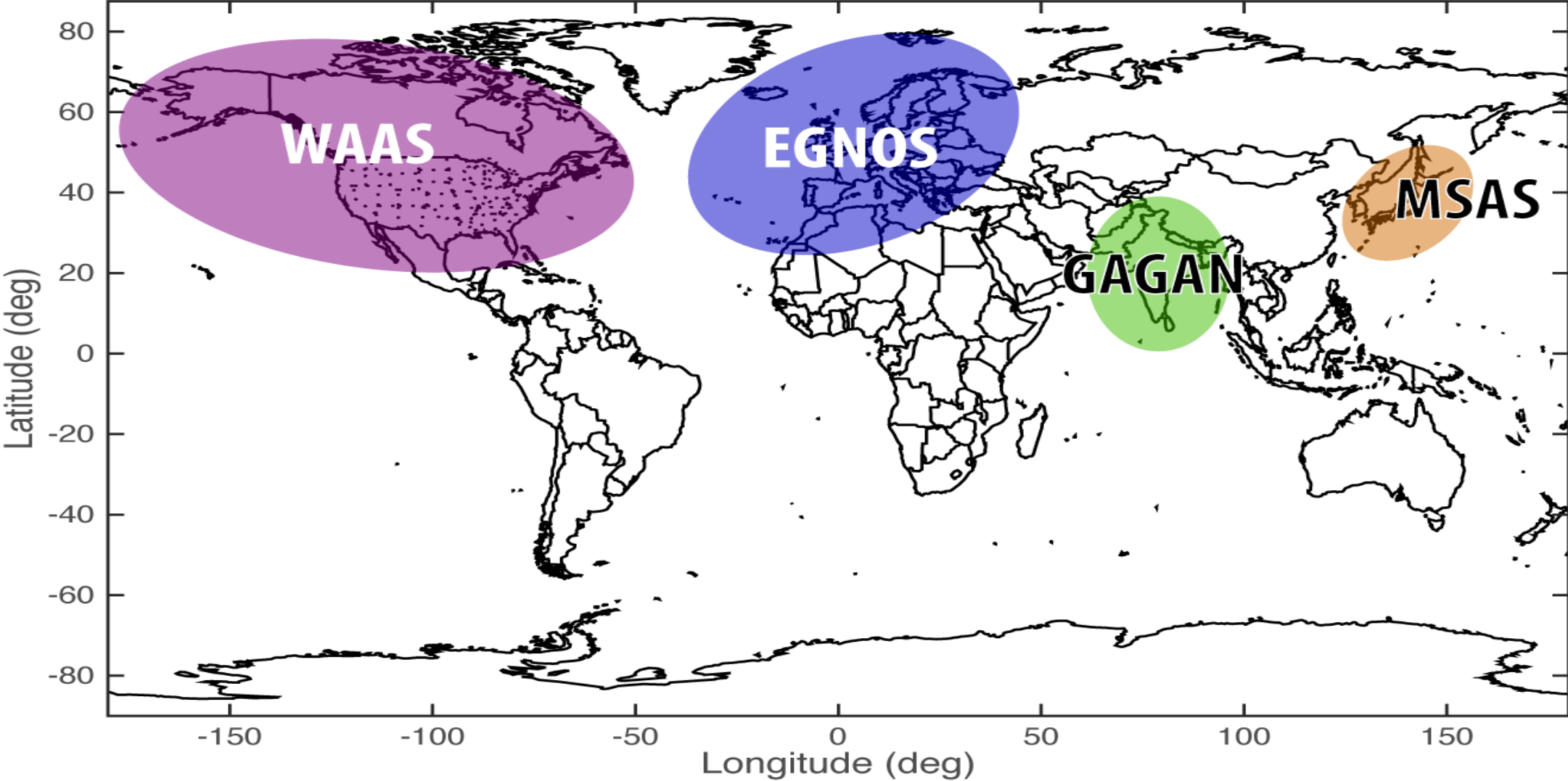
2 Operational Control Centers



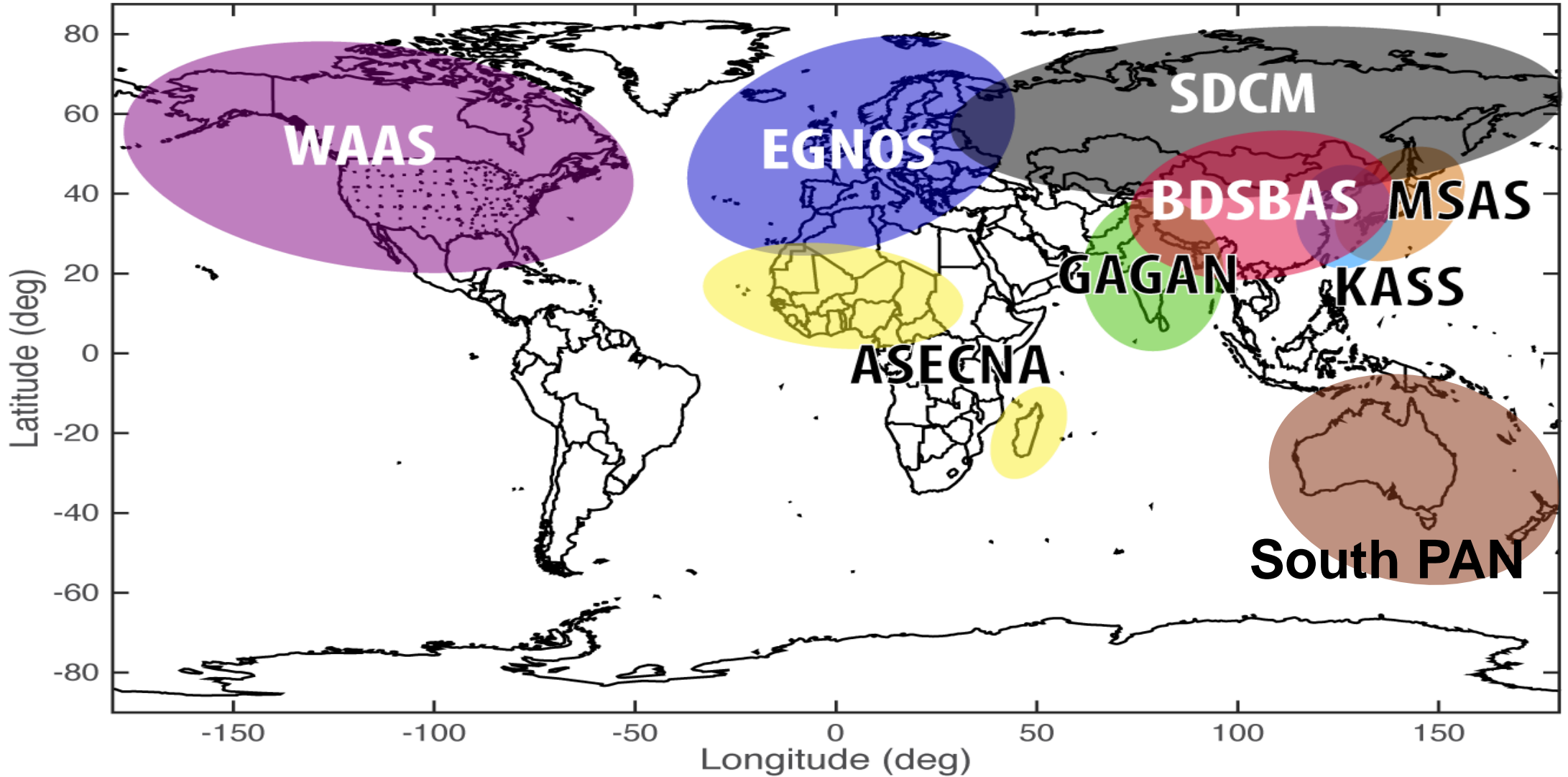
SBAS / WAAS



SBAS Networks Today

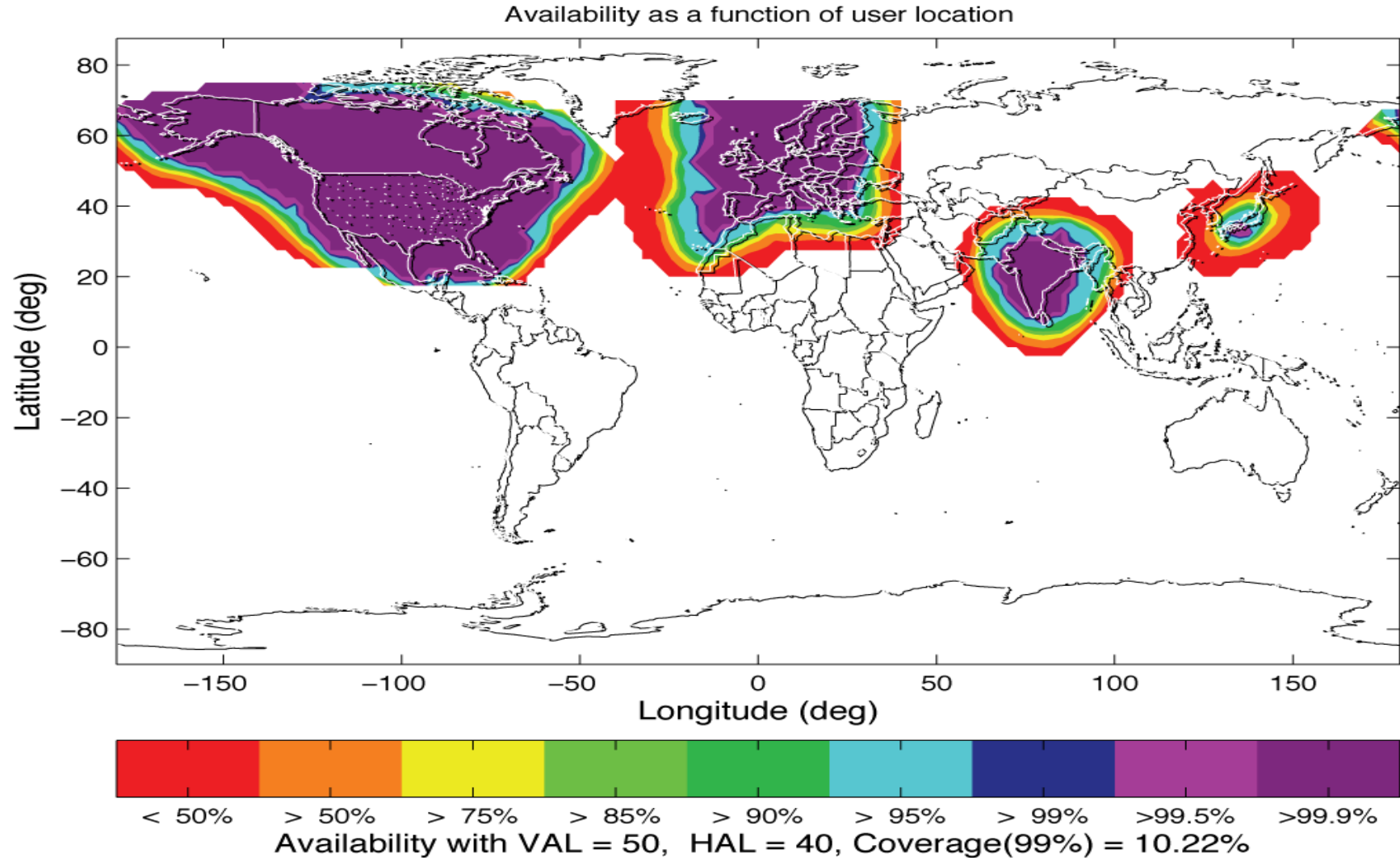


SBAS Networks in 2024?



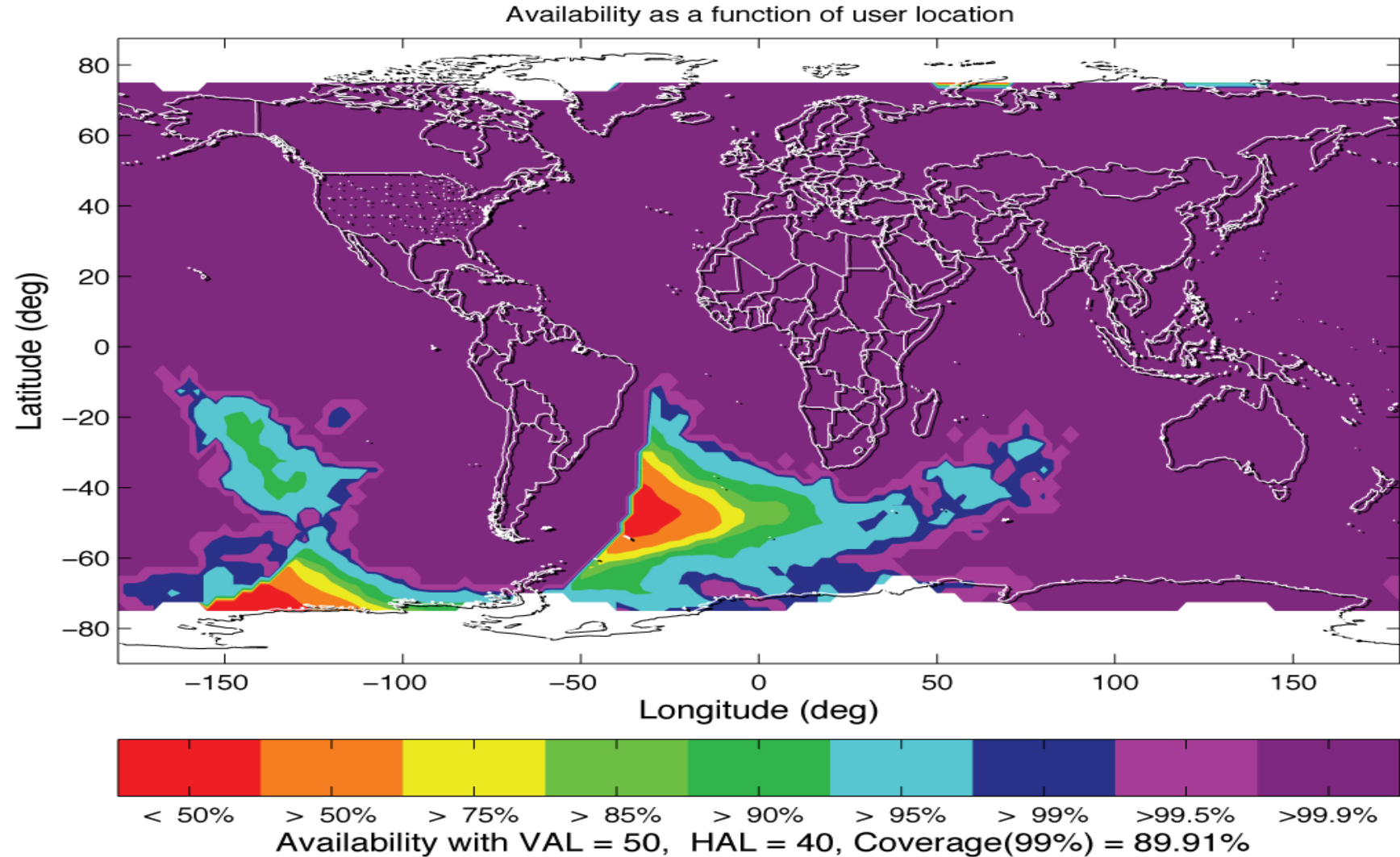
Current Coverage at 250' DH

WAAS
EGNOS
MSAS
GAGAN



Future Coverage

- WAAS
- EGNOS
- MSAS
- GAGAN
- South PAN
- BDSBAS
- KASS
- ASECNA
- SDCM



Key Aspects of Safety of Life Demonstration (1 of 2)

- **Well-defined integrity requirement**
 - › e.g. 10^{-7} WAAS integrity requirement applies to each and every approach
- **The system must be proven safe**
 - › Rationale/evidence for safety claim
 - › Threats that are sufficiently likely to occur will require a monitor to mitigate
- **Threat models are required to judge performance and safety**
- **Fault-trees are required to trace individual risks against the top level requirement**
 - › Sets allocations for individual monitors
 - › Separate trees for continuity and integrity
- **Data usually insufficient to demonstrate very small probabilities**
 - › Rarely possible to prove values $<10^{-5}$
 - › Small probabilities require analytic proof or the product of multiple actions



Key Aspects of Safety of Life Demonstration (2 of 2)

- Documentation of the overall safety analysis is critical because:
 - › Integrity analyses are often complex
 - › Many assumptions and agreements
 - › May be revisited after lengthy period of time or with new information
 - › New team members may question previous decisions/agreements
 - › Need to convince third parties

- Data should be continuously collected
 - › Necessary for anomaly resolution
 - › Replay capability is essential
 - Direct comparison of algorithm updates
 - › Should be constantly compared to safety analysis expectations
 - Demonstrates either consistency with or a need to revise threat models
 - Successful comparisons build confidence
 - › Place upper bounds on likelihood of rare events



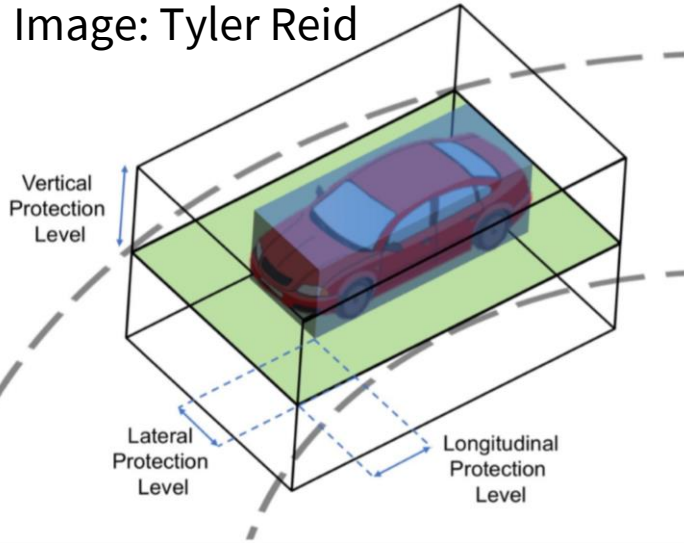
Rationale/Evidence for Safety

- **System must be proven safe**
 - › Otherwise it is assumed unsafe
- **Observability must be characterized**
 - › What magnitude of errors can the system observe the current time?
- **Measurement error to be described to required probability**
 - › Must ensure adequate characterization of noise under worst allowed conditions



Extension to Other Modes of Transportation

Image: Tyler Reid



- Aviation has led the way with clearly defined requirements and developing systems to provide service
- Other modes are specifying their requirements which are often more difficult to meet
 - Tighter protection regions and risk levels in obstructed environments
- Automotive (lane level guidance)
- Maritime (harbor entrance)
- Rail (track determination)
- Urban air mobility and UAVs



Conclusions

- GNSS provides accurate, world-wide, all-weather, 3-D positioning and timing
- There are many challenges to using GNSS for safety of life
 - › Integrity – GPS error sources have been well characterized and continue to be scrutinized to ensure they are properly described and handled by the different augmentation systems
 - › Continuity and availability – GPS satellites have proven to be very reliable, and the residual threats can be kept adequately small to support most aviation operations
- GPS L1 signals widely in use in aviation
 - › ABAS, GBAS, and SBAS in operation throughout the globe
 - › Utilization of new signals and new constellations is underway

