



# NavIC Availability, Performance and Advantages

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**Date: 10 December, 2019**

**ICG-14, Bengaluru**



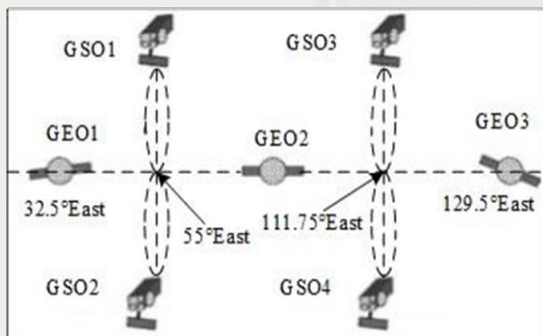
# AGENDA



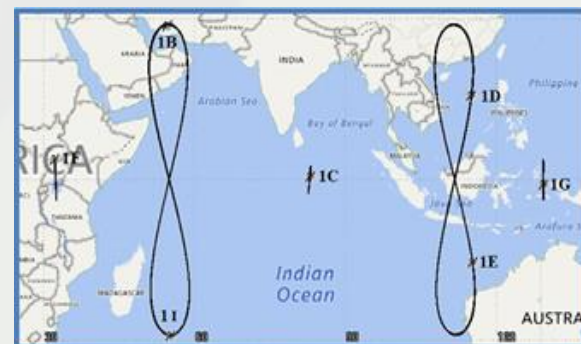
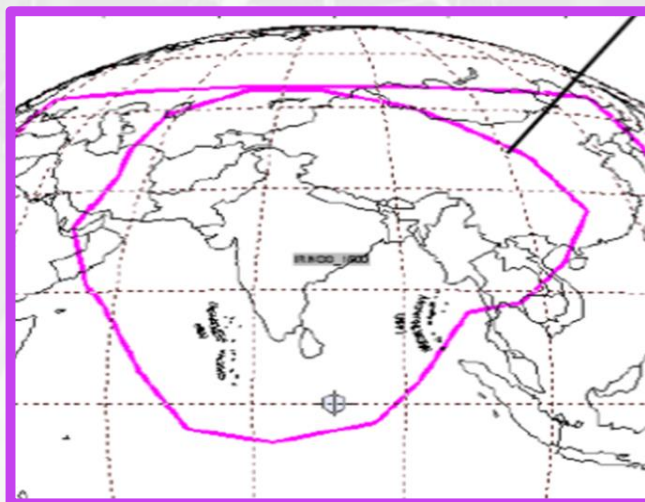
- **NavIC: Constellation**
- **Visibility**
- **Offshore NavIC reception report**
- **Accuracy**
- **GNSS Visibility Issue and NavIC Support**
- **NavIC hardware modules**
- **Concluding Remarks**



# NavIC Constellation

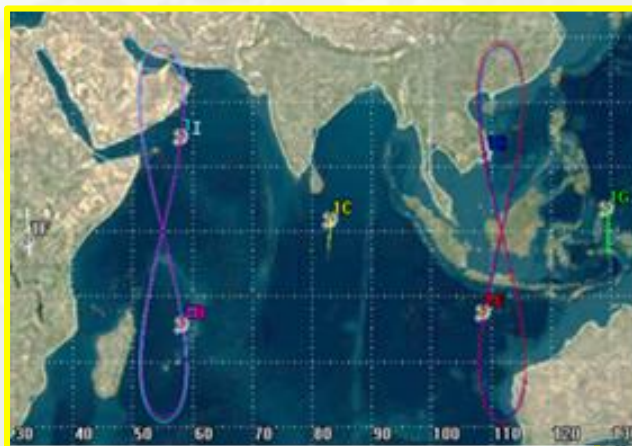


NavIC Constellation

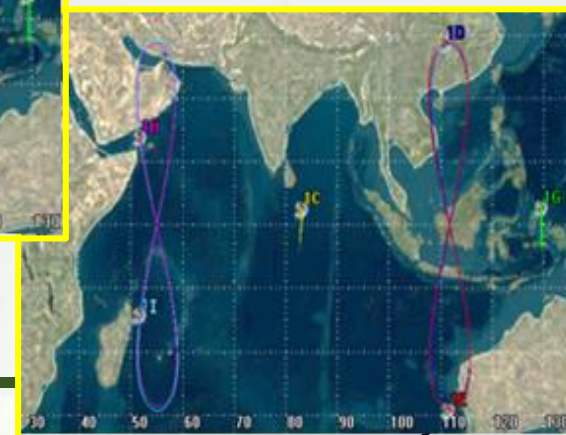


NavIC Typical Footprint

- Complimentary Coverage
- GEO/ GSO satellites (fixed/ low-varying IPP)
- **S Band** operation with L5 supports Enhanced Interference/ Jamming resistance



Best geometry



Worst geometry



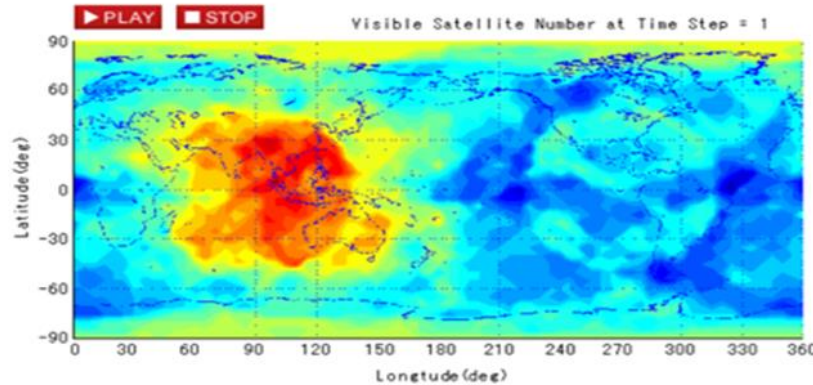


# Multi-GNSS: Advantage Asia

## (Skyplot from Javad Triumph LS Multi GNSS receiver)

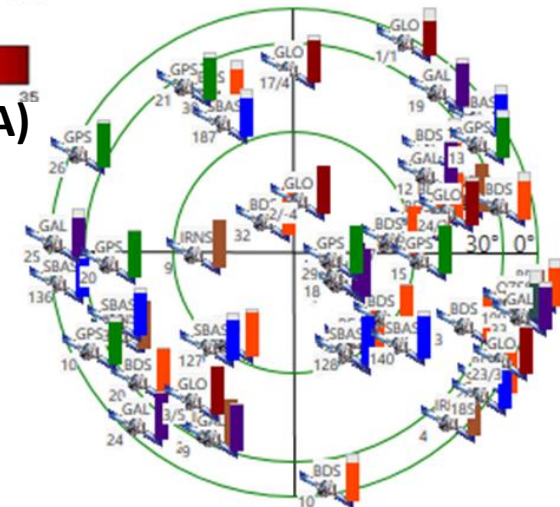
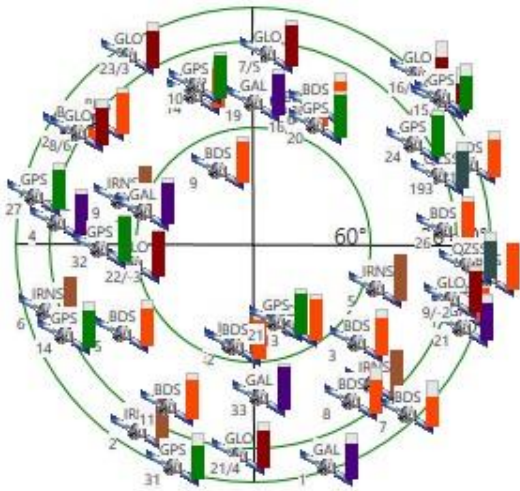


Asia Oceania Region is Showcase of New GNSS Era  
GPS+GLONASS+Galileo+COMPASS+IRNSS+QZSS



Courtesy: Multi GNSS Asia (MGA)

GPS+GLONASS+Galileo+Beidou  
+NavIC+QZSS



Typical skyplot for Eastern India  
(04 December, 2019: 10:15 hrs IST)

48 satellites in view, 46 used

Typical skyplot for Western India  
(23 June, 2019: 18:11 hrs IST)

54 satellites in view, 45 used



# Simulation Tool integrating STK, Matlab



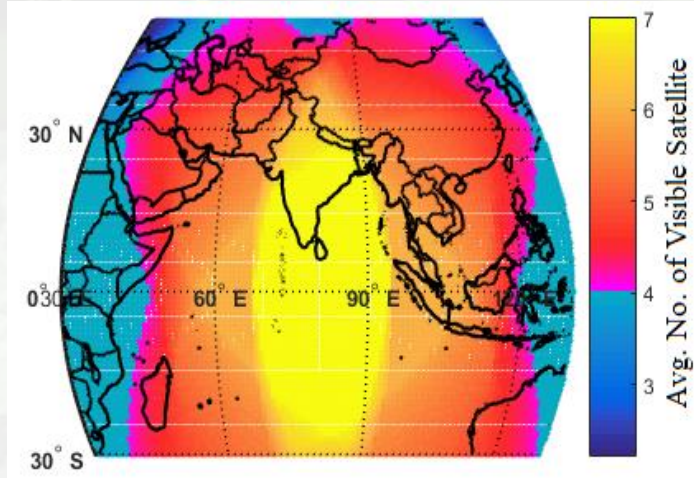
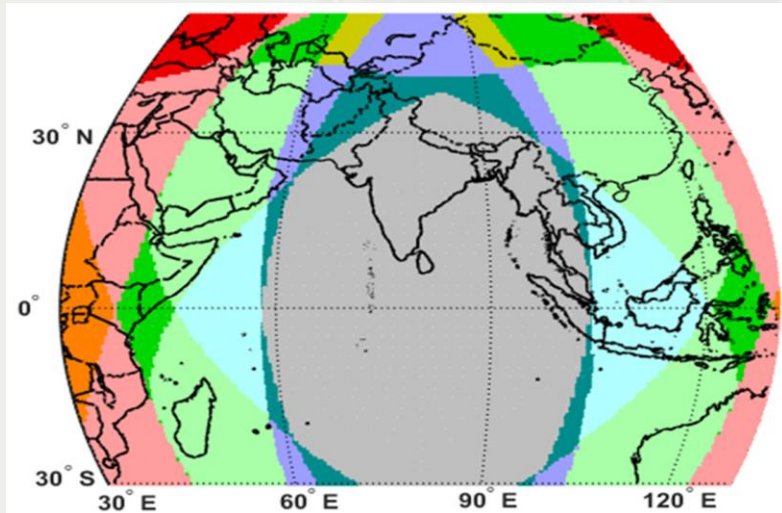
- ❑ A simulation tool was developed integrating System Tool Kit (STK) and MatLab, generates Look Angles (Elevation and Azimuth) for the GNSS satellites
- ❑ GNSS satellite visibility scenario are created for any observation point
- ❑ The Tool is used to generate global GNSS satellite visibility scenarios at grid points separated by  $5^\circ$  in latitude and longitude ( $5^\circ \times 5^\circ$ )
- ❑ Simulated results are validated; GSLP is used for NavIC visibility prediction

The screenshot displays the GSLAP software interface. On the left, a window titled "GSLAP" contains the title "GNSS Satellite Look Angle Predictor (GSLP)" and credits: "Developed By Sukabya Dan, GNSS Laboratory Burdwan, The University of Burdwan, https://bugnss.webs.com/, Financial Support by Space Applications Centre (SAC), ISRO". A "Next" button is visible. The main window, titled "GSLAP\_ELE\_AZI", features several panels for satellite selection: GPS (GP\_01 to GP\_32), GLONASS (GL\_716 to GL\_S-M), GALILEO (GA\_01 to GA\_33), and IRNSS. A "Constellation" legend indicates the selected constellations. Below the selection panels, the "Starting Time" is set to 2018 12 03 0:0:0, the "Stopping Time" to 2018 12 03 12:0:0, and the "Step (in Minutes)" to 5. A "Load Data" button is present. On the right, a polar plot shows satellite visibility scenarios with various satellite IDs (e.g., GP13, GL733, GA12, GA26) plotted against Azimuth and Elevation. The plot includes a grid and a "Load Data" button. At the bottom right, the current Azimuth is 298.7007 and Elevation is 12.0609. The date and time are shown as 2018 / 12 / 03 0 : 0 : 0.





# NavIC visibility



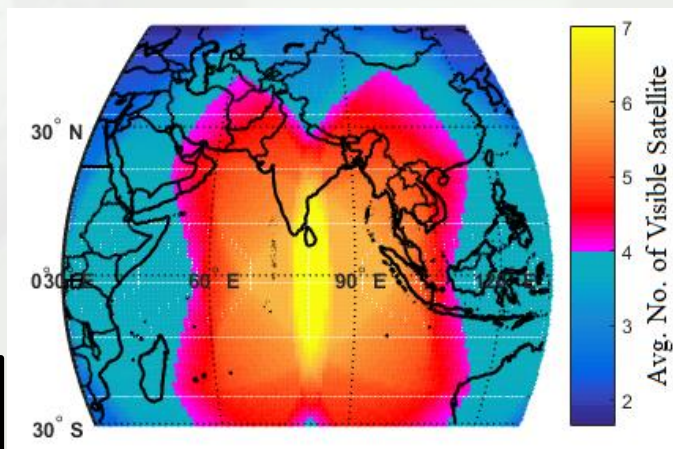
**20° elevation mask angle**

Colour Code	Maximum No. of Satellite	Minimum No. of Satellite	Colour Code	Maximum No. of Satellite	Minimum No. of Satellite
	7	6		5	4
	7	5		5	3
	7	4		Always 7	
	6	5		Always 6	
	6	4		Always 4	

**10° elevation mask angle**

Even with 20 or 30° elevation mask, over a large area of the globe sufficient NavIC satellites are available

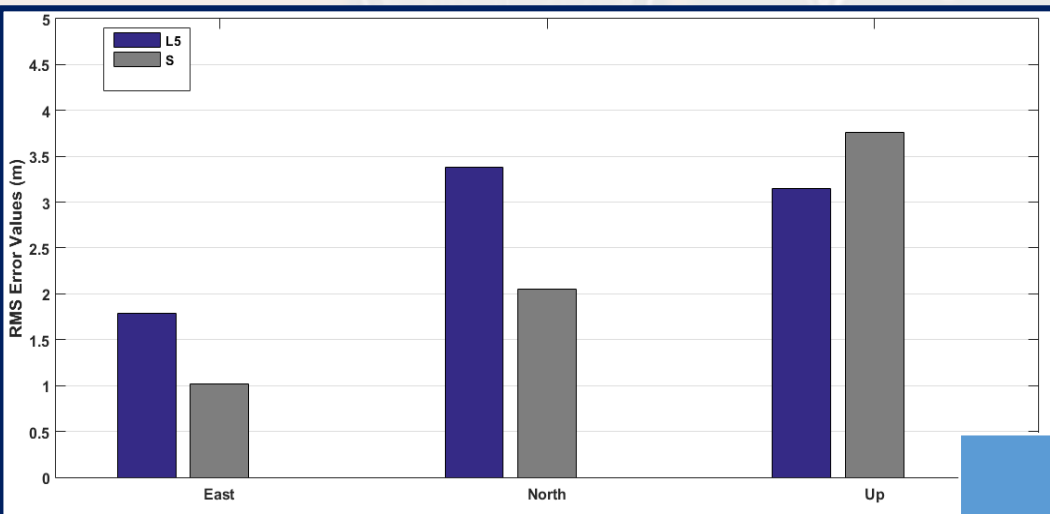
Users in and around India may obtain the benefit of NavIC



**30° elevation mask angle**



# NavIC Solution Accuracy (Receiver: IRNSS-GPS-SBAS [IGS] )



## Precision and Accuracy

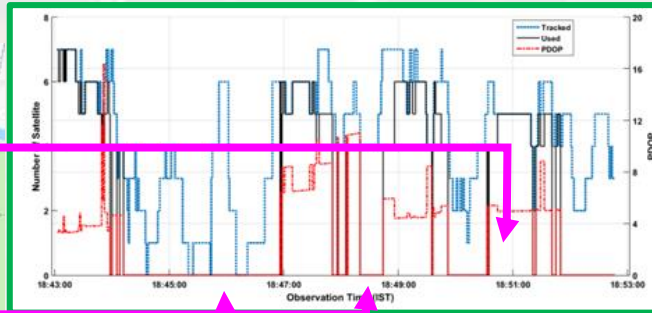
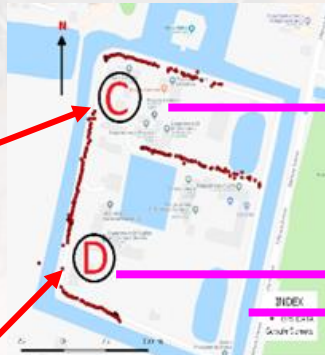
**Single Point Position  
solution components,  
GLB, Burdwan, India,  
February, 2019**

Operation Mode	Precision				2d Offset (m)	3d Offset (m)
	2DRMS (m)	CEP (m)	SEP (m)	MRSE (m)		
L5	6.97	2.68	3.83	4.65	1.57	1.71
S	4.51	1.80	3.30	4.13	0.39	1.53

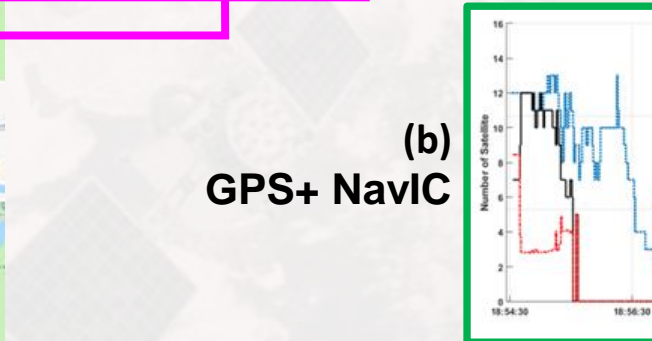
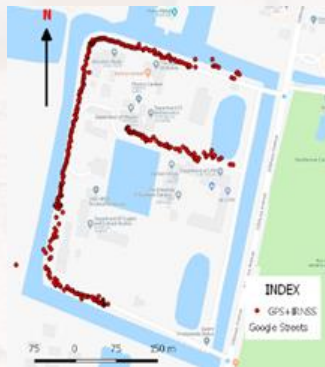




# NavIC supporting navigation in real-life environment (University of Burdwan Campus)



(a)  
GPS



(b)  
GPS+ NavIC

## Number of tracked and used satellites and satellite geometry using IGS receiver on 1 June 2018

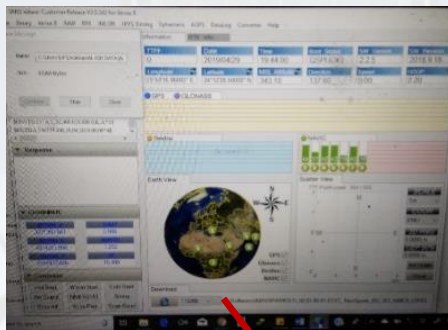
“A Study using Multi-GNSS Services in Indian Semi-Urban Environment”, Atanu Santra, Somnath Mahato, Prasenjit Ghosh, Sukabya Dan and Anindya Bose, Proc. MDCCT 2018, The University of Burdwan, India, 2018, pp. 77-80

Total Epochs	GNSS constellation(s) used	Solution Success Rate
587	GPS	45.99%
570	GPS+NavIC	58.07%

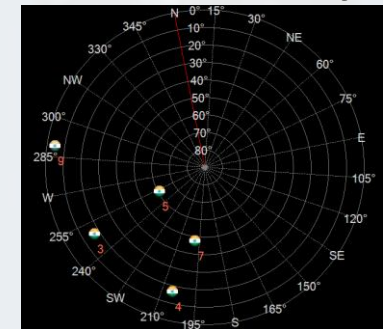




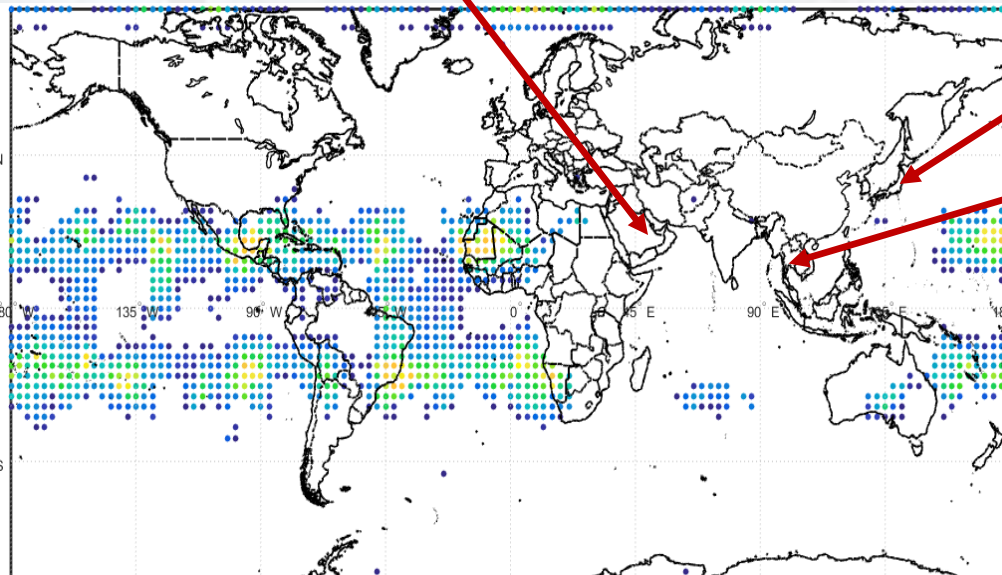
# NavIC International Data Collection Efforts



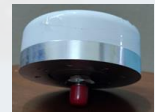
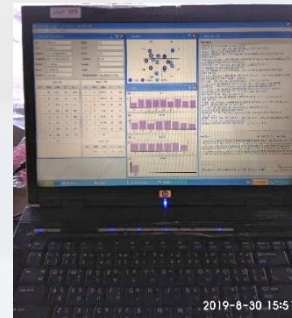
**TUMSAT, Tokyo, Japan**  
From field surrounded by buildings  
Receiver used: Allystar (L5)



**AI-AIN, UAE**  
Data for small time, not all-in-view visibility  
Receiver used: Skytraq (L5)



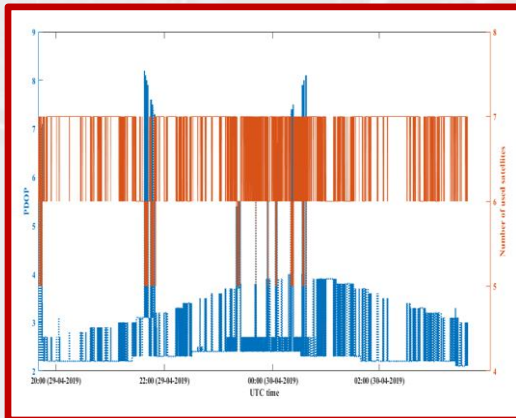
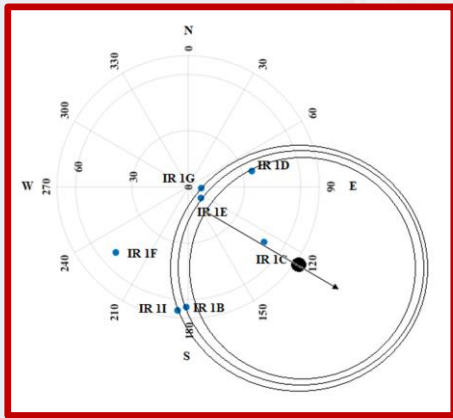
**NIMT, Bangkok, Thailand**  
Clear view of the sky, 7-day data  
L5, S, NavIC+GAGAN  
Receivers used: Allystar (L5); Elena (L5 +S)



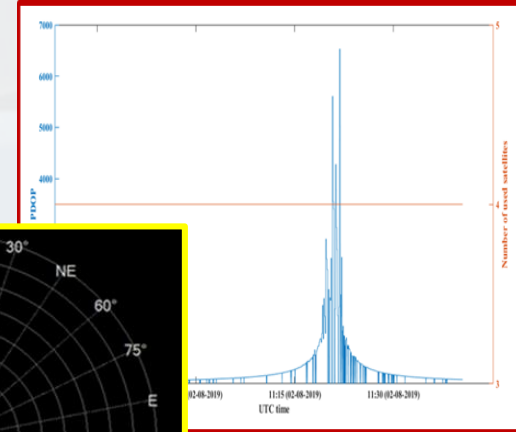
S-Band capable Antenna used



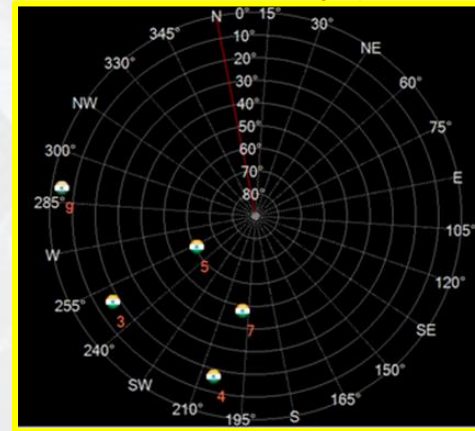
# Results



**AL AIN,  
UAE**



**TOKYO,  
JAPAN**

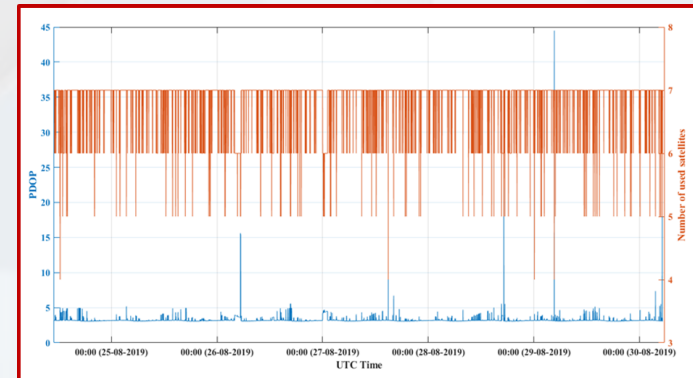
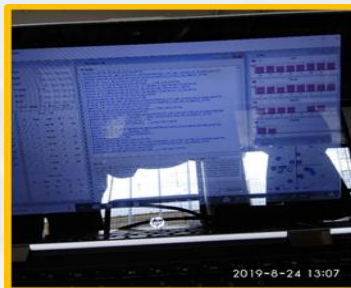


**Skyplot :01:16:19 UTC  
30-04-2019**      **Satellite visibility and geometry**

The **black dot** denotes the symmetry axis of the cone formed by satellites IR 1D, 1B, 1E and 1I i.e., the direction in which the receiver position estimate is poorest [1].

[1] "IRNSS stand-alone positioning: first results in Australia, Journal of Spatial Science", S. Zaminpardaz, P. J. Teunissen and N. Nadarajah, 2016, 61(1), pp.5-27

**Pathum  
Thani,  
Thailand**



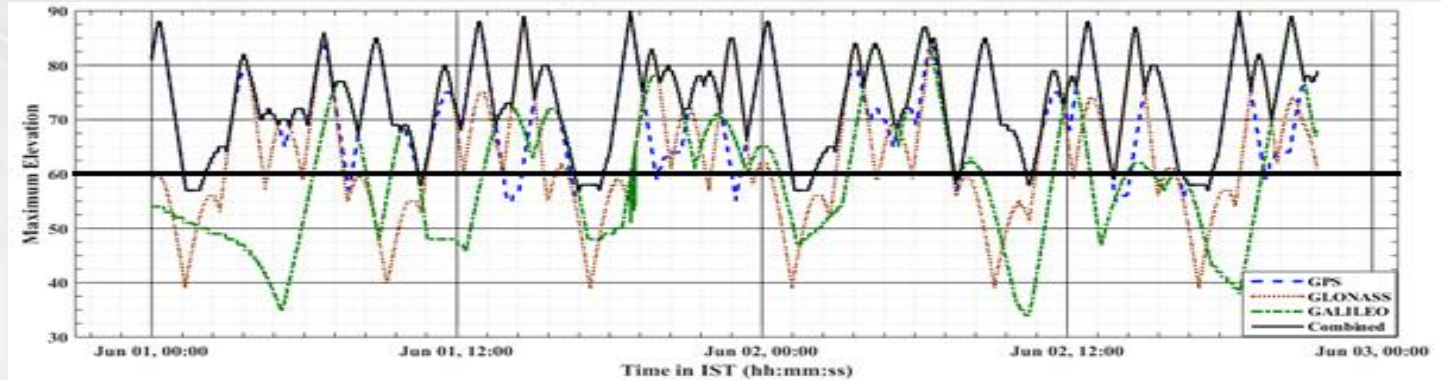
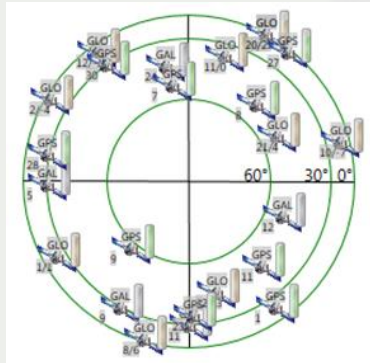




# GNSS Visibility Issue (from GLB, Burdwan, INDIA)



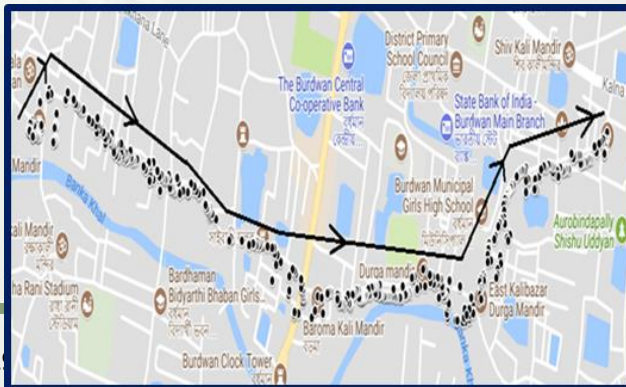
During some parts of the day, all GPS+GLONASS+Galileo satellites lie below 60° elevation angle



Typical 'skyplot' for all tracked satellites below 60° elevation angle for GPS+GLONASS+Galileo satellites. Maximum elevation of tracked satellites in standalone and hybrid GNSS operation (June 2017 from GLB, India)

During the affected period of "No GNSS above 60°", from a restricted satellite visibility region with obstruction from lower elevation angles, solution performance and quality degrades.

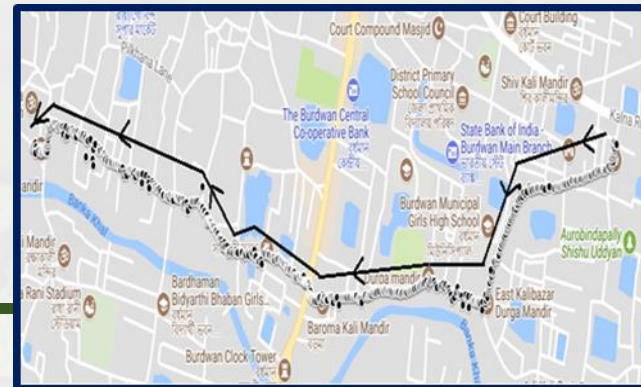
Affected period



12/27/201

ISRO

Normal period

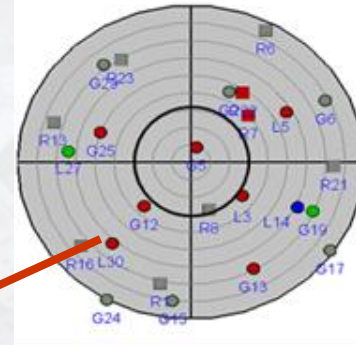
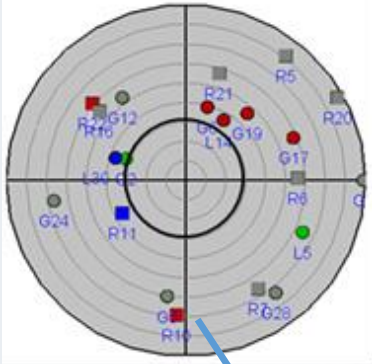


11





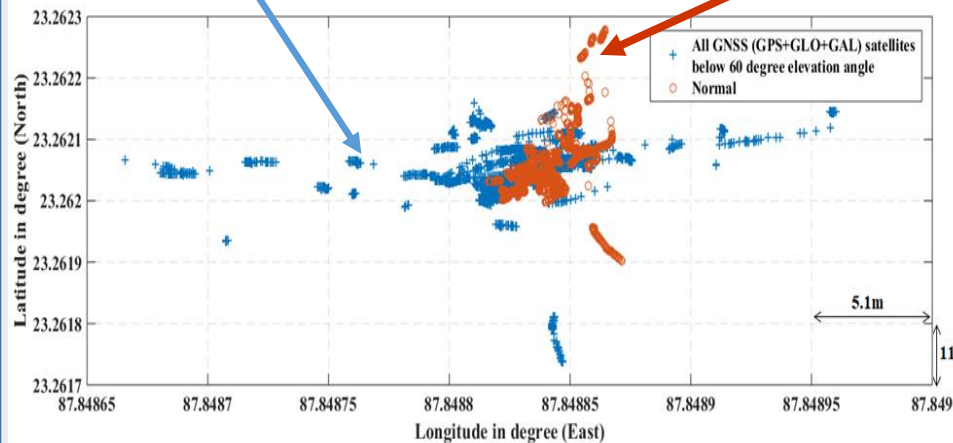
# Consequences of the situation (Static Case, GNSS, Burdwan, INDIA)



A Multi-GNSS receiver in GPS+GLONASS+Galileo mode is used within a constrained city environment

Table: Comparison of position solution in normal and affected periods for static hybrid (GPS+GLO+GAL) operation in constrained city environment of Burdwan, India, 14 July 2018

Condition (Time, IST)	Total Epochs (Average PDOP)	Total Solution Obtained (Solution Success)	Maximum Variation (m)			2DRM S (m)	CEP (m)	SEP (m)	MRSE (m)
			Lat	Lon	Alt				
Normal (06:53 – 07:10 and 08:24 – 09:14)	4012 (3.05)	4012 (100%)	41.8	5.64	26.08	11.74	4.22	5.45	6.97
Affected period (07:10 -08:24)	4441 (6.23)	4146 (93.35%)	46.94	30.05	126.05	11.8	4.87	11.30	15.17

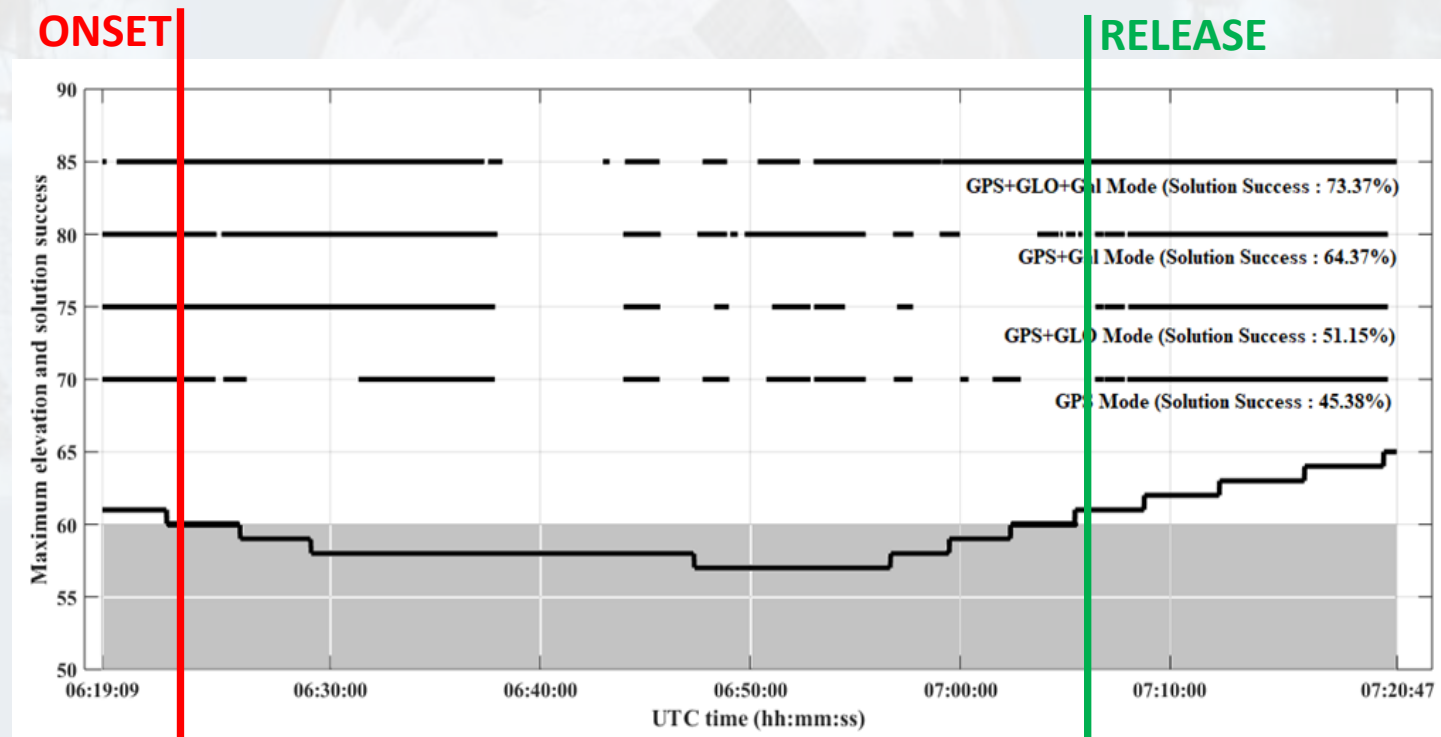




# Consequences of the situation (Static, GNSS, Burdwan, INDIA)



- Data collected within an urban canyon using a “Record and Replay” system
- **GPS+ GLONASS+ Galileo data was recorded before, during and after the affected period**
- Recorded data was played back through a multi-GNSS receiver.
- **Position solution success rates for GPS and Multi-GNSS combinations were calculated**



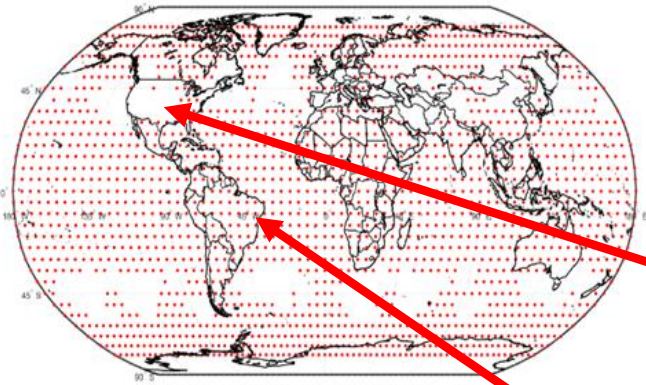




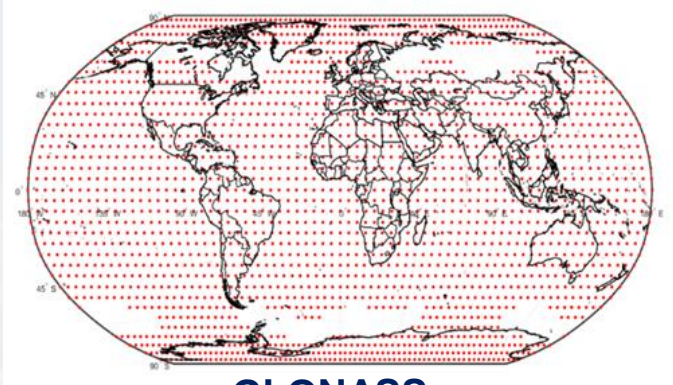
# Global Scenario and Validation using IGS data



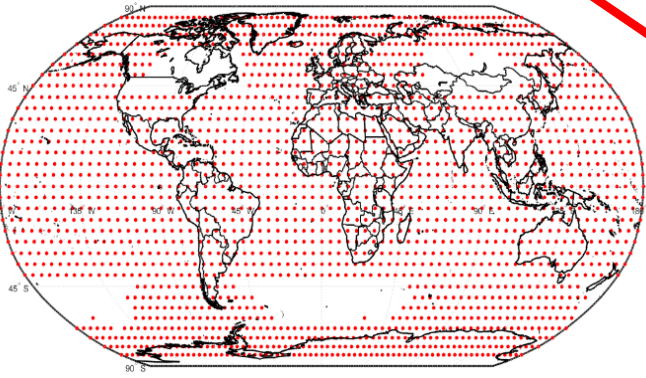
The **red dots** show the locations where all satellites lie below 60 deg elevation angle for more than 20 minutes over a day.  
(24 April 2018)



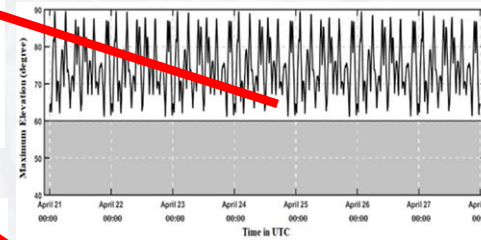
**GPS**



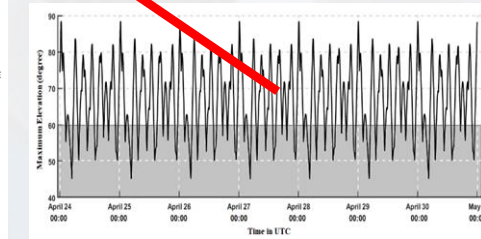
**GLONASS**



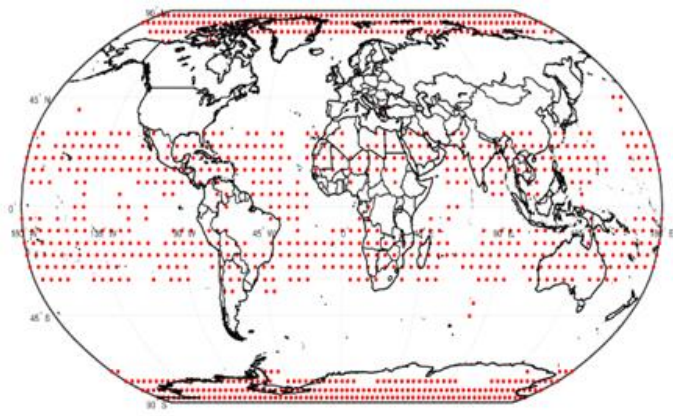
**GALILEO (22 satellites)**  
06 April 2019



**Quincy (42.2529° N, 71.0023° W),  
United States (QUIN)**



**Addis Ababa (8.9806° N, 38.7578° E),  
Ethiopia (ADIS)**

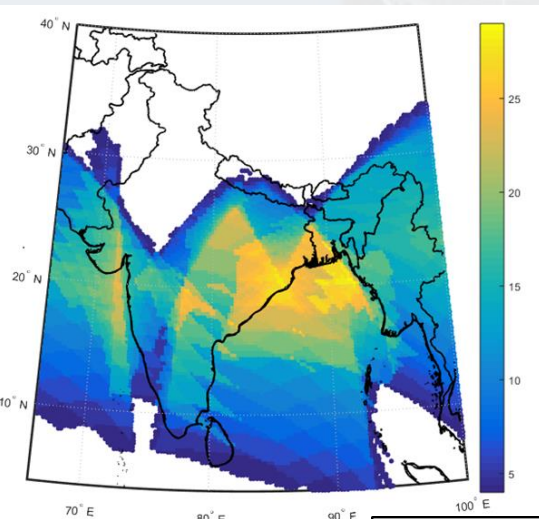


**GPS+GLO+GAL**

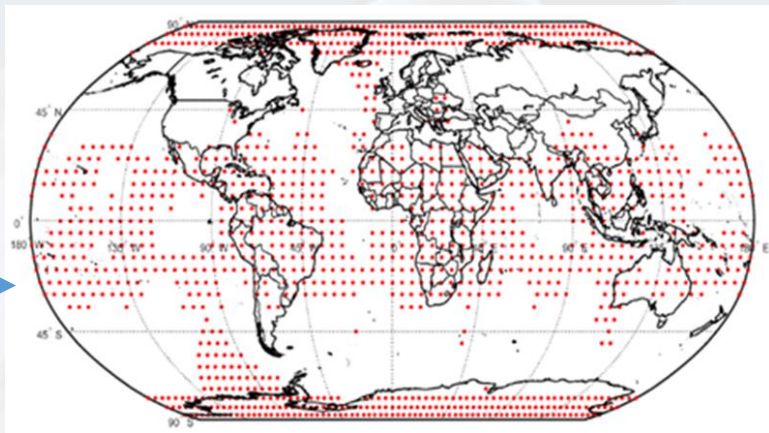




# NavIC supporting navigation in such situation

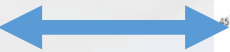
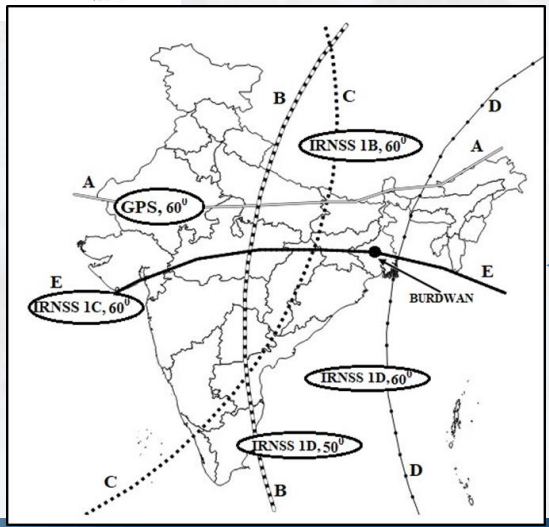


GPS+  
GLONASS+  
GALILEO

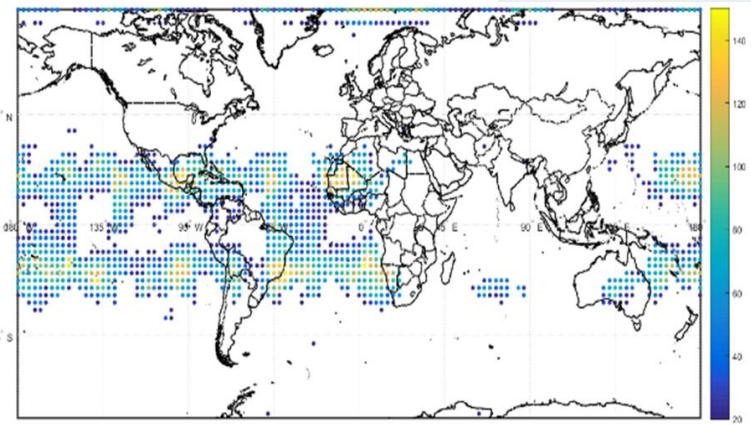


GLOBALLY

FOR INDIA

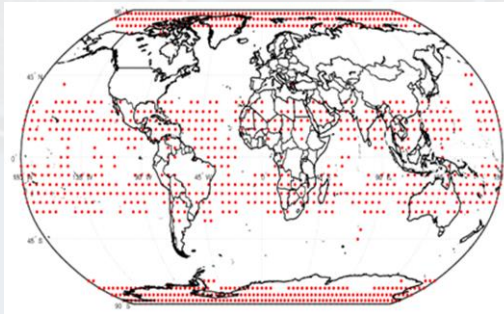


GPS+GLONASS+  
GALILEO+NavIC

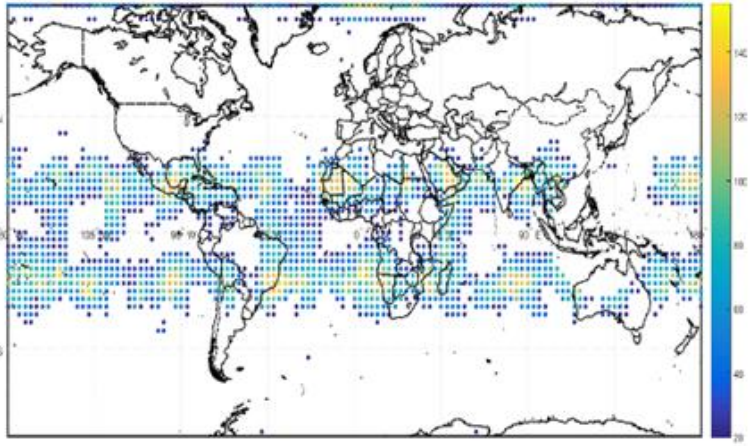




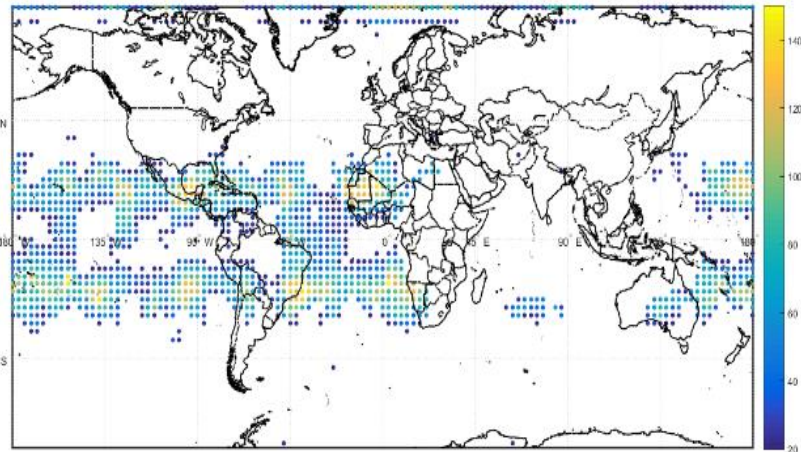
# GNSS + QZSS or NavIC



GPS+GLONASS+ Galileo



GPS+GLONASS+Galileo+QZSS



GPS+GLONASS+Galileo+NavIC

Cumulative time span of the problem for more than 20 minutes over a day (03 December 2018)

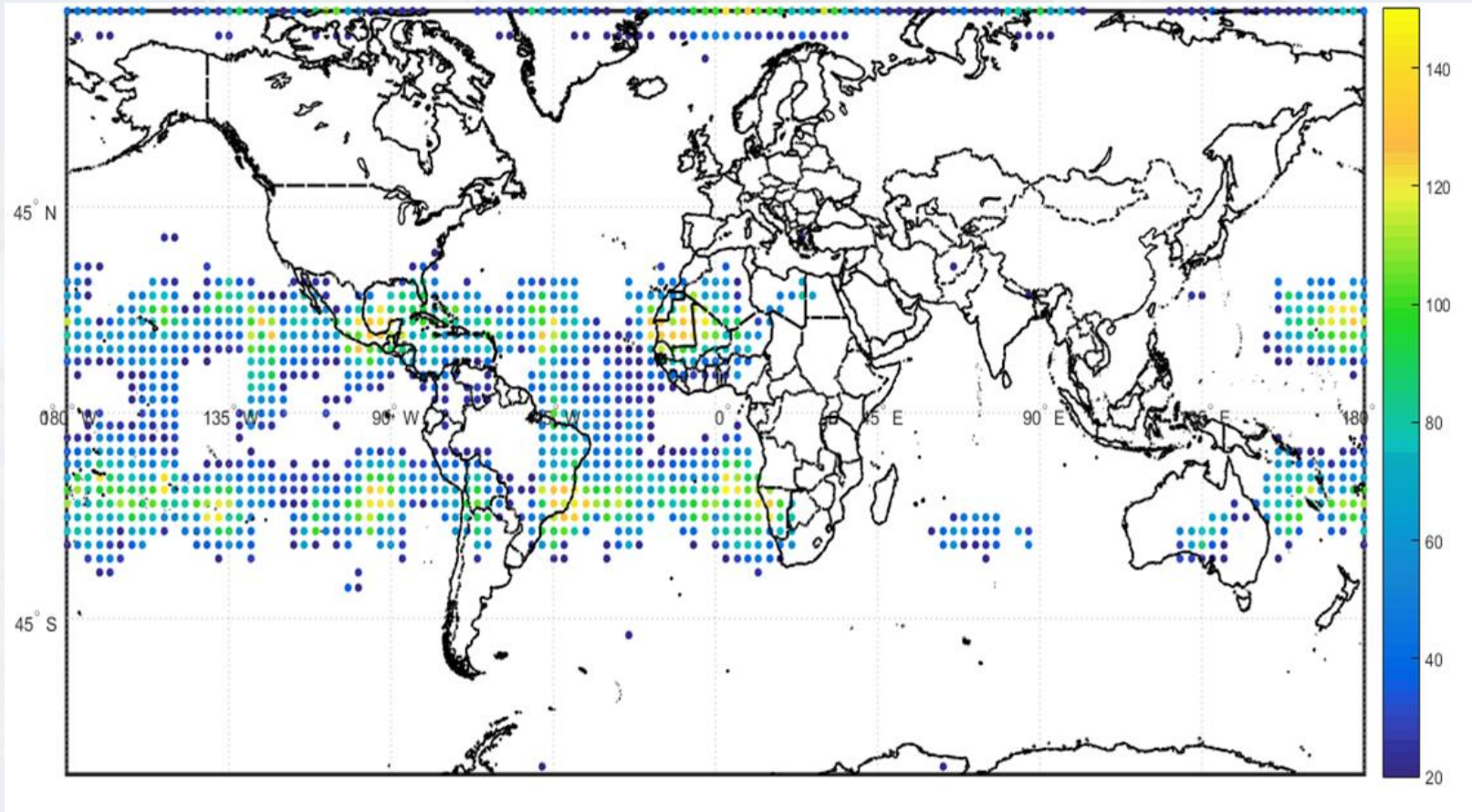
**NavIC shows the capability of mitigating the problem of limited GNSS visibility over a larger part of the globe**

“Augmentation of GNSS Utility by IRNSS/ NavIC Constellation Over the Indian Region”, Atanu Santra, Somnath Mahato, S Mandal, Sukabya Dan, Pratibha Verma, P Banerjee and Anindya Bose, *Advances in Space Research*, 63(9), pp 2995-3008, (2019) DOI: <https://doi.org/10.1016/j.asr.2018.04.020>





# GPS+GLONASS+Galileo + QZSS +NavIC



**Using NavIC and QZSS with the global systems, over a large part of the globe, the problem of time-dependent limited visibility disappears**





# Available NavIC Hardware at GLB (Survey Grade and Compact)



NavSpark  
GPS+GLONASS+  
NavIC



Quicktel  
GPS+NavIC



IRNSS-GPS-SBAS (IGS) Receiver **L5+S**



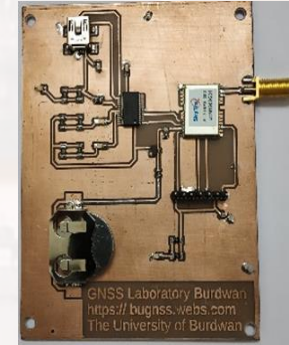
JAVAD Triumph LS and DELTA      Leica  
Commercial Survey-grade Receivers **L5**



Telit  
GPS+NavIC



Allystar  
GPS+NavIC



GLB NavIC module  
Version 1.0  
(NavSpark Chip)

**L5**



**RACELOGIC**

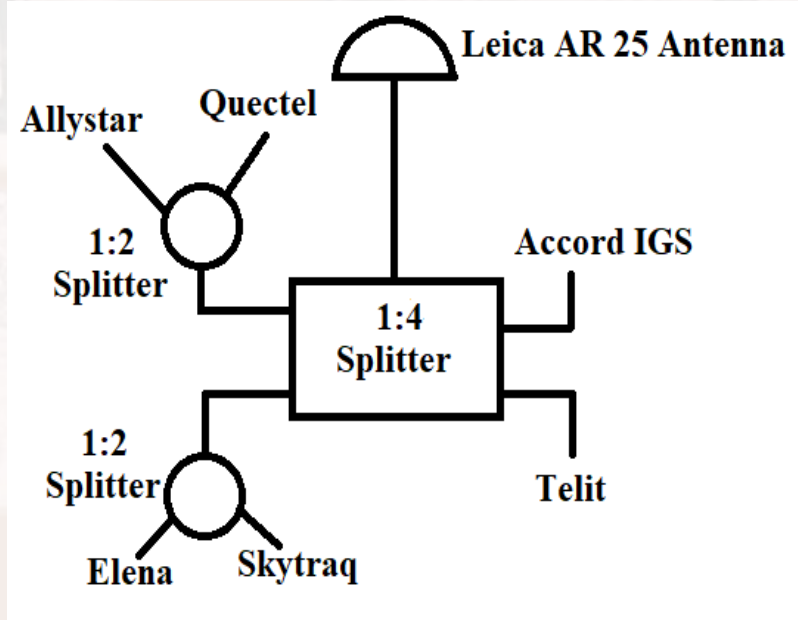
Record and Replay System **L5**



ELENA  
GPS+NavIC  
**L5+S**



# Performance comparison of compact NavIC modules



- The antenna is in a precise location calculated through PPP using AUSPOS service (True Value) [It is also being used for NTRIP service].
- Data has been collected for NavIC only (7 days) and GPS+NavIC (7 days)
- Parameters of interest are: Data quality, Position solution accuracy, signal strength,
- Future studies would be made on: cold start TTF, interference tolerance, multipath handling capability





# Result: Solution Performance comparison of compact NavIC modules (NavIC L5 only)



Make # (data duration)	Max Latitude variation (m)	Max Longitude variation (m)	Max Altitude variation (m)	2DRMS (m)	CEP (m)	SEP (m)	MRSE (m)	RMS Offset* (m)		
								East	North	UP
<b>#1</b> (7 days)	59.968	41.300	102.400	6.553	2.637	4.641	5.735	1.521	2.934	4.917
<b>#2</b> (5 days)	56.301	38.918	139.570	13.274	5.519	11.395	14.648	4.552	5.386	20.256
<b>#3</b> (7 days)	98.526	81.511	42.100	10.446	4.363	4.788	5.596	3.729	4.081	10.071
<b>#4</b> (7 days)	25.002	18.889	46.150	5.819	2.357	4.618	5.891	1.617	2.575	5.553
<b>ISRO-IGS</b> (7 days)	15.946	7.988	21.389	5.133	2.083	3.560	4.343	1.379	2.273	5.335

\*Precision of Satellite Based Navigation Position Solution: a Review using NavIC Data, Atanu Santra, Somnath Mahato, Sukabya Dan and Anindya Bose, Proc. ICRTCS 2019, National Institute of Technology, Silchar, India, March, 2019

\* RTKLib, <http://www.rtklib.com/>



# Result: Performance comparison of compact NavIC-enabled modules (NavIC L5 + GPS L1)



Make # (data duration)	Max Latitude variation (m)	Max longitude variation (m)	Max Altitude variation (m)	2DRMS (m)	CEP (m)	SEP (m)	MRSE (m)	RMS Offset (m)		
								East	North	UP
<b>#1 (7 days)</b>	10.278	7.368	20.400	2.662	1.106	1.978	2.418	0.859	1.091	2.031
<b>#2 (5 days)</b>	23.576	14.770	31.350	8.795	3.523	5.773	7.006	3.430	3.968	5.986
<b>#3 (7 days)</b>	2.778	2.552	8.500	1.932	0.750	1.215	1.456	0.878	0.852	2.253
<b>#4 (7 days)</b>	14.446	28.929	33.460	2.983	1.240	2.591	3.343	1.114	1.256	3.664
<b>#5 (7 days)</b>	13.333	11.915	48.030	2.467	1.011	1.791	2.199	0.754	1.066	1.868
<b>ISRO-IGS (7 days)</b>	5.277	4.078	9.416	2.095	0.572	1.463	1.750	0.687	0.870	2.374





# FINAL REMARKS



- **NavIC would be beneficial for regions surrounding INDIA**
- **Can enhance Multi-GNSS potential for System Independence, Redundancy and Confidence for the users**
- **NavIC enabled hardware is being increasingly available (Compact, Low-Cost, Power-efficient)**
- **NavIC Single Point Positioning Accuracy in Single Frequency mode is <5m**
- **In really challenged environment, NavIC inclusion with GPS improves position availability from 46% to 58%**

