





# QZSS Update

ICG-13 Providers System and Service Updates on Nov. 5, 2018 @Xi'an, China

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National Space Policy Secretariat Cabinet Office, Government of Japan

## Contents



- Services
- System Architecture
- Development Status
- 2. Recent Development
  - QZSS Performance
  - SBAS Service and Experiments
  - QZSS Satellite Information
- 3. International Cooperation
- 4. Summary





#### • Functional Capability:

- GPS Complementary Service
- GNSS Augmentation Service
- Messaging Service
- Coverage: Asia and Pacific region







• Coverage: Asia and Pacific region



Minimum Largest Elevation Angle Contour in the QZSS 4SV Constellation





#### Functional Capability 1 GPS Complementary Service

## QZSS improves positioning

#### <u>availability</u>

- Navigation signals L1-C/A, L1C, L2C, and L5 coming from high elevation (near zenith) improve PNT availability.
- QZSS is the first L1C and L5 signals provider offering interoperability among other GNSS.
- SIS-URE: 2.6m (95%)







#### Functional Capability 2 GNSS Augmentation Service

**QZSS** improves positioning accuracy and reliability





#### Functional Capability 2 GNSS Augmentation Service



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#### Functional Capability 2 GNSS Augmentation Service

#### **Centimeter Level Augmentation Service: CLAS**





#### Functional Capability 3 Messaging Service

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#### Satellite Report for Disaster and Crisis Management (DC Report)





#### Functional Capability 3 Messaging Service



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- Constellation:
  - 1 GEO Satellite, 127E
  - 3 QZO Satellite (IGSO)
- Ground System
  - 2 Master Control Stations
    - Hitachi-Ota and Kobe
  - 7 Satellite Control Stations
    - Located south-western islands
  - Over 30 Monitor Stations around the world







#### QZSS Satellite (#2 and #4)

#### L-band Antenna-

Launch Vehicle : H-IIA Mass Dry/Launch : 1.6t/4.0t Lifetime : 15years+



Orbit Parameter	Nominal Allocation
Semimajor Axis(A)	42164km
Eccentricity(e)	0.075
Inclination (i)	41 degree
Argument of Perigee(w)	270 degree
RAAN(Ω)	Block I_Q: 117 degree Block II_Q: 117±130 degree
Central Longitude (λ)	136 degree

RAAN: Right Ascension of the Ascending Node 13



#### QZSS Satellite (#3 GEO)





Launch Vehicle : H-IIA Mass Dry/Launch : 1.8t/4.7t Lifetime : 15years+

Orbit Parameter	Nominal Allocation
Longitude	E 127
Latitude	0

- Additional S-band antenna for two-way communication for emergency safety report (Q-ANPI service).
- L1Sb signal for SBAS service.





#### **QZSS** Master Ground Station

http://www.mlit.go.jp/koku/15\_bf\_000367.html



QZSS Control Center, Kobe





- Two-Ground Station (Control Center)are available with site diversity.
- Hitachi-Ota station is main operation site and Kobe is a redundant site.

QZSS Control Center, Hitachi-Ohta, http://www.mlit.go.jp/koku/15\_bf\_000367.html





- 7 TTC (Telemetry, Tracking, and Command) stations: Most are at the southern part of Japan for satellite continuous visibility.
- All TTC stations were built and set operational by the end of 2016.







- 25 monitor stations for POD of both QZSS and GPS satellites
- Additional 10 domestic stations for SLAS (totally 13 sites)

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• CLAS uses GEONET, Japanese CORS more than 1200 stations

:Monitor Site



#### Ranging Signals of QZSS

Signal	Frequency	Sorvico	Compatibility	QZS-1	QZS-2/4	QZS-3
Signal	MHz Service		Compationity	IGSO	IGSO	GEO
L1C/A		Positioning	Complement GPS	$\checkmark$	$\checkmark$	$\checkmark$
L1C		Positioning	<b>Complement GPS</b>	$\checkmark$	$\checkmark$	$\checkmark$
L1S	1575.42	Augmentation(SLAS)	DGPS (Code Phase Positioning)	~	~	$\checkmark$
		Messaging	Short Messaging	$\checkmark$	<ul> <li>✓</li> </ul>	$\checkmark$
L1Sb		Augmentation(SBAS)	SBAS (L1) Service	-	-	$\checkmark$
L2C	1227.60	Positioning	Complement GPS	$\checkmark$	<ul> <li>✓</li> </ul>	$\checkmark$
L5 I/Q	1176 / 5	Positioning	Complement GPS	$\checkmark$	$\checkmark$	$\checkmark$
L5S	1170.43	Experimental(L5 SBAS)	L5 SBAS (DFMC)	-	×	$\checkmark$
L6D	4070 75	Augmentation(CLAS)	PPP-RTK (Carrier Phase Positioning)	$\checkmark$	✓	$\checkmark$
L6E	1278.75	Experimental(MADOCA)	PPP, PPP-AR (Carrier Phase Positioning)	-	~	$\checkmark$







Performance Standard (PS-QZSS) and Interface Specification (IS-QZSS) are available in our website http://qzss.go.jp/en/technical/ps-is-qzss/ps-is-qzss.html



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### **QZSS Overview -Development Status-**



#### QZSS Program Schedule (latest)



![](_page_20_Picture_4.jpeg)

### **QZSS Overview -Development Status-**

![](_page_21_Picture_1.jpeg)

# Three consecutive launches have successfully been conducted in 2017.

![](_page_21_Picture_3.jpeg)

![](_page_21_Picture_4.jpeg)

![](_page_21_Picture_5.jpeg)

#2 satellite: Jun. 1, 2017 00:17:46(UCT)

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#3 satellite: Aug. 19, 2017 05:29:00(UTC) #4 satellite: Oct. 9, 2017 22:01:37 (UTC)

## **QZSS Overview -Development Status-**

![](_page_22_Picture_1.jpeg)

#### QZSS services were started officially on November 1, 2018 !

![](_page_22_Picture_3.jpeg)

Prime minister Shinzo Abe (the 2nd from the right) attended the QZSS service-in ceremony on November 1, 2018.

![](_page_22_Picture_5.jpeg)

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![](_page_23_Figure_1.jpeg)

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#### **QZSS Performance -PNT Service-**

![](_page_24_Picture_1.jpeg)

#### Performance(SIS Accuracy)

[Specification] less than 2.6m(95%)

[ Evaluation (2018/5/11~ 2018/5/17) ]

QZS-1: 0.61m(95%), QZS-2: 1.11m(95%), QZS-3: 0.96m(95%), QZS-4: 1.01m(95%)

#### The improvement by the tuning

In order to improve SIS Accuracy (i.e. orbit error and clock error), parameters in our estimation engine were adjusted.

![](_page_24_Figure_8.jpeg)

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#### **QZSS Performance -SLAS Service-**

![](_page_25_Picture_1.jpeg)

![](_page_25_Figure_2.jpeg)

Service Area is the area surrounded by the red line. The left-axis is latitude, and lower-axis is longitude.

#### Accuracy of SLAS

positioning errorm(95%)		errorm(95%)	Bomarka
	horizontal	vertical	Remarks
	≤ 1.0 m	≤ 2.0 m	EL mask : $10^{\circ}$ User range error caused by user's receivers and user's situation : 0.87 m(95%)

![](_page_25_Picture_6.jpeg)

#### **QZSS Performance -SLAS Service-**

![](_page_26_Picture_1.jpeg)

#### **Recent Test results**

 Using the GNSS-based control stations in GNSS Earth Observation Network System (GEONET) operated by Geospatial Information Authority of Japan as a rover.

- Evaluation period: 2018 May 10 (24 hours)
- •Evaluation point: Gushikawa, Okinawa Pref.
- Signal subject to augmentation: GPS(L1-C/A),QZSS(L1-C/A)
- •The graph shows error figures by time transition, the table shows statistical figures.

![](_page_26_Figure_8.jpeg)

Positioning Accuracy	m (95%)
Horizontal	0.66
Vertical	0.88

![](_page_26_Picture_10.jpeg)

### **QZSS Performance -CLAS Service-**

![](_page_27_Picture_1.jpeg)

#### **1.** CLAS (Centimeter Level Augmentation Service) Quasi-Zenith Satellite System GNSS (QZSS: JPN) Positioning Signal Altitude Broadcast via satellite 500km •Accuracy: (or on ground DError in Positioning communication) Orbit clock. Signals Biases. lonosphere. ②Create augmentation Troposphere ④ Positioning errors data and compress corrected by 1) Automobile each receiver CORS (Continously Operationg Server and facility Reference Station) for CLAS 2) Agriculture Space & On-Ground Infrastructure Users for High-Precision Positioning

#### 2. Technical features

- 1)Augmentation data is created from CORS data
- 2)Error resulting from lonosphere, Troposphere conditions can be corrected
- 3) Augmentation data is broadcasted from QZSS free of charge

#### 3. Servicing situation

- 1) Present: Test service on running
- 2) From 1<sup>st</sup> Nov 2018: Public service distribution
  - •Range of service: Japanese domain and 800,000km2 area off shore

 $H \le 6.0 \text{ cm} (95\%), V \le 12.0 \text{ cm} (95\%) \text{ (Static)}$ 

- $H \le 12.0 \text{ cm} (95\%), V \le 24.0 \text{ cm} (95\%)$  (Kinematic)
- 4. Examples of use and demonstration

Precise positioning used in combination with HD Maps for automated control

![](_page_27_Picture_15.jpeg)

- Precise positioning used for automated control of tractors
- 3) Snowplough Assists recognition of self position in comparison with HD maps

![](_page_27_Picture_18.jpeg)

![](_page_27_Picture_19.jpeg)

![](_page_27_Picture_20.jpeg)

#### **QZSS Performance -CLAS Service-**

![](_page_28_Picture_1.jpeg)

#### Recent Test results (mobile use)

- Evaluated from positioning results earned from a mobile vehicle mounting both general RTK and CLAS receivers in open-sky condition maneuver.
- Difference between CLAS positioning results and RTK positioning results are evaluated (defined as error figures)
- Error is evaluated by content (direction),

the graph shows error figures by time transition, the table shows statistical figures

![](_page_28_Figure_7.jpeg)

Error content (Direction)	cm (rms)
East-West	2.0
North-South	1.8
Vertical	4.2

![](_page_28_Picture_9.jpeg)

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![](_page_30_Picture_0.jpeg)

### **MSAS: Japanese SBAS**

![](_page_30_Picture_2.jpeg)

□ MSAS: Japanese SBAS in operation.

■ Operational since Sept. 27, 2007.

Currently operated by JCAB with a GEO called MTSAT-2.

![](_page_30_Picture_6.jpeg)

ENRI IN 2020: MSAS V2 with QZSS GEO

![](_page_31_Picture_1.jpeg)

![](_page_31_Figure_2.jpeg)

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![](_page_32_Picture_0.jpeg)

### MSAS V2 RF Performance

![](_page_32_Picture_2.jpeg)

![](_page_32_Figure_3.jpeg)

PRN 129 and PRN 137 are transmitted from MTSAT-2 (MSAS-v1).

PRN 187 is currently transmitted from QZS-3 GEO; Will be switched to PRN 129 or 137 for MSAS-v2.

![](_page_32_Picture_6.jpeg)

![](_page_33_Picture_0.jpeg)

### **MSAS Evolution Plan**

![](_page_33_Picture_2.jpeg)

![](_page_33_Figure_3.jpeg)

- DFMC SBAS trial began in summer 2017 with QZS-2 L5S signal.
- MSAS V2: Replacement to the new QZSS-based system in 2020.
- MSAS V3: LPV/LPV-200 upgrade likely around 2023 and DFMC SBAS (MSAS V4) will follow.

![](_page_33_Picture_7.jpeg)

![](_page_34_Picture_0.jpeg)

![](_page_34_Picture_2.jpeg)

- DFMC (Dual-Frequency Multi-Constellation) SBAS
  - International standard augmentation system using L5 signal.
    - > Following L1 single-frequency single-constellation SBAS.
  - Eliminates ionospheric effects dramatically.
    - > Vertical guidance service everywhere in the coverage.
  - Allows SBAS signal transmission from non-GEO (IGSO) satellites.
    - > Improved SBAS signal availability in polar regions and urban canyons.
- MPAT is now conducting DFMC SBAS Experiment
  - The first L5 SBAS experiment with live L5 signal from the space.
    - ➤ Using QZSS L5S signal transmitted from GEO and IGSO satellites.
  - The prototype DFMC SBAS for experiments has been developed.
    - ➢ GPS/GLONASS/Galileo/QZSS-capable dual-frequency SBAS.
    - > Compliant with the draft ICAO L5 SBAS SARPS.
  - Began the initial test on 23 Aug., 2017 using L5S signal (PRN 196) of QZS-2 IGSO.

Expects participation to this experiments. Contact: <sakai@mpat.go.jp>

![](_page_34_Picture_18.jpeg)

![](_page_35_Picture_0.jpeg)

![](_page_35_Picture_1.jpeg)

![](_page_35_Figure_2.jpeg)

 Provides observation in real time

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ENR

- Supports GPS+GLONASS +Galileo+QZSS
- message data

36

![](_page_36_Picture_0.jpeg)

## **Realtime Experiment**

![](_page_36_Picture_2.jpeg)

![](_page_36_Figure_3.jpeg)

- Evaluation of L5 SBAS message generated in real time.
  - Supporting GPS, Galileo, and QZSS in L1/L5 dual-frequency mode.
- Confirmed that L5 SBAS augments multi-constellation of GPS+Galileo+QZSS.

![](_page_36_Picture_7.jpeg)

## **PPP Experiment using MADOCA**

![](_page_37_Picture_1.jpeg)

#### Precise Point Positioning (PPP)

- A precise positioning methodology obtaining absolute location with deci-meter level
- Resolving Integer ambiguity of carrier phase is called "PPP-AR" which can reach a couple of cm level solution.

![](_page_37_Figure_5.jpeg)

#### ④Noise · Multipath

- Relative position wrt. reference station
- Double Difference between satellites and ref stations cancels errors above shown (1)(2)(3)
- cm level accuracy with instant convergence time
- Dense reference network required

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- Absolute position
- Precise orb and clk are indispensable
- Iono-error ② is canceled by using Iono-free combination or estimated by using some models
- cm(PPP-AR)~deci meter (PPP) accuracy but long convergence time (30-40 minutes)
- Global coverage with global ref. network

## **CLAS Service and MADOCA Experiment**

![](_page_38_Figure_1.jpeg)

:region

- CLAS (Centimeter Level Augmentation Service) will be provided via L6D signal.
- Employs the dense GNSS monitoring network in service area.
- CLAS for Japanese territory begins in 2018.
- Service for other regions is under consideration.

:region

- Experimental augmentation based on PPP with MADOCA will be conducted using L6E signal on QZS-2/3/4.
- MADOCA: Multi-GNSS Advanced Demonstration tool for Orbit and Clock Analysis.
- Global GNSS monitoring network.
- Will also begin in 2018.

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![](_page_39_Figure_1.jpeg)

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## **QZSS Satellite Information**

![](_page_40_Picture_1.jpeg)

 Considering ICG WG-D recommendation and IGS White Paper, Satellite Property Information (SPI) and Operational History Information (OHI) for each QZS SV was published on our website.

#### http://qzss.go.jp/en/technical/qzssinfo/index.html

- Following info are included;
- Satellite Property Information(SPI)
- Reference Frame
- Attitude Law
- Mass and Center of Mass
- Navigation Antenna Phase Center Corrections
- Geometry
  - Satellite dimension
- Optical Property
- Laser Retro Reflector Location
- Differential Code Bias

![](_page_40_Picture_15.jpeg)

#### Operational History Information(OHI)

- Attitude Change history
  - mode/start end
- Orbit maintenance maneuver history
  - time/duration/delta-V/direction
- Estimated mass history

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![](_page_41_Figure_1.jpeg)

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#### International Collaboration

![](_page_42_Picture_1.jpeg)

#### JP-US

- Continuous discussion on Interference Mitigation on L1C/A
- Cooperation on Ground Segment (Monitoring Site) for future extension

#### JP-EU

- Cooperation Agreement relative to Satellite Navigation Applications between Japan (National Space Policy Secretariat, Cabinet Office) and EU (DG-Glow, European Commission) was established on March 8, 2017.
  - Annual Round Table and Working Group discussions
  - Emergency Warning Services, Autonomous driving and 3D mapping, E6/L6 signals, DFMC SBAS, Knowledge sharing about Operations
- Current Activities
  - Definition of common EWS message format is on going.
  - Galileo-QZSS joint EWS trial in Australia was successfully completed on 19 Sept.
  - Joint working team activity will begin soon: Joint R&D activity on DFMC SBAS supporting IGSO SBAS concept will be planned.

![](_page_42_Picture_13.jpeg)

## Summary

![](_page_43_Figure_1.jpeg)

- QZSS is Japanese regional satellite navigation system to improve not only GNSS availability but also accuracy and reliability.
  - 4 satellite constellations: Three IGSO and one GEO satellites.
  - Three consecutive launches have successfully been conducted in 2017; All four satellites are now ready on their orbits.
- Operational Service begins on November 1, 2018.
  - GPS complement service, GNSS augmentation service including SBAS, and messaging service.
  - Precise positioning service can be utilized in many applications with Multiple GNSS as well as multi-sensors.
  - Some experiments including DFMC SBAS and PPP are also ongoing.

![](_page_44_Figure_0.jpeg)

![](_page_44_Picture_1.jpeg)

## Thank you for your attention.

more information, please visit our web site http://qzss.go.jp/en/

![](_page_45_Picture_0.jpeg)

![](_page_45_Picture_1.jpeg)

![](_page_45_Figure_2.jpeg)

- DFMC SBAS could be transmitted by non-GEO satellites like QZSS IGSO.
- Transmission from the Zenith: Improves availability of augmentation signals where GEO signal is blocked.
  - Polar regions, mountain area, urban canyons, building on the south side, approaching aircraft, and so on.

![](_page_45_Picture_6.jpeg)