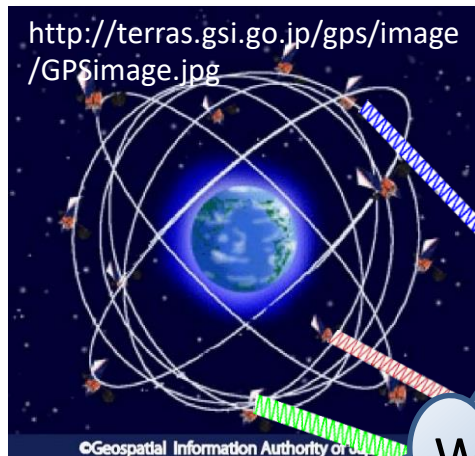


Water Vapor Analysis Over the Ocean using Shipborne GNSS Measurements for the Mitigation of Weather Disaster

[Yoshinori Shoji](#)^{*}, K. Sato^{**}, M. Yabuki^{***}, and T. Tsuda^{***}

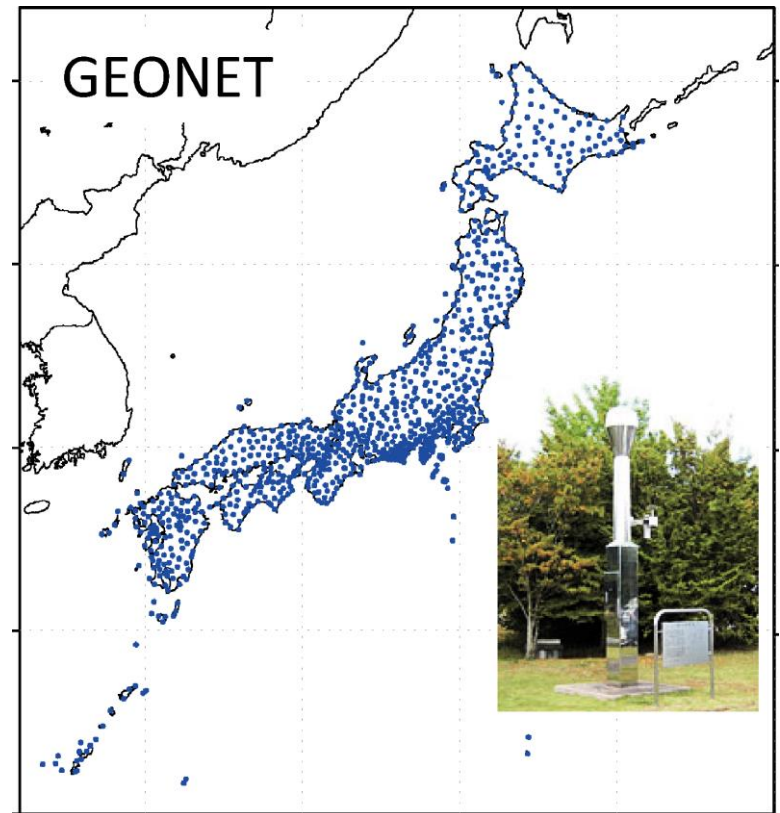
^{*}MRI/JMA, yshoji@mri-jma.go.jp, ^{**}JAXA, ^{***}RISH/Kyoto University



Signal
For
Meteorology

Water
Vapor

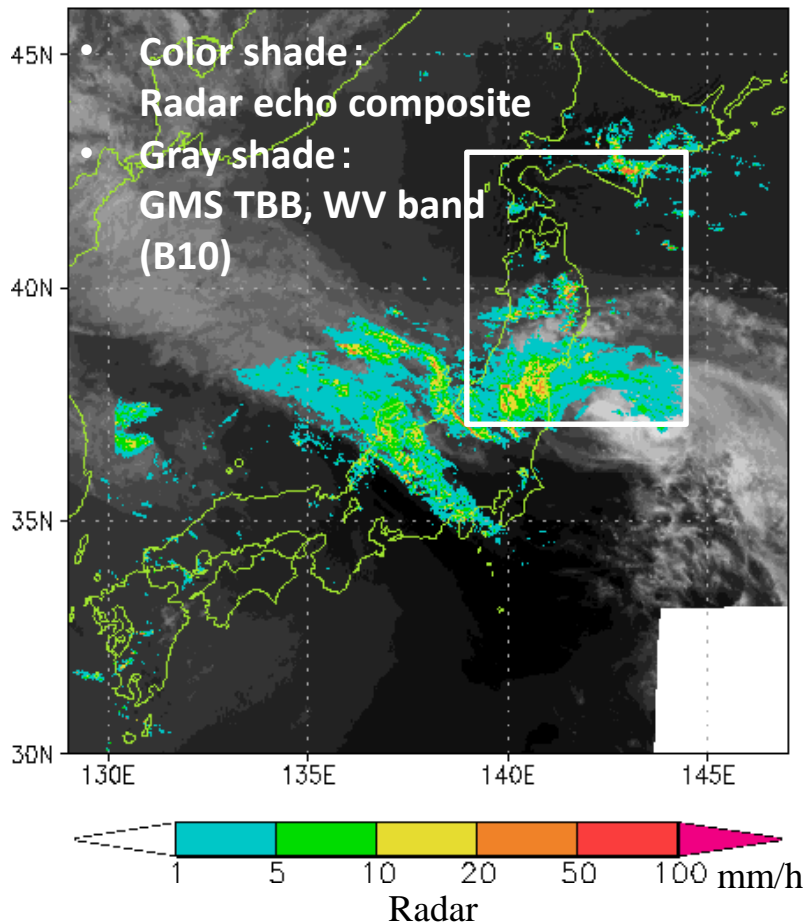
Noise
For
Positioning



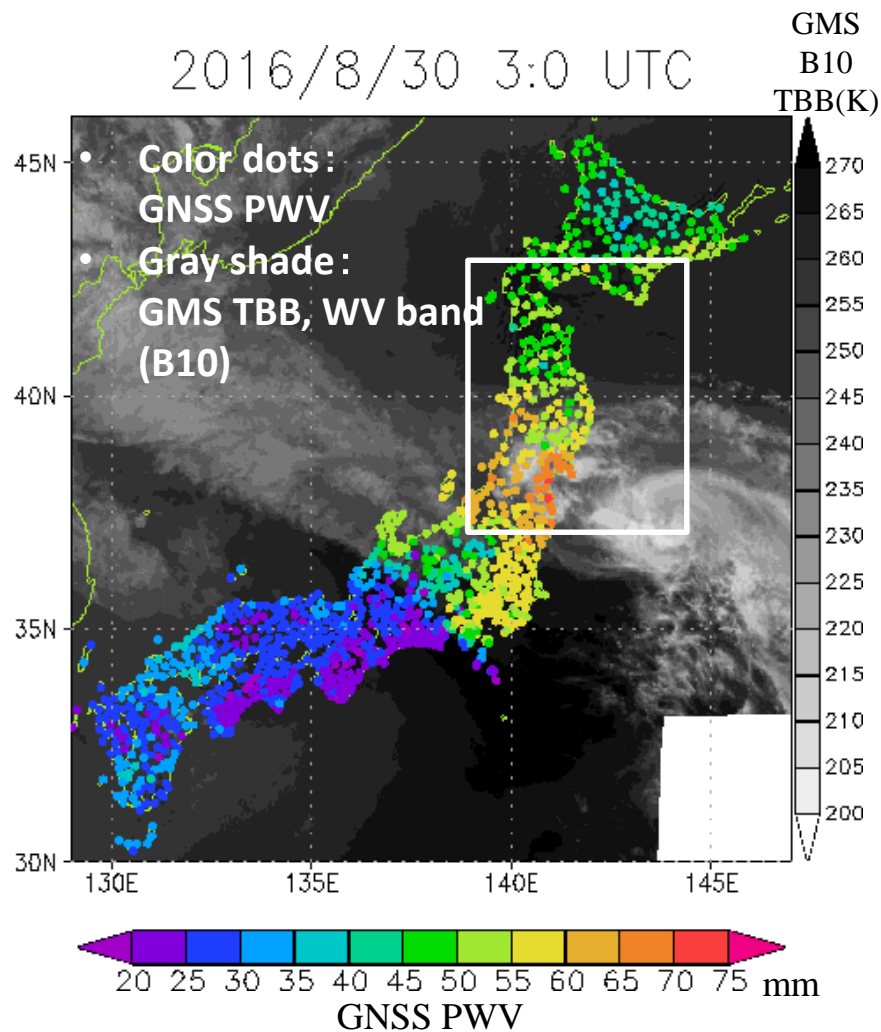
GNSS : Practical water vapor sensor

High accuracy, continuously, under all weather

TY1610(Lionrock)



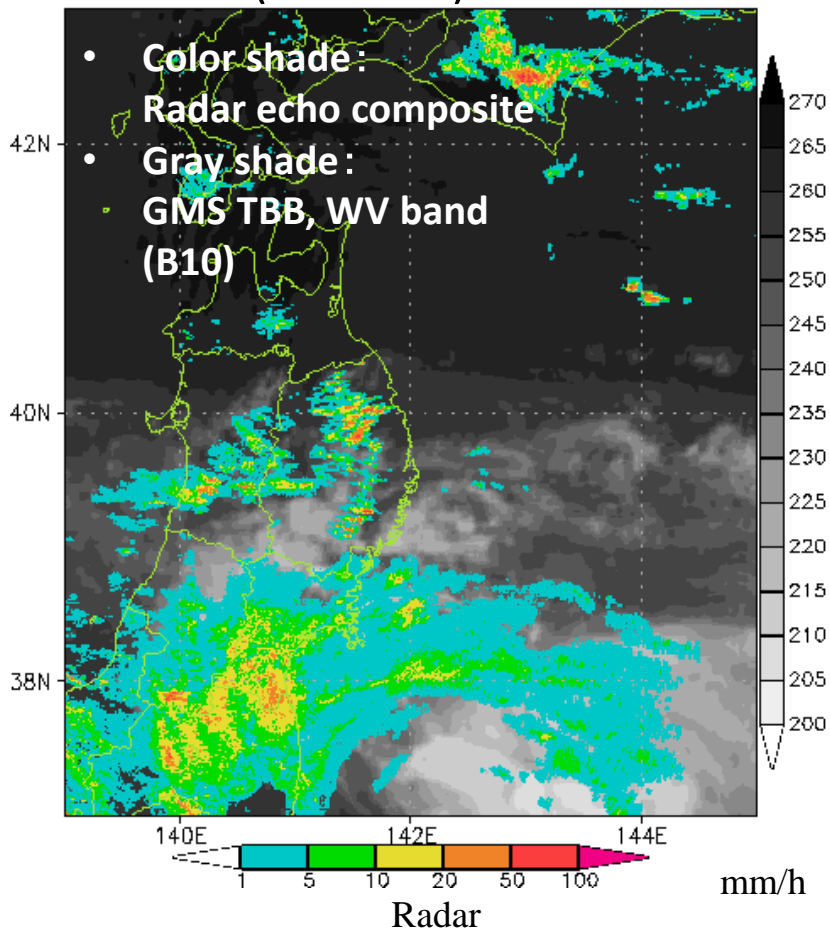
2016/8/30 3:0 UTC



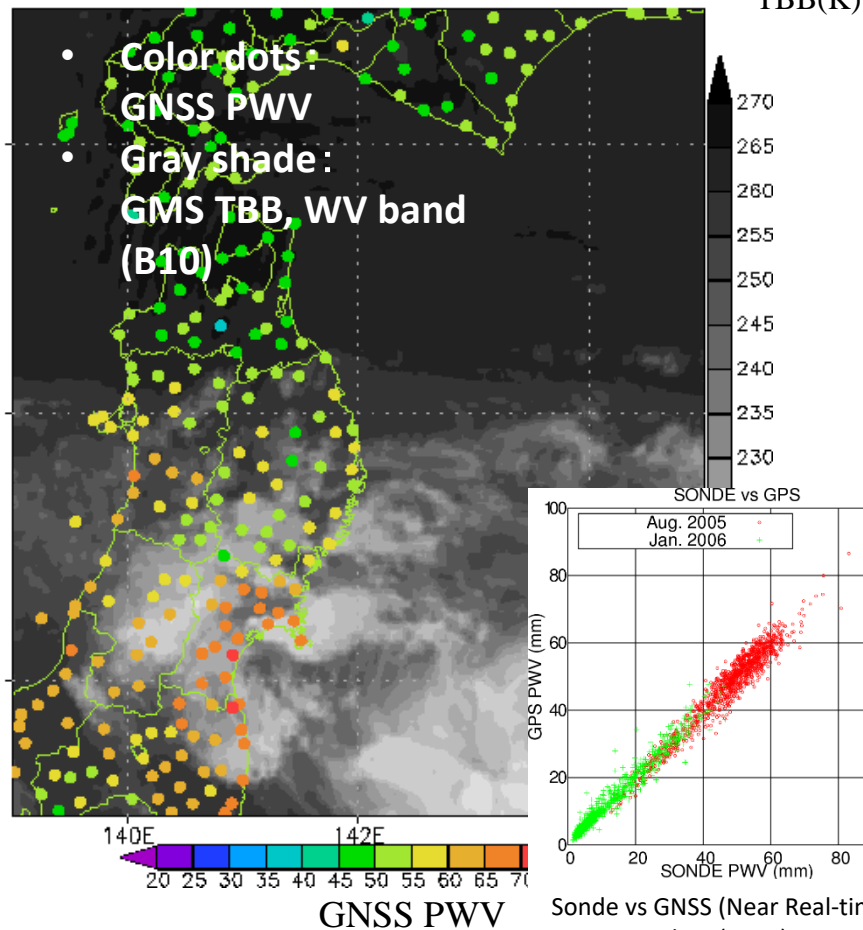
GNSS : Practical water vapor sensor

High accuracy, continuously, under all weather

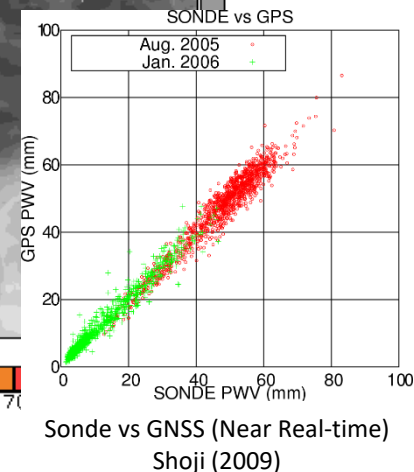
TY1610(Lionrock)



2016/8/30 3: 0 UTC

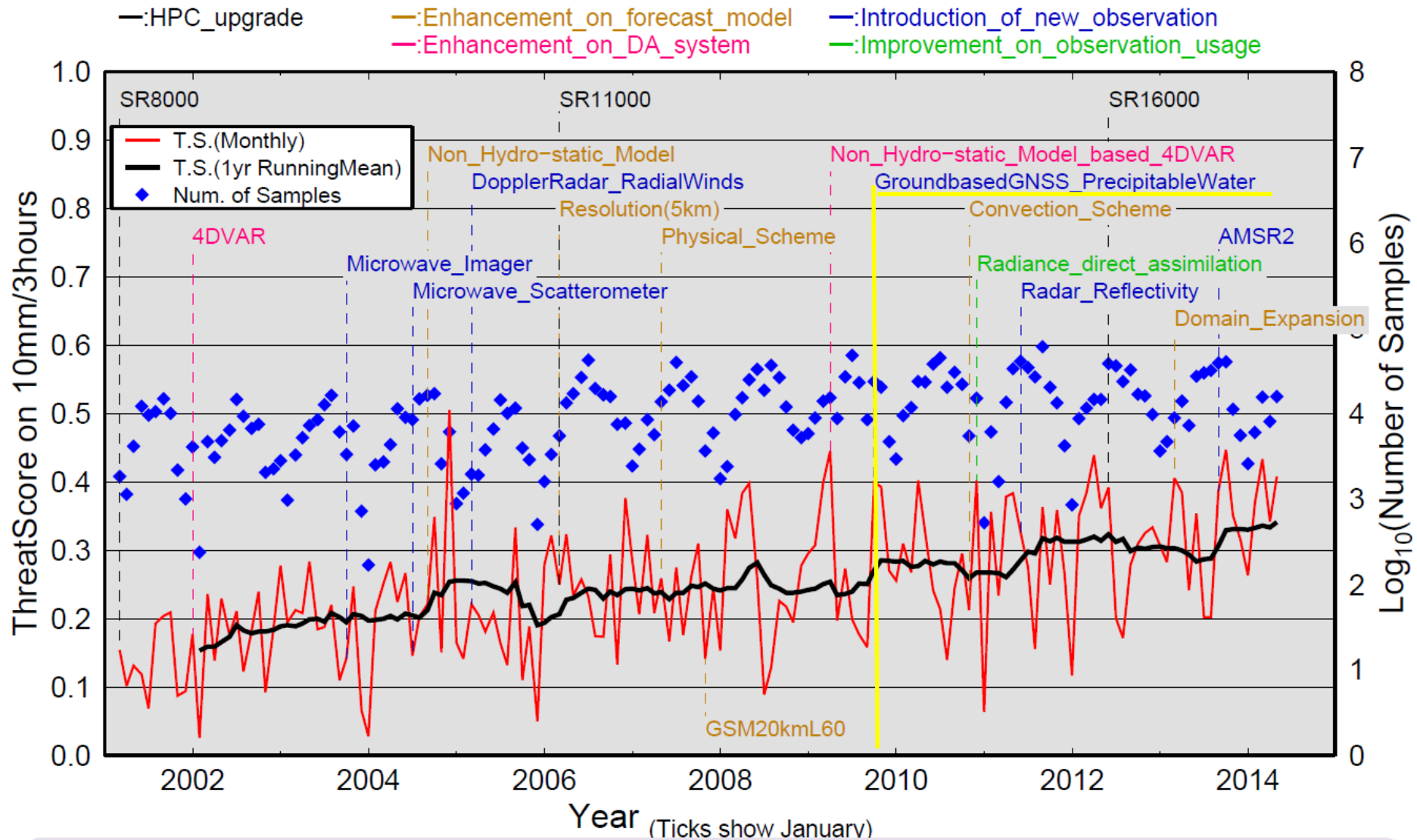


GMS
B10
TBB(K)



- GNSS PWV has been used as one of WV data in JMA's operational NWP system since Oct. 2009.

Improvement of forecast score

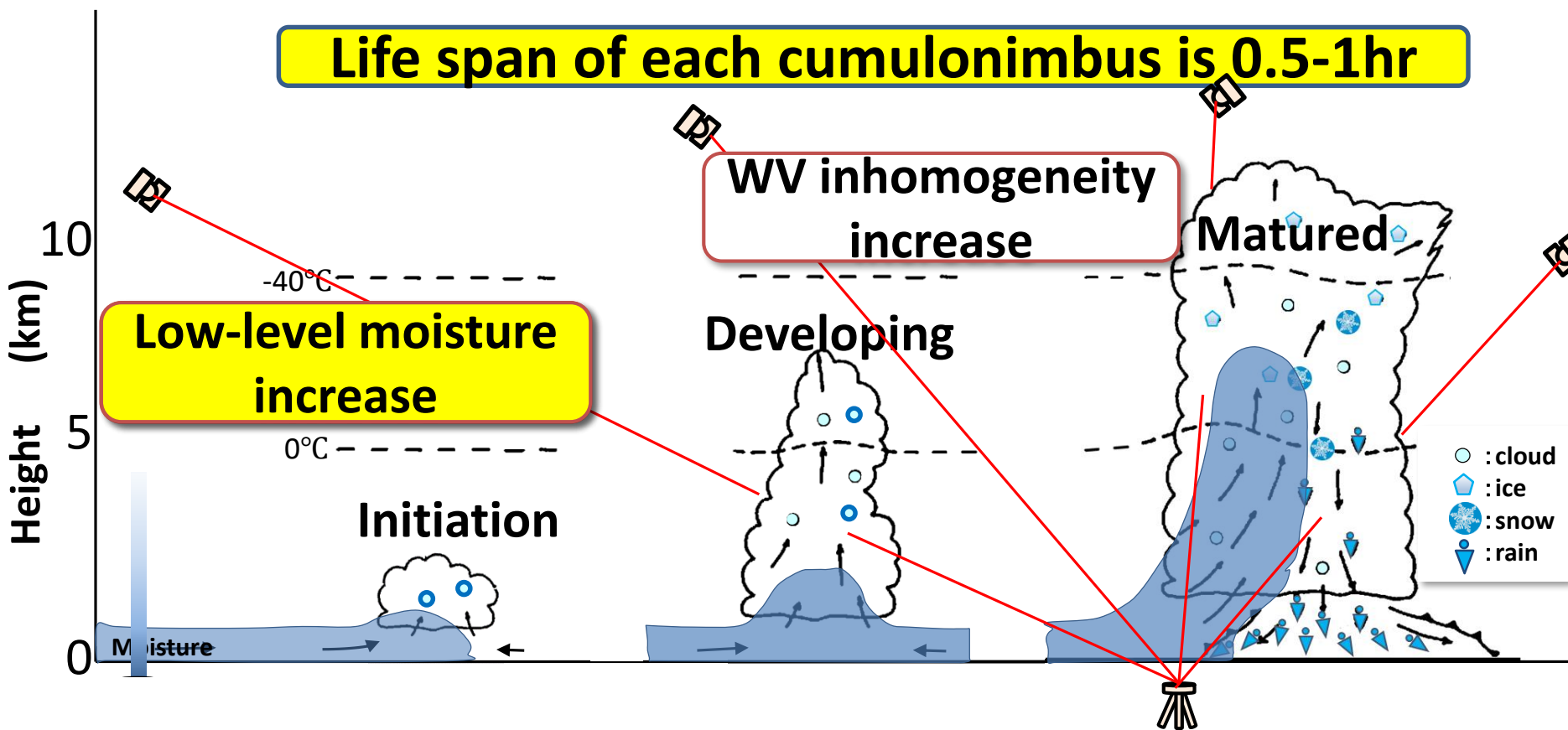


GPS R & D Groups in JMA and MRI were awarded by the director general of JMA in 2010.

Water Vapor:

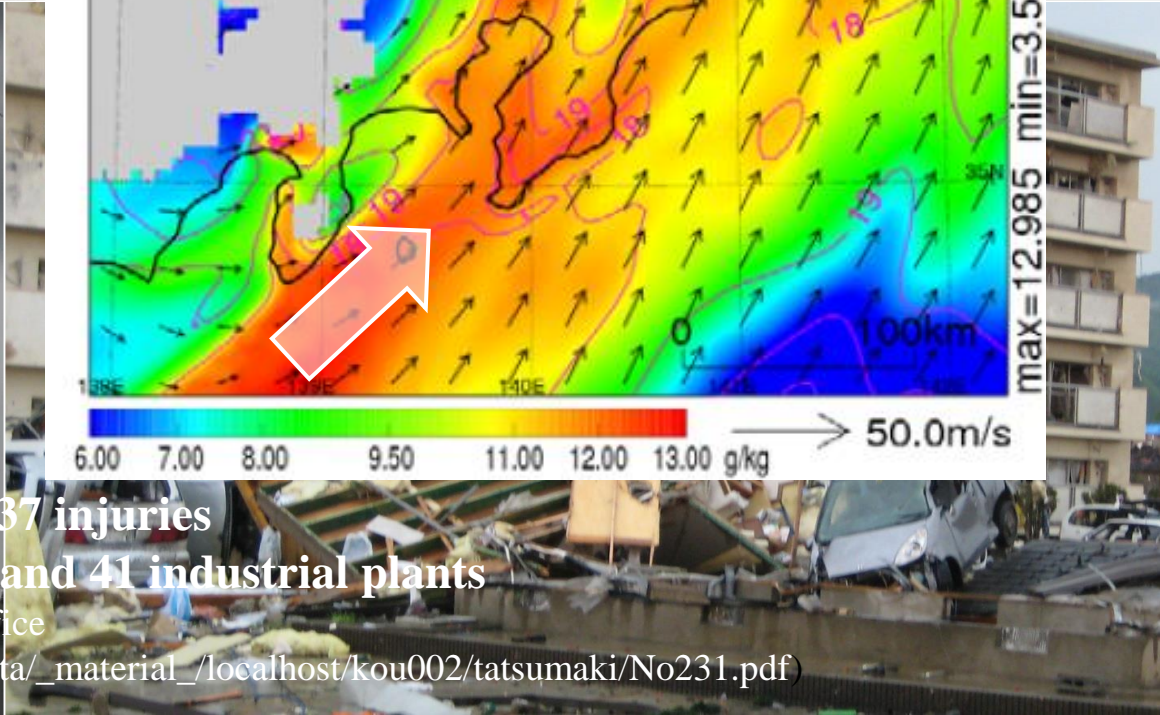
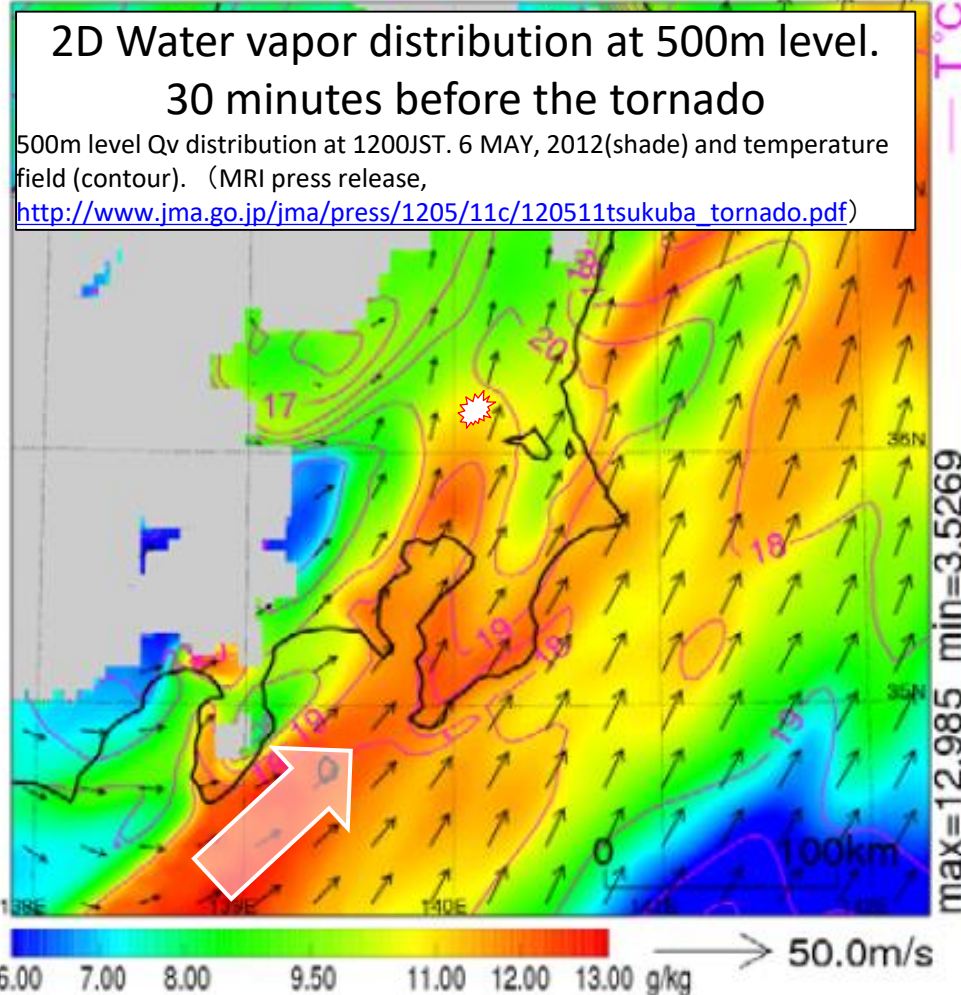
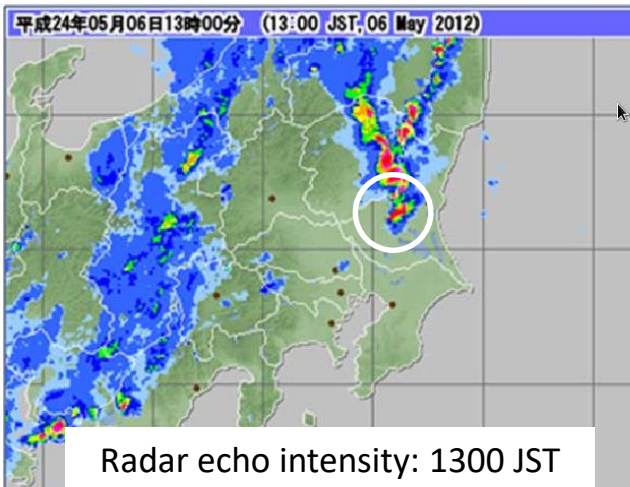
Energy source of hazardous weather

Life span of each cumulonimbus is 0.5-1hr



GNSS can monitor WV variation over a lifetime of cumulus convection

Low-level WV from the Ocean triggered a Strong (F3) Tornado on 6 May 2012

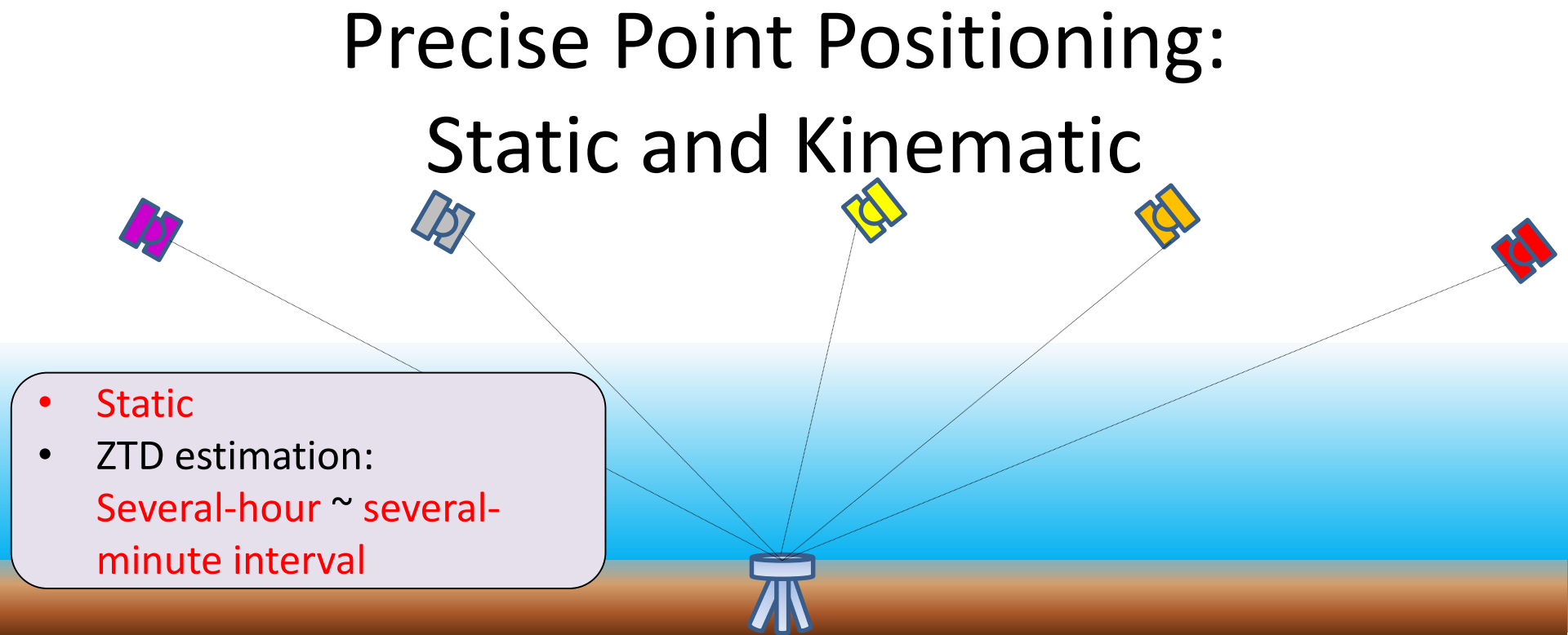


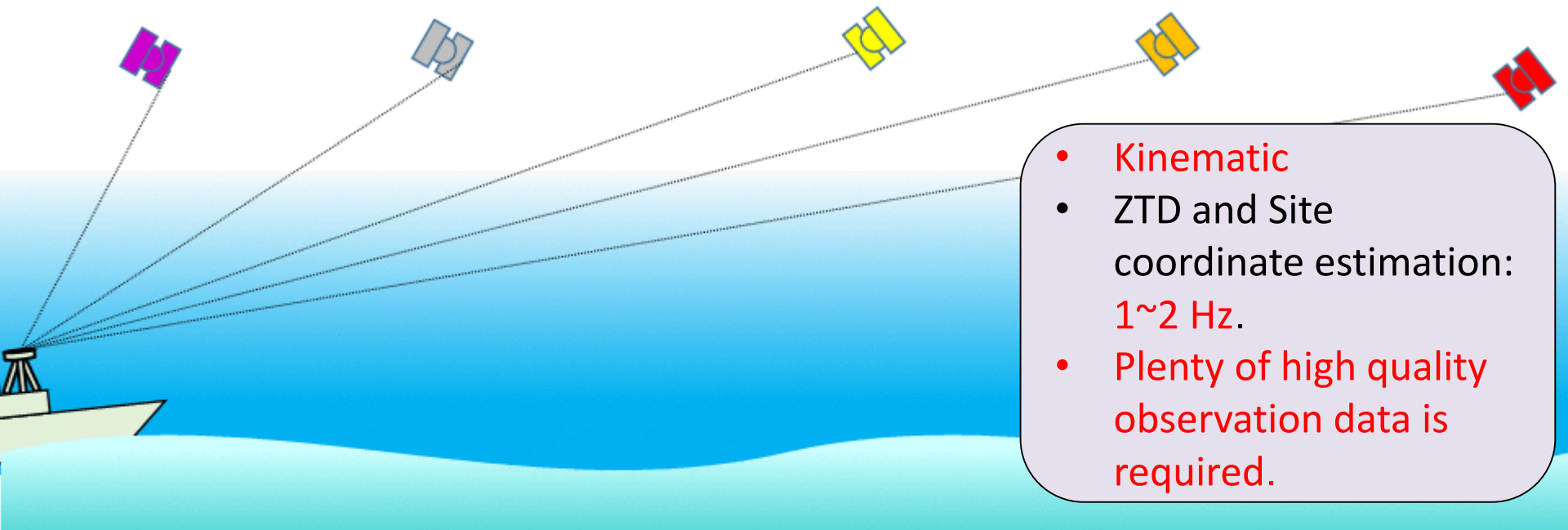
- ① Human damage: 1 fatality and 37 injuries
- ② Building damage: 1,108 houses and 41 industrial plants

(Tsukuba-city disaster countermeasures office

http://www.city.tsukuba.ibaraki.jp/dbps_data/_material_/localhost/kou002/tatsumaki/No231.pdf)

Precise Point Positioning: Static and Kinematic

- 
- The diagram shows a ground-based receiver on a brown surface. Five GPS satellites are shown in the sky, each with a unique color and antenna pattern. Dotted lines represent the signal paths from each satellite to the receiver. The background is a blue gradient representing the sky.
- **Static**
 - ZTD estimation:
Several-hour ~ several-minute interval

- 
- The diagram shows a receiver on a yellow ship's deck. Five GPS satellites are shown in the sky, each with a unique color and antenna pattern. Dotted lines represent the signal paths from each satellite to the receiver. The background is a blue gradient representing the sky, with a light blue wave pattern at the bottom representing the sea.
- **Kinematic**
 - ZTD and Site coordinate estimation:
1~2 Hz.
 - **Plenty of high quality observation data is required.**

Kinematic PPP needs more than 10 GNSS satellites for practical PWV analysis

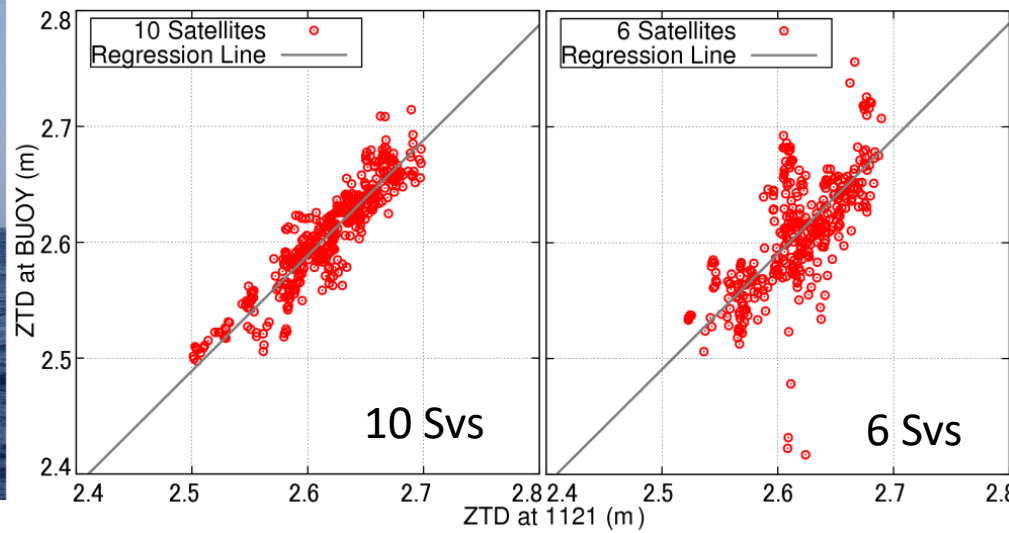
2012年2月3日ICTシンポジウム2012

GPSブイを用いた津波予測の可能性
 ～GPS津波計・波浪計開発の経緯・成果と課題～

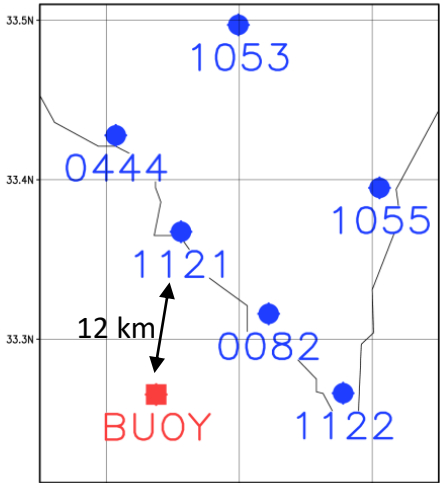


東京大学地震研究所 加藤照之
 科研費基盤研究(S)21221007研究チームを代表して

Teruyuki Kato,
 2012/2/3: http://ictfss.nict.go.jp/yokohama2012/DL/03_Kato_20120203.pdf



GEONET and BUOY



■ : GPS buoy
 Tsunami gauge
 ● : GEONET

Shoji et al. 2010

1. Retrieved PWV accuracy depends on the number of SVs which are used in PPP analysis.

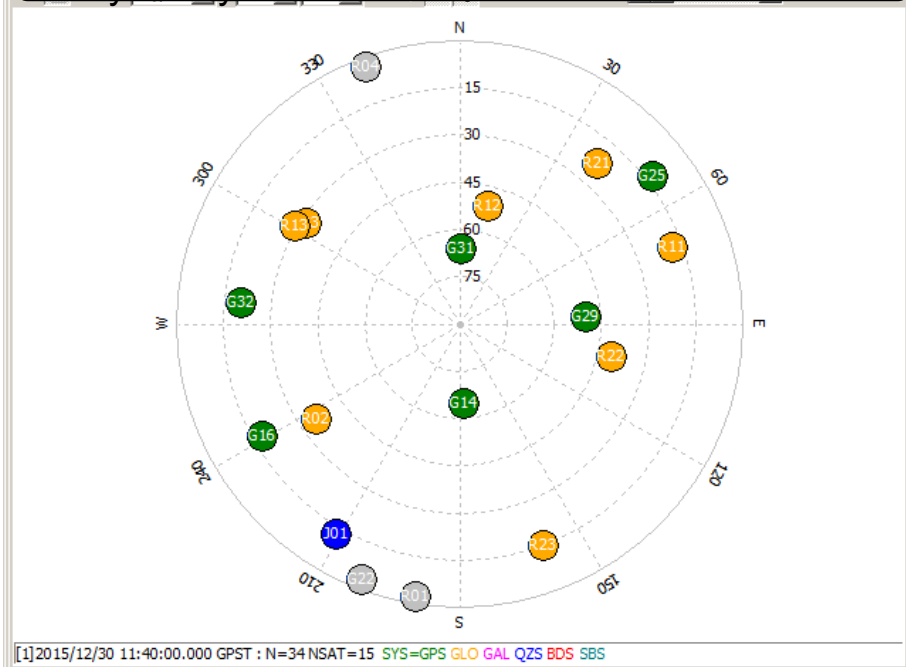
Multi-GNSS provides visibility of more than 10 satellites at all times

31 satellites → ≐60 satellites

Skyplot of GNSS satellites observed at MRI
GNSS station

2015/12/30 11:40-14:40 (UTC)

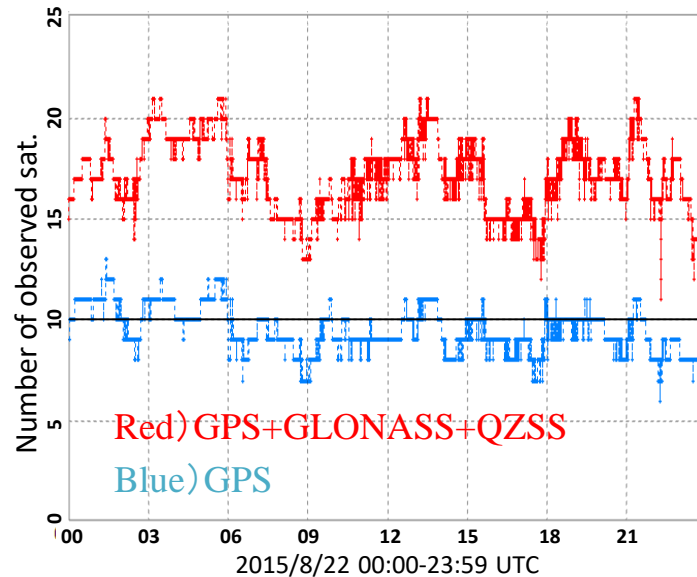
Orbit and clock of GPS, GLONASS, and QZSS are analyzed by JAXA's MADOCA.



● : GPS, ● : GLONASS, ● : QZSS

● : < 5 degree elevation

24-hour sequence of number of
observed GNSS satellites



More than 10 GNSS satellites
can be observed anytime.

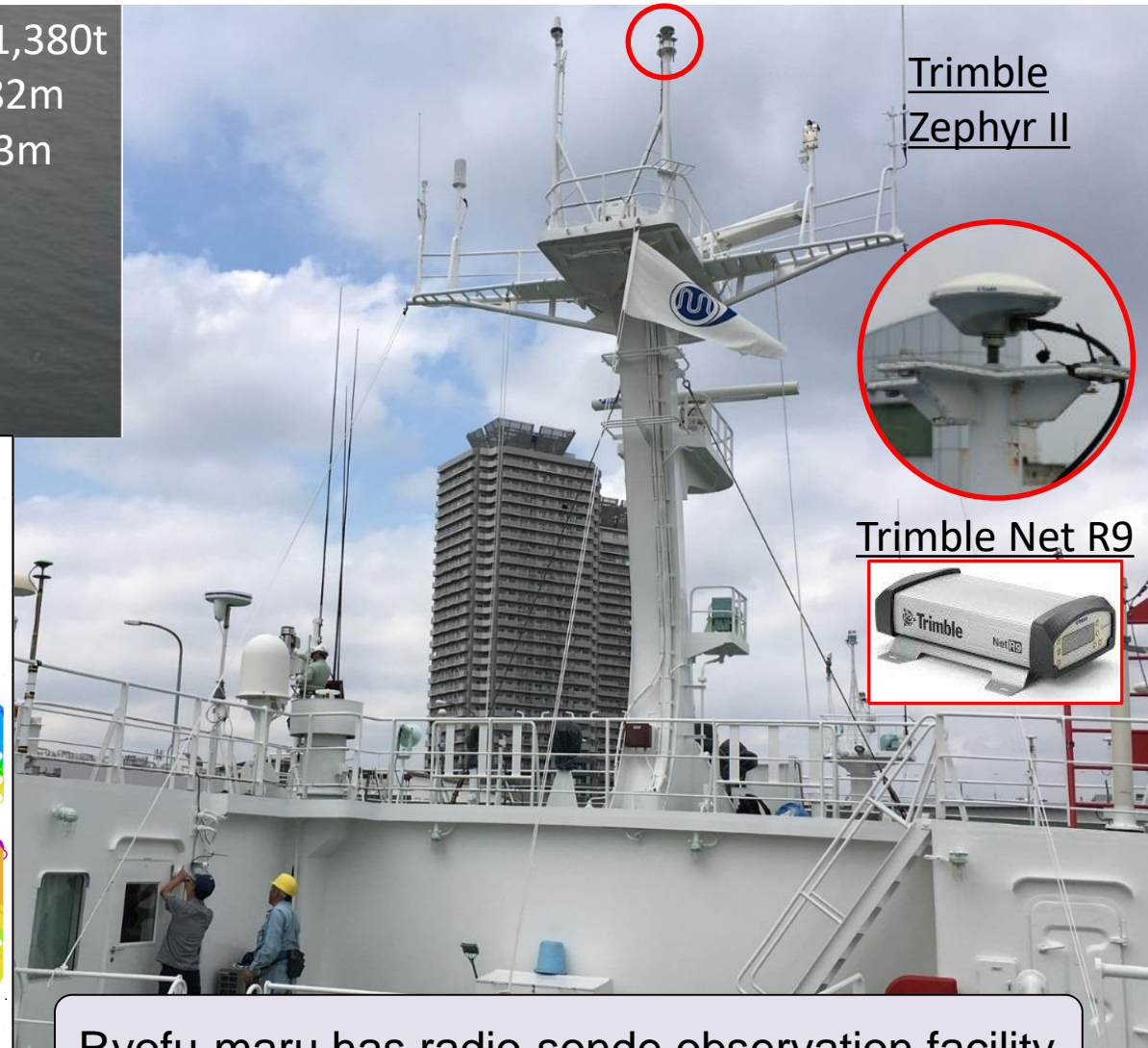
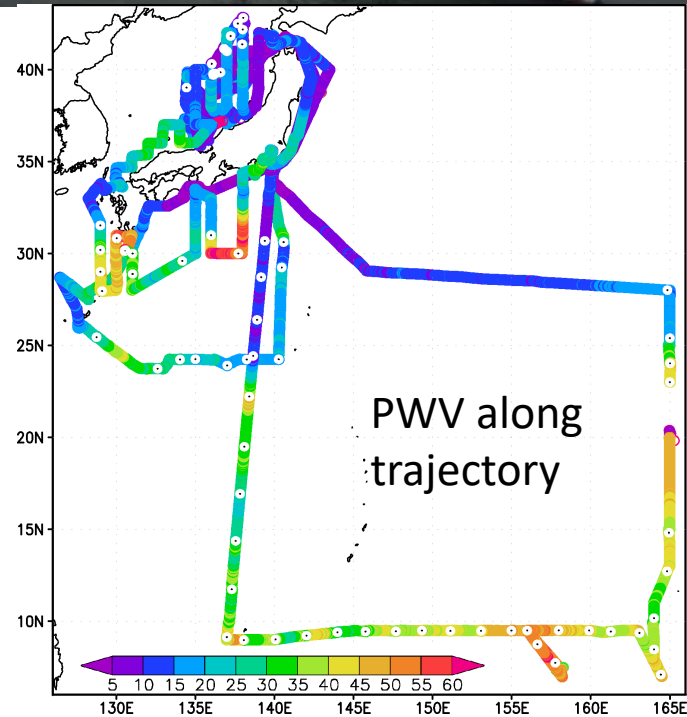
WV retrieval experiment over the OCEAN

Oct. 2016 – Jun. 2017

Ryofu-maru
(JMA)

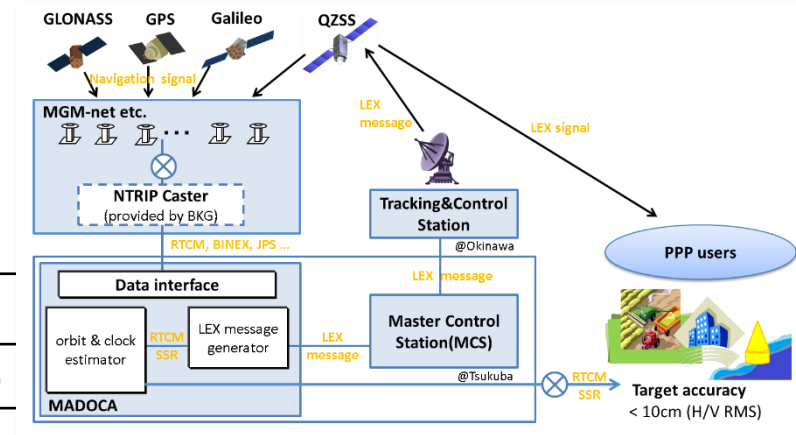
Weight 1,380t
Length 82m
Width 13m

http://www.data.jma.go.jp/gmd/kaiyou/data/db/vessel_obs/description/fig/Ryofu-Marujpg



Ryofu-maru has radio-sonde observation facility.

Specification of GNSS Analysis

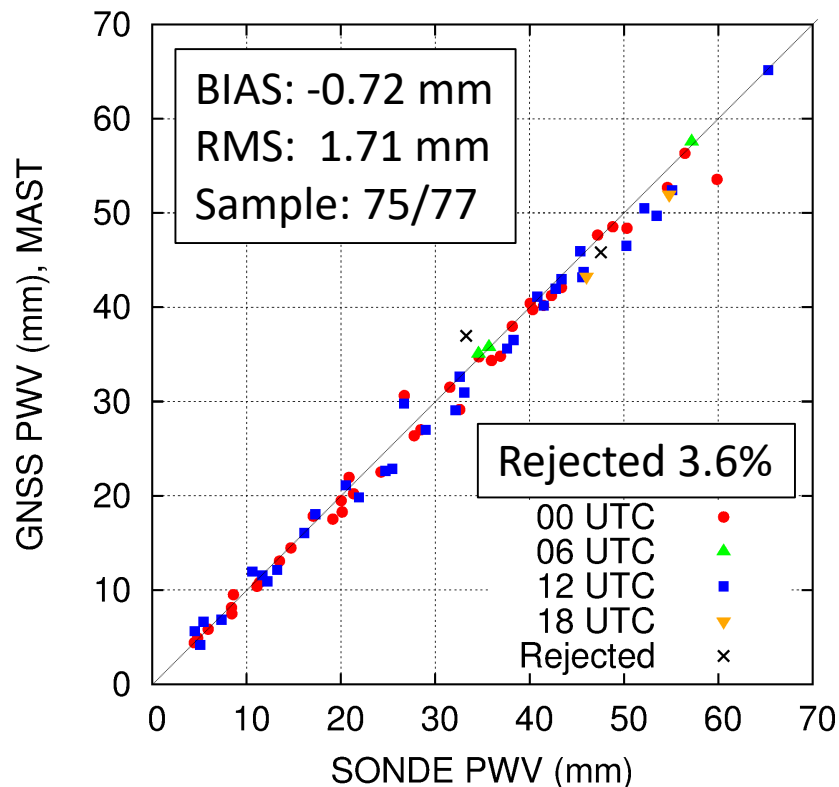


Classification	Specification	
Software	RNX2RTKP (RTKLIB ver. 2.4.2, p12)	
Analysis procedure	Precise Point Positioning - Kinematic (Shipborne GNSS)	
Integer ambiguity	Not fixed (no PPP-AR applied)	
Ephemeris	MADOCA realtime product (MDC2)	https://ssl.tksc.jaxa.jp/madoca/public/public_index_en.html
Mapping function	GMF (no gradient estimation)	Boehm et al. 2006
Elevation cut-off angle	3 degree	
Antenna phase center variation	IGS08_1915.atx	ftp://ftp.igs.org/pub/station/general/igs08.atx
Ionosphere correction	Ionosphere-free linear combination	
ZHD	$ZHD = 0.002277 \cdot P$ $P = 1013.25 \times (1 - 2.2557 \times 10^{-5}h)^{5.2568}$	Elgered et al. 1991
Time dependent parameters	<ul style="list-style-type: none"> • Antenna coordinate • Receiver clock • ZWD random-walk variable with process noise of $0.1\text{mm/s}^{1/2}$	Updated every 1 sec

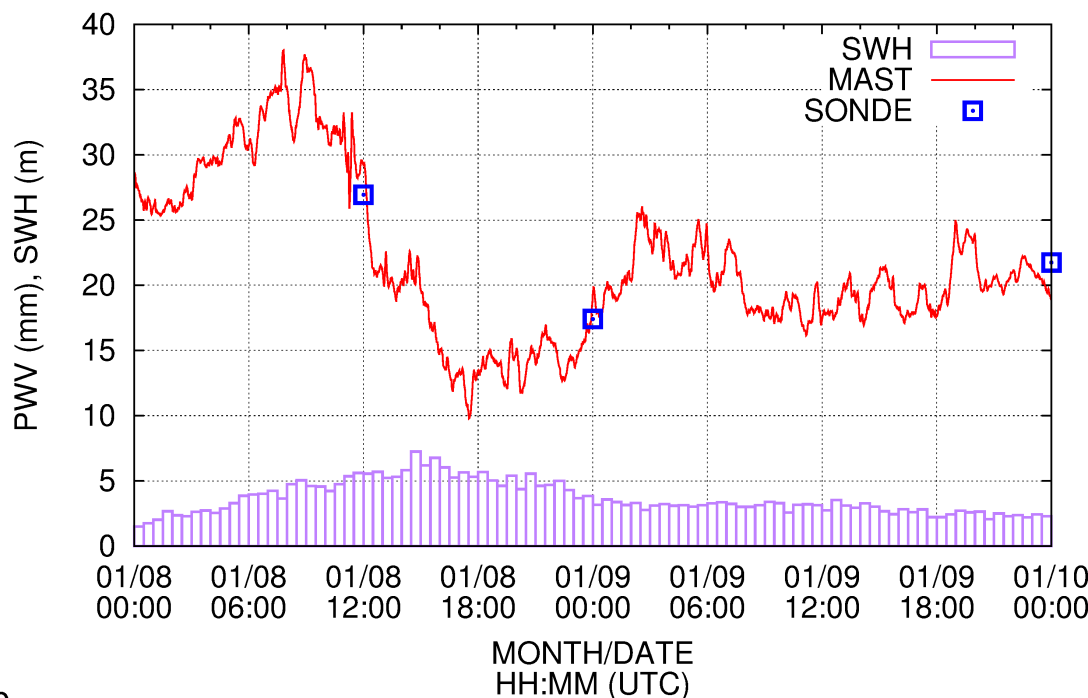
Retrieved PWV using **RTKLIB** with **MADOCA** real-time product

Shoji *et al. Earth, Planets and Space* (2017) 69:153, DOI 10.1186/s40623-017-0740-1

MAST, 27 OCT. 2016 - 8 JUN. 2017



PWV, 08 00:00 - 10 00:00, JAN. 2017



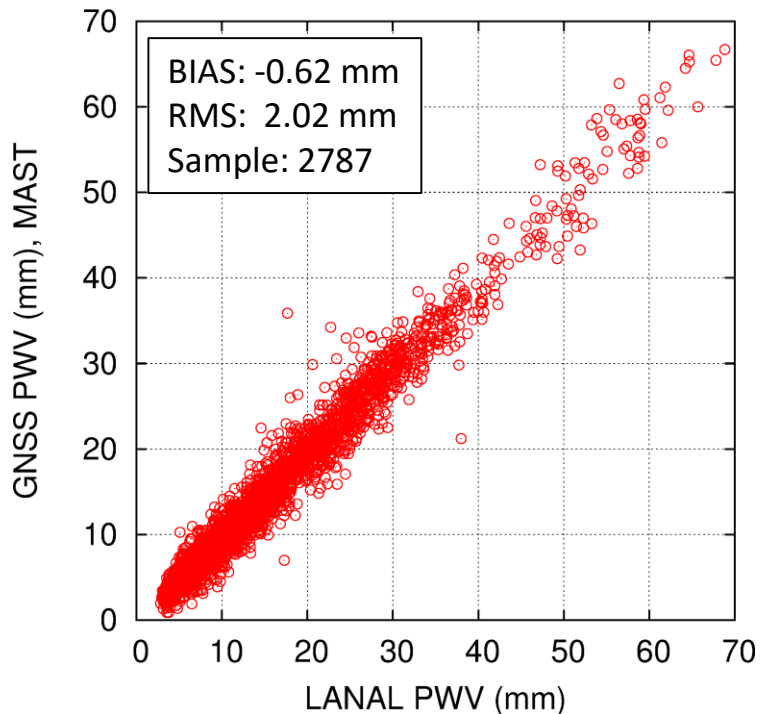
PWV measurement by Ocean platform GNSS is promising.

Comparison with JMA's hourly NWP analysis



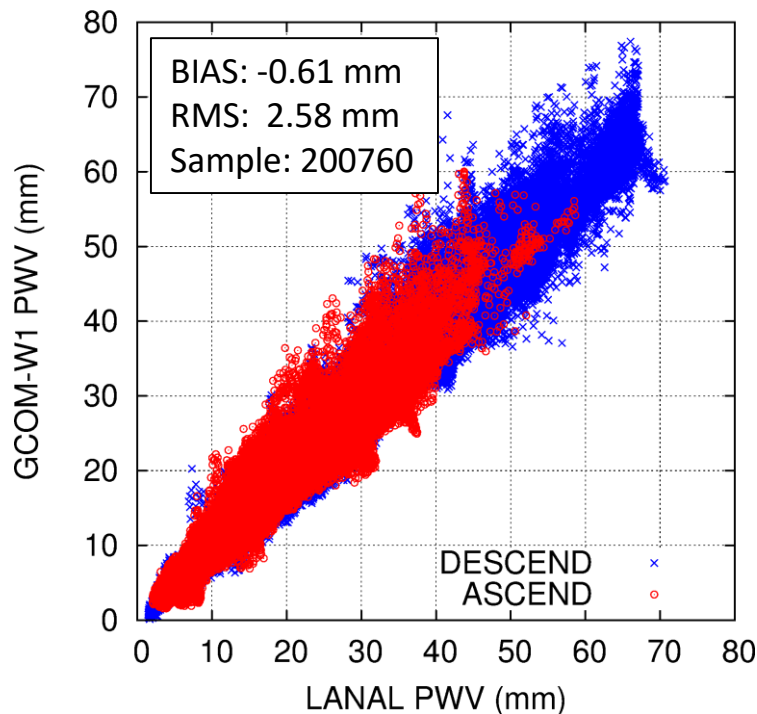
Ship-borne GNSS

MAST, 23 OCT. 2016 - 15 JUN. 2017



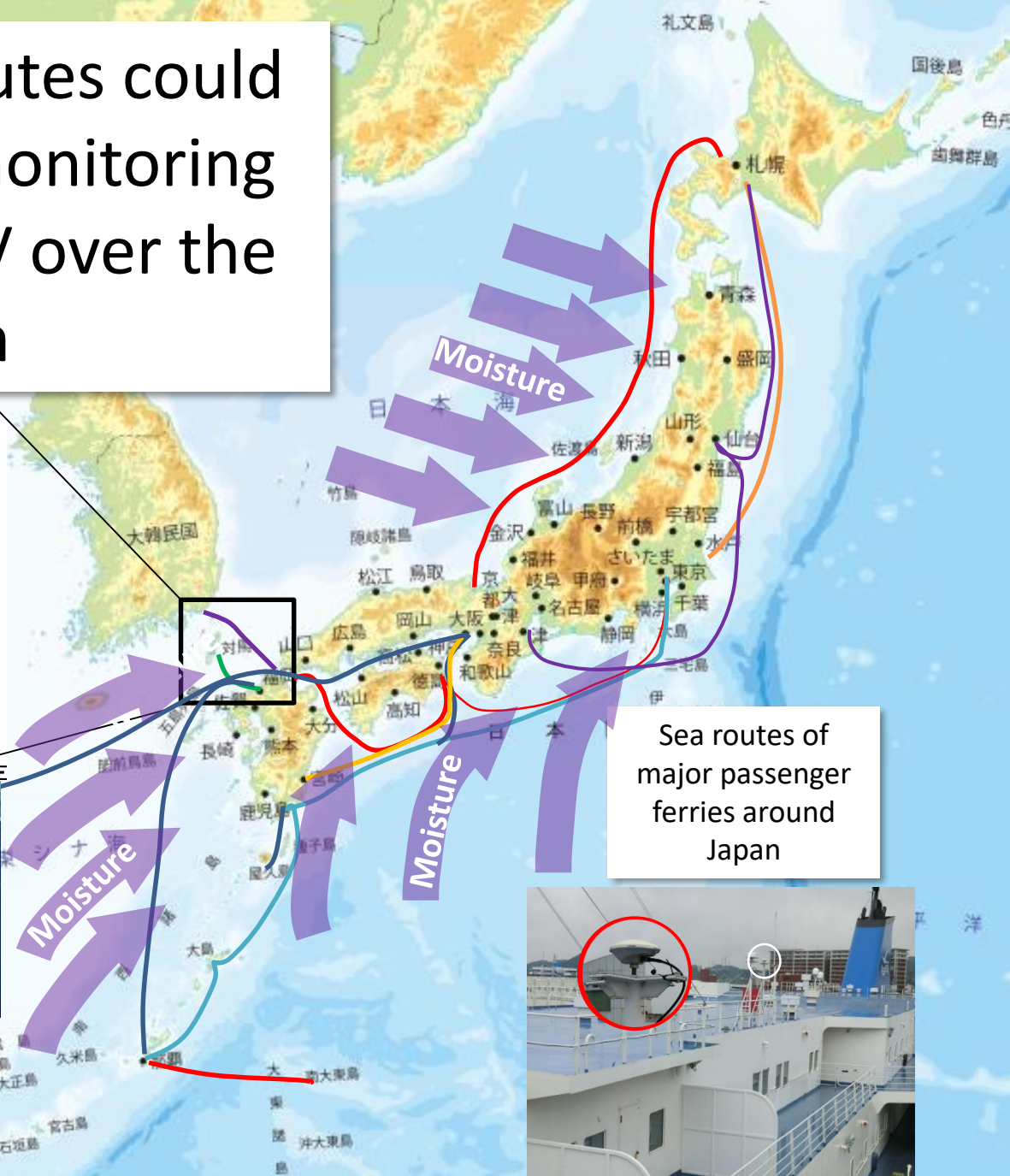
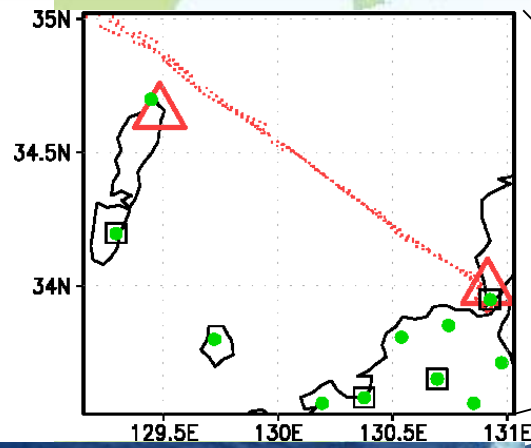
Satellite-borne MWR

23 OCT. 2016 - 15 JUN. 2017



Ship-borne GNSS shows better agreement with JMA's NWP analysis (LA) than satellite-borne MWR.

Regular sea routes could be used as a monitoring network of WV over the ocean



Sea routes of major passenger ferries around Japan



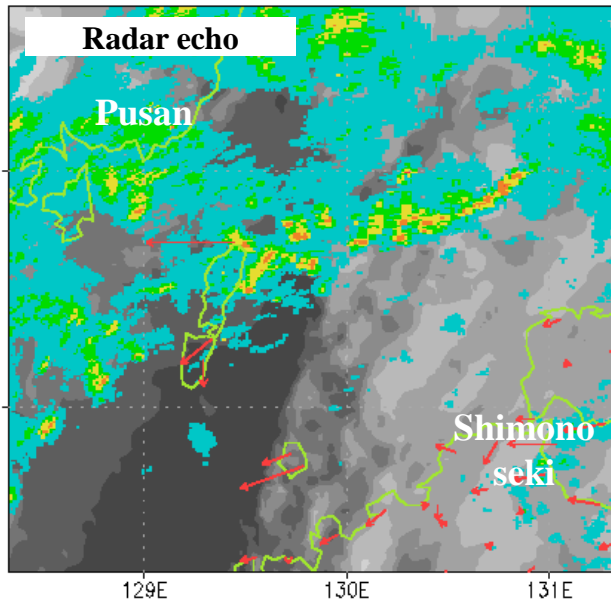
17 Sep. 2015

http://www.kampuferry.co.jp/img/hamayu_uall.jpg

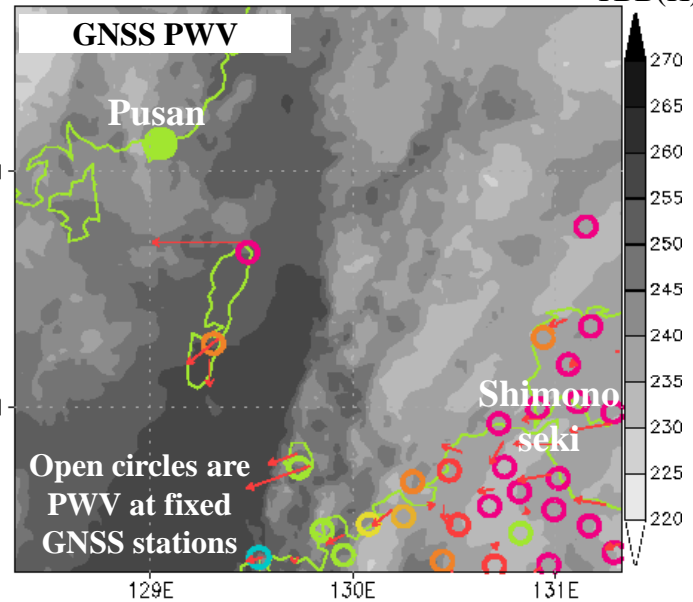


KAMPU FERRY

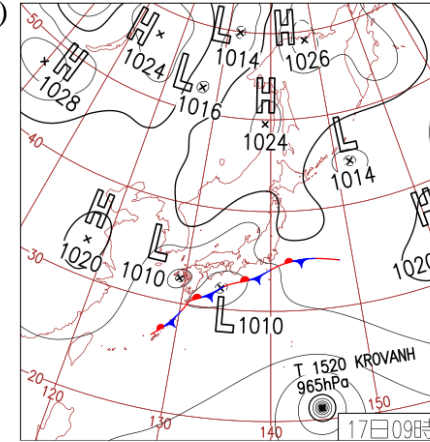
2015/09/16 11:50 UT



2015/09/16 11:50 UT



B10
TBB(K)



17日(木)チリ沿岸でMw8.3の地震

南岸に前線が停滞し、沖縄・奄美や西～東日本と東北南部で曇りや雨。上空の寒気の影響もあって長崎県上大津で83mm/1hの猛烈な雨。東北北部や北海道は高気圧に覆われて晴れ。

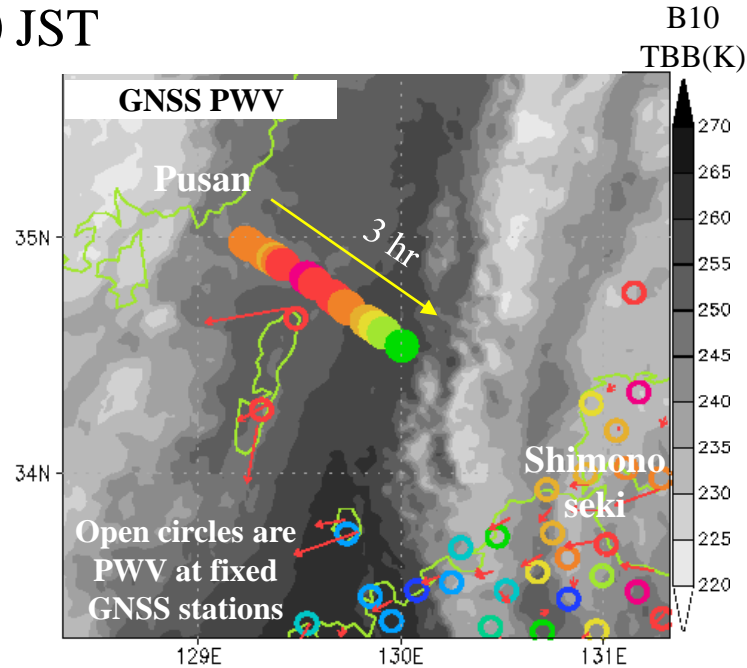
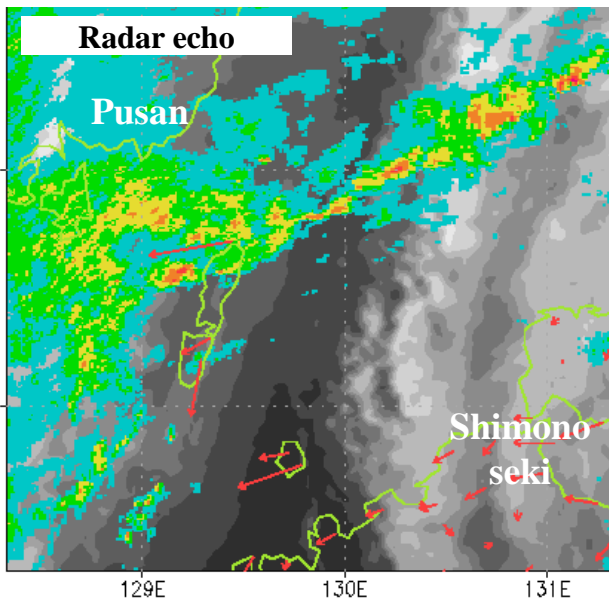
17 Sep. 2015

http://www.kampuferry.co.jp/img/hamayu_uall.jpg



KAMPU FERRY

0110 JST



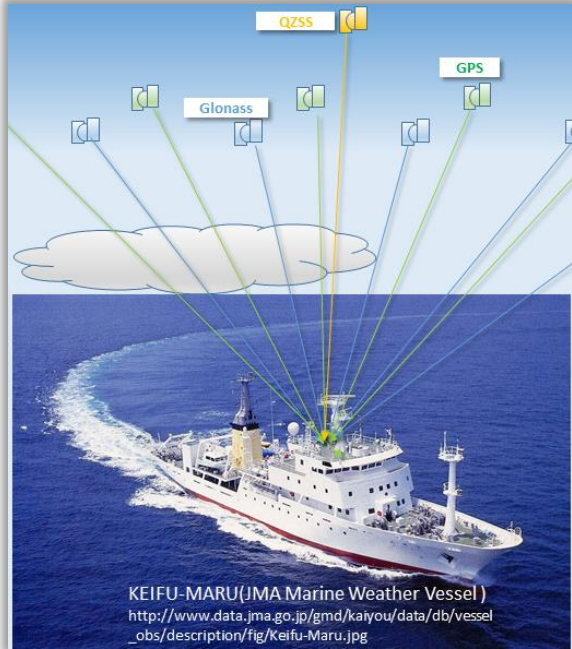
- PWV gradient associated with precipitation system is well expressed

Thank you for your attention

Summary

1. For monitoring of hazardous cumulus convection
 - **Continuous WV monitoring** is indispensable
2. JMA's operational GNSS PWV assimilation resulted **stepwise improvement** in precipitation forecast
3. **Innovations in GNSS** remote sensing technology enable us to monitor WV variation over a **lifetime of convection**
 - Initiation stage
 - Moisture increase in **low-level**
 - WV measurement over the ocean using GNSS on **floating buoys** and/or **vessels**
 - Development ~ matured stage
 - WV inhomogeneity
 - Slant path delay analysis
4. The results obtained by experimental WV observation using shipborne GNSS are **promising**.
 - Agree with radiosonde observation with **2mm RMS** (Shoji et al. 2017).
 - Continuous observation could **capture strong WV gradient** associated with strong precipitation system.

Acknowledgements



- The campaign observation was funded by a research grant for Mission Research for Sustainable Humanosphere from the Research Institute for Sustainable Humanosphere (RISH) at Kyoto University, “Study on accuracy improvement of shipborne GNSS water vapor measurement.”
- We would like to express our deepest appreciation for the support and help given by the Kampu Ferry Company.
- A part of the study was also supported by JSPS KAKENHI Grants 16H06310.
- RTKLIB ver.2.4.2 (patch 12) was downloaded from the following [link;](https://github.com/tomojitakasu/RTKLIB/archive/master.zip)
<https://github.com/tomojitakasu/RTKLIB/archive/master.zip>.
- We would like to express our sincere appreciation for Mr. Tomoji Takasu for his valuable comments and supports for the GNSS analysis.
- The GEONET observation data were acquired from the ftp server of the Geospatial Information Authority of Japan (GSI) in RINEX format.
- MADOCA real-time product was provided by JAXA via the internet
(https://ssl.tksc.jaxa.jp/madoca/public/public_index_en.html).