

# Galileo Terrestrial Reference Frame (GTRF)- Status

Werner Enderle on behalf of the GGSP Consortium ICG-13 Meeting 04-09 November 2018, Xi'an, China





GÉOGRAPHIQUE ET FORESTIÈRE

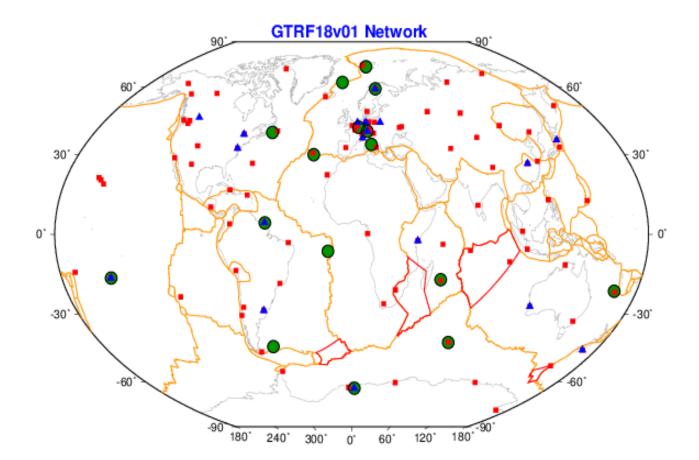
#### GTRF Generation Latest realization: GTRF18v01



- The GTRF18v01 was obtained by accumulating (rigorously stacking) the 406 weekly GTRF combined solutions spanning 11.66 years
- GTRF18v01 is aligned to ITRF2014 (through IGS14) using the minimum constrains approach over a set of 83 IGS/ITRF stations, located in 63 sites
- The GTRF18v01 combination process makes use of:
  - 1. annual and semi-annual signals present in the station position time series were estimated during the stacking, and
  - Post Deformation (PSD) parametric models were applied to the coordinates of stations that are subject to major earthquakes before stacking the time series.

#### **Tracking Network for the GTRF – All stations**

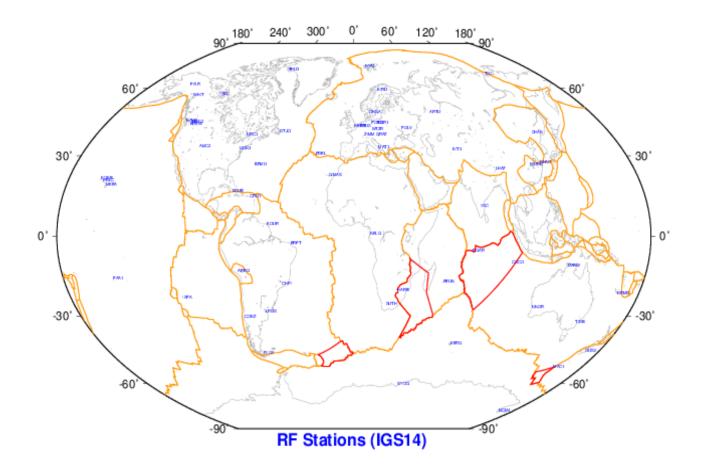




Latest GTRF Realisation: GTRF18v01 includes 193 stations in 111 sites red squares: ITRF/IGS stations Green/blue: GSS/GESS sites

#### **Reference Frame Network for the GTRF**

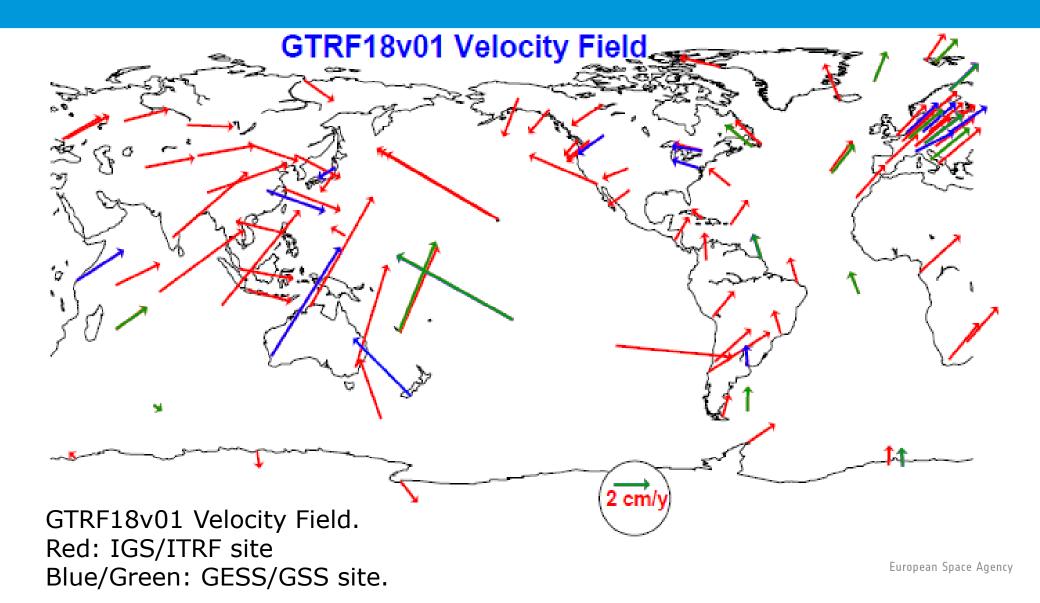




Latest GTRF Realisation: GTRF18v01 includes 193 stations in 111 sites red squares: ITRF/IGS stations including 63 reference frame stations Green/blue: GSS/GESS sites

#### **GTRF Velocity Field**





#### **GTRF Releases in 2018**

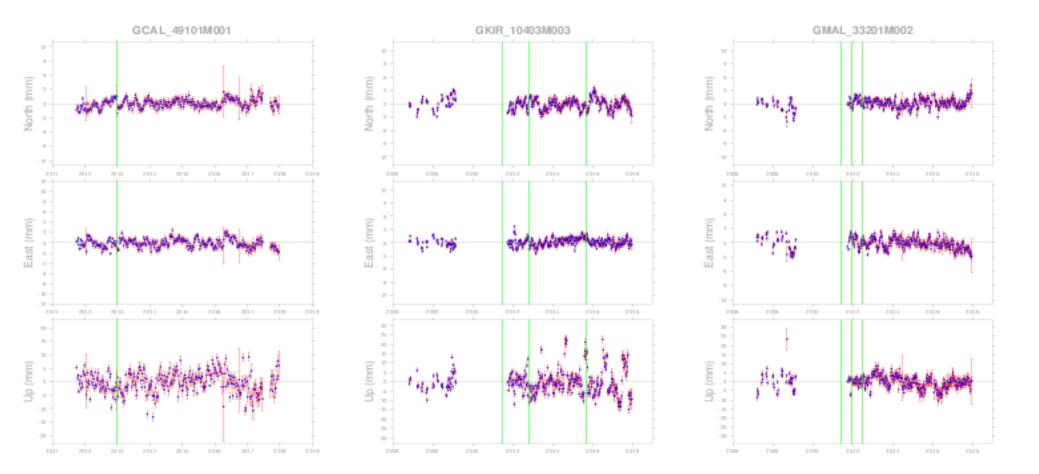


## - GTRF18v01

- Released July 2018
- Rigorously aligned to ITRF2014
- Next update is expected in 2019

#### **GESS station time series - Examples**

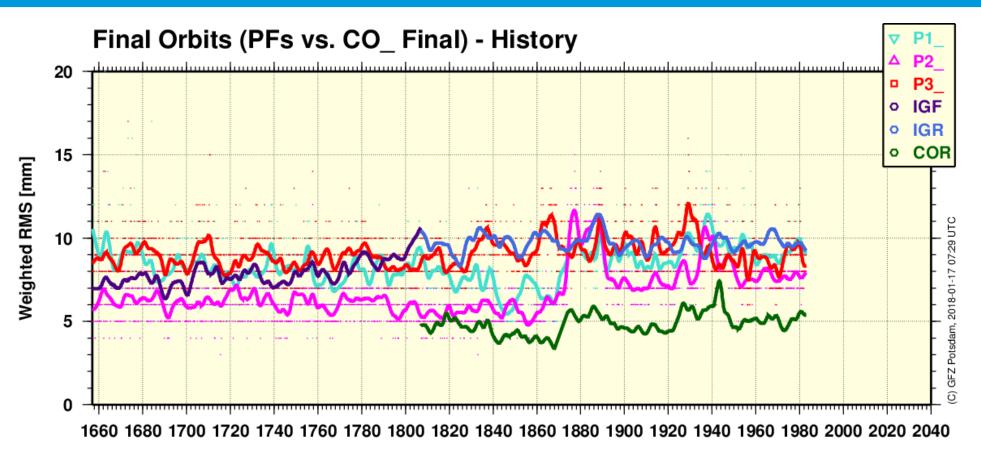




#### Green lines: Estimated discontinuities Red bars: formal error of weekly solutions

### **Orbit Combination (Final, full history)**



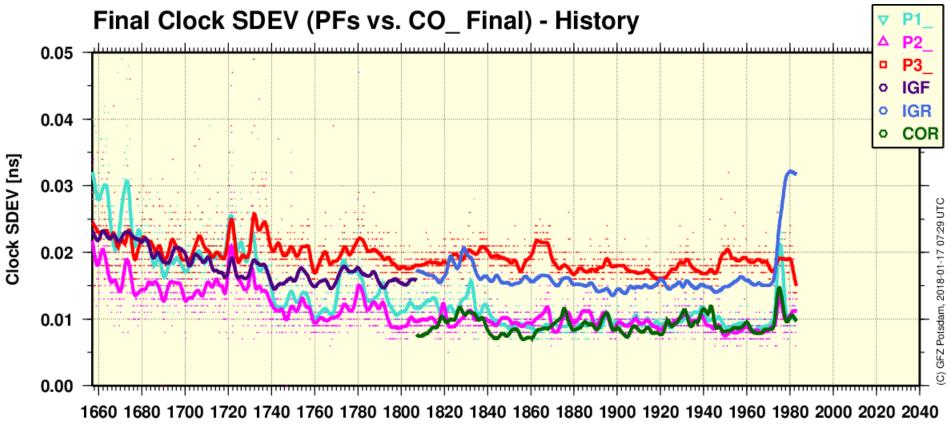


Time [GPS weeks]

- Orbit RMS agreement btw PFs and combined (co\_) orbits for GPS satellites
  - Agreement mostly at the level of 5-10 mm
- COR is combined rapid product, IGF is IGS Final and IGR is IGS Rapid

#### **Clock Combination (Final, full history)**



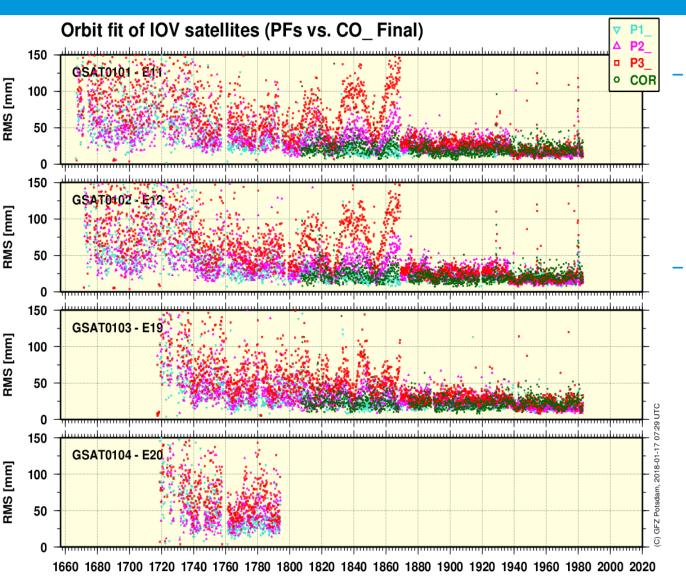


Time [GPS weeks]

- Agreement for the clocks shows RMS of about 8 to 25 ps
  - all biases subtracted

# Galileo final PF and OVF rapid orbit solutions compared to OVF final



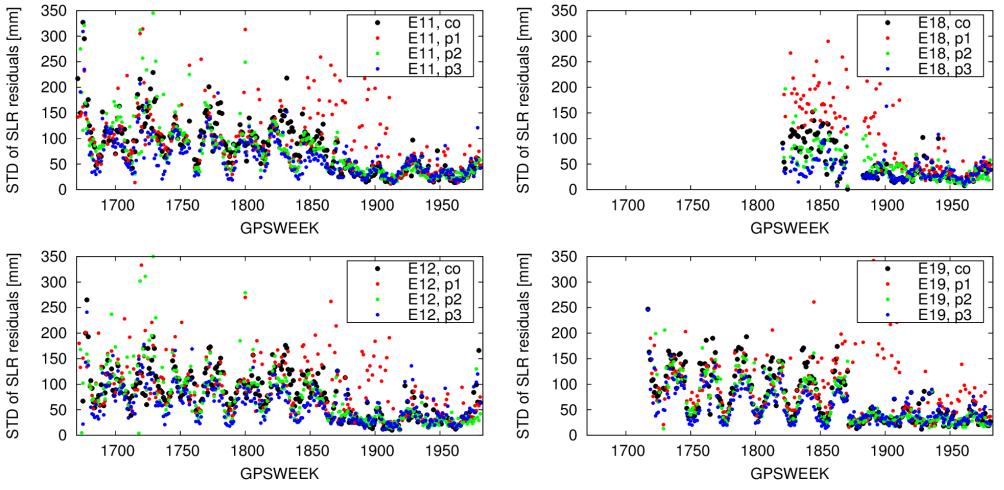


- Difference between PF and co\_ Galileo orbits are in the range of 50 to 150 mm (with outliers in case of data problems)
- From week 1873: Improved modeling with ECOM2 (PF1 and PF3) and Box-Wing (PF2) significantly improved agreement to 10 to 60 mm level.

Time [GPS weeks]

#### SLR Residuals Standard deviation





The SLR residuals are confirming the overall orbit accuracy (3D – 1 Sigma) of 10 – 20 cm

Notice improvement thanks to improved modelling starting week 1873







- Validation is carried out on a weekly basis when the last reference product is available (in general, the IGS troposphere solution)
- Validation result is a weekly summary file (vf\_wwww7.sum)
- Example from summary file (vf\_19817.sum)
- High quality, demonstrated by the RMS of Helmert-transformation (see table below)

			#sites	North [mm]	East [mm]	Up [mm]
IGS14	RMS ,	/ COMPONENT	71	2.63	2.53	6.43
IGS14week	RMS ,	/ COMPONENT	117	1.88	1.96	5.10
GTRF17V0e	RMS ,	/ COMPONENT	111	2.16	1.82	5.33



#### **THANK YOU**

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