



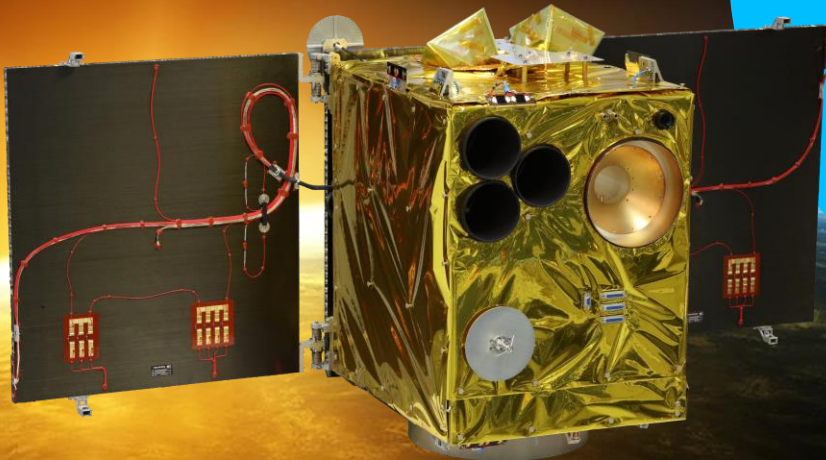
**University of Stuttgart**  
Institute of Space Systems



**Stuttgart University  
small satellite  
mission capacities  
built up along with its  
Flying Laptop project.**

**14th Nov. 2018**

**Prof. Dr.-Ing.  
Sabine Klinkner**



# Flying Laptop

## Mission goals:

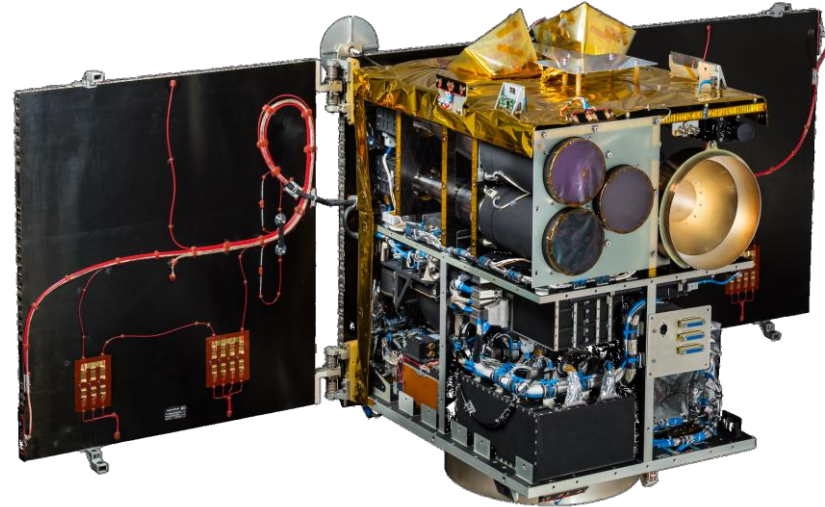
- Technology demonstration
- Earth observation
- Installation of infrastructure
- Education

## Key characteristics:

Mass	110 kg
Dimensions	60 x 70 x 87 cm <sup>3</sup>
Power	max. 270 W
Orbit	600 km sun-synchronous, LTAN 11:30
Lifetime	> 2 years, Launch 14th of July 2017

## Industrial design approach:

- Usual Design and Analysis tools
- Communication using professional approach
- Qualifications procedures based on ECSS
- System verification according to industrial approach



Gefördert durch:



Bundesministerium  
für Wirtschaft  
und Energie

aufgrund eines Beschlusses  
des Deutschen Bundestages

# Infrastructure developed at the University for the Flying Laptop mission

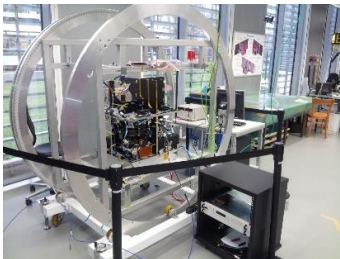
- Infrastructure for development, integration, qualification and operation of satellites
- Ground station network / Ground control software
- Automation of satellite operation



**Ground station**



**Control room**



**Clean room – ISO8**



**TV chamber**



**Simulation environment**

# International Launch campaign



- Main payload: Kanopus-VI-K
- Flying Laptop (Universität Stuttgart)
- TechnoSat (TU-Berlin)
- WNISAT-1R (Japan)
- Norsat 1+2 (Norway/Canada)
- 48 Planet Labs Cubesats
- 19 further Cubesats

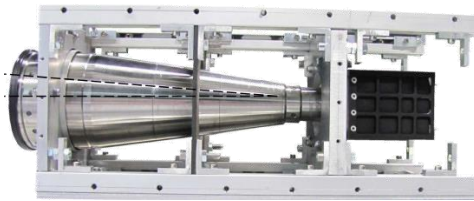
# Flying Laptop Operations Team



# Major payloads and technologies on Flying Laptop



FPGA-based  
Payload computer  
(PLOC)



Multi-spectral  
camera system  
(MICS)



AIS receiver  
- DLR Cooperation -



S-Band downlink system  
- Tesat Cooperation -  
(DDS)



Panoramic camera  
(PAMCAM)



De-Orbit Mechanism  
- Tohoku University  
Cooperation -  
(DOM)



Star sensor:  
Space Debris  
Near Earth  
Objects



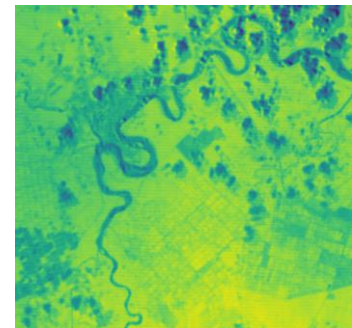
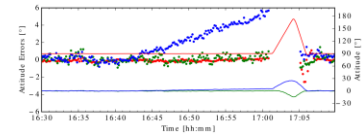
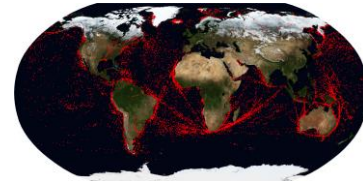
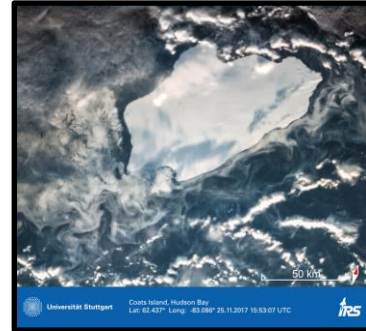
Laserlink  
- DLR Cooperation -  
(OSIRIS)



GPS-based  
Attitude determination  
- DLR Cooperation -  
(GENIUS)

# Status of our satellite

- All satellite components tested and fully operational
- Satellite system is fully stable
- Ground station in Stuttgart is used for nominal operation
  - Genius experiment (Attitude determination with GPS)
  - Encryption and compression algorithm
  - Analyses on Radiation tolerance of components
- Multispectral Imaging of Malaysia
  - AIS data combined with Camera pictures
  - Observation of Space Debris
- Active support of satellite operation by undergraduate students
  - Operations lecture, Payload practical training





**University of Stuttgart**  
Institut für Raumfahrtssysteme

# Thank you!



**Prof. Dr.-Ing. Sabine Klinkner**

e-mail [klinkner@irs.uni-stuttgart.de](mailto:klinkner@irs.uni-stuttgart.de)

phone +49 (0) 711 685-62677

fax +49 (0) 711 685-63596

University of Stuttgart  
Institut für Raumfahrtssysteme  
Pfaffenwaldring 29, 70569 Stuttgart

Twitter.com/flying\_laptop

