





Precise Point Positioning (PPP) with Standalone NavIC

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Abstract



➤The average standalone NavIC user solution determination using NavIC Broadcast parameters is achieved to be better than 10m in near real time.

➢In order to further refine the positioning, the proposed technique uses the reference stations dual frequency carrier phase measurements in post facto mode.

The improved solution is obtained in post processing with latency of 3-6 Hrs with refined orbit and clock parameters.

➢ The technique adopted uses Forward Backward Forward Extended Kalman Filter (FBF-EKF) with carrier phase processed measurements whose accuracy is better than code range measurements and solving for instantaneous Reference receiver clock offsets.

Currently the process uses one day span of measurement data to obtain the improved targeted accuracy.



Precise Point Positioning (PPP) With Standalone NavIC









Precise Point Positioning (PPP) allows a single NavIC receiver user to determine position at the centimeter error level in post processing mode using precise satellite orbits and clocks





NavIC performance using Broadcast and Dual Frequency measurements







NavIC Independent Receiver Performance With PPP (Post Facto)



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➤The NavIC user solution thus obtained with an accuracy better than 20cms using smoothened measurement.

➢Further improvements on the accuracy is being analyzed, currently this solutions can be used in many low−precision accuracy applications, surveying and precise positioning requirements.















