



GNSS Data Processing for High-Accuracy Positioning using Low-Cost Receiver Systems

Low-Cost Receiver Systems: Is Centimeter Level Accuracy Possible? RTK/PPK and MADOCA-PPP

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Quiz

- What is the Price of a GNSS Receiver?
 - \$10? / \$100? / \$500 / \$1,000 / \$3,000 / \$10,000 or more?
- What is the Accuracy that you can get from a GNSS receiver?
 - mm, cm, dm, few meters or 10 30m
- But, what are your requirements?
 - Types of Applications
 - Accuracy Requirements
 - Data Logging Methods
 - Static Mode on a Tripod
 - Dynamic Mode on a Car, Tractor or Machine?
 - Real-Time or Post-Processing





Low-Cost Receiver Systems

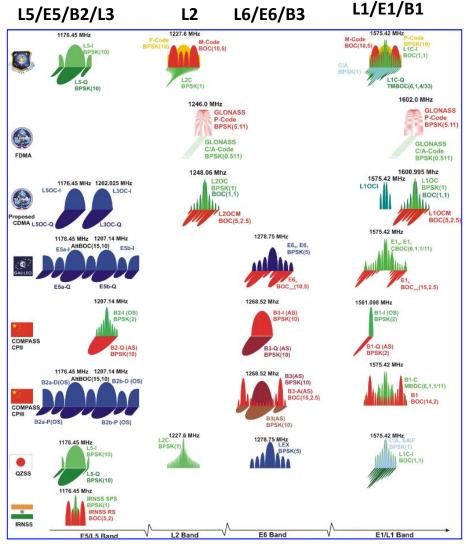




High-End Survey Grade Receivers

- Multi-frequency
 - GPS : L1/L2/L5
 - GLONASS : L1/L2/L3
 - GALILEO : E1/E5/E6
 - BDS

- : B1/B2/B3 : L1/L2/L5/L6
- QZSSNAVIC
- : L5/S
- Multi-system
 - GPS, GLONASS, GALILEO, BeiDou, QZSS, NAVIC, SBAS etc
- Price varies from \$3, 000 to \$30,000 or more

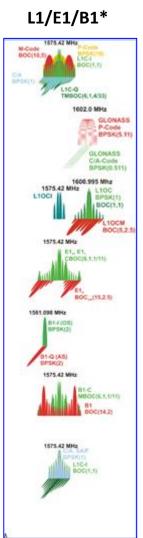






Low-Cost Receivers

- Multi-System
 - GPS, GLONASS, GALILEO, BeiDou, QZSS, SBAS etc
- Basically Single Frequency
 - L1/E1/B1-Band
 - Very soon: Multi-System, Multi Frequency, L1/L2 or L1/L5
 - Future trend for Mass Market System will be L1/L5
 - Some chip makers have already announced Multi-System, Multi-Frequency GNSS Chips for Mass Market
- Low Cost:
 - Less than \$300 (Multi-GNSS, L1 Only) including Antenna and all necessary Hardware, Software
 - Our target is within \$100 or less including everything



*Note: Only one signal type from each system is processed e.g. GPS has L1C/A and L1C in L1, ,but only L1C/A is used in Low-Cost Receiver





Our Definition of Low-Cost Receiver

- Price
- Accuracy
- Weight

- : \$100 or less
- : Better than 100cm
- : 100g or less (Without Battery)

100³ \$100 x 100cm x 100g

Will it be possible?





Many Applications require Low-Cost, Small-Size & Low-Power Receiver System

But, is it possible to get High-Accuracy with Low-Cost Receivers?





Question?

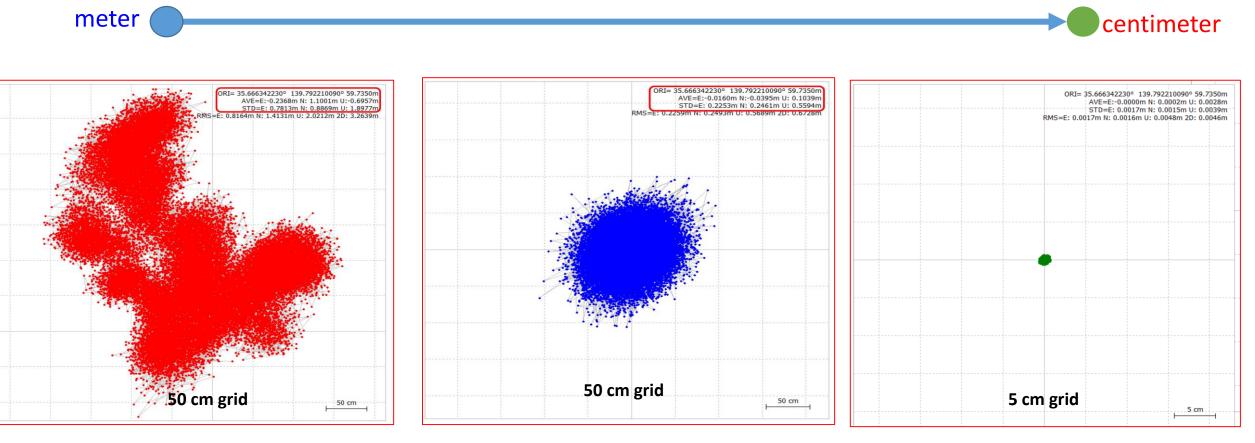
Although the <u>Normal Accuracy of GPS is about 10m</u>, why can we get <u>Centimeter Level Accuracy</u>?





GPS Position Accuracy

How to achieve accuracy from few meters to few centimeters?



SPP (Single Point Position)

DGPS (Differential GPS) Code-phase observation RTK (Real Time Kinematic) Carrier-phase observation





Errors in GPS Observation (L1C/A Signal)

Error Sources	One-Sigr	na Error , m	Commonts				
Error sources	Total	DGPS	Comments				
Satellite Orbit	2.0	0.0	Common errors are				
Satellite Clock	2.0	0.0	removed				
Ionosphere Error	4.0	0.4	Common errors are				
Troposphere Error	0.7	0.2	reduced				
Multipath	1.4	1.4					
Receiver Circuits	0.5	0.5					

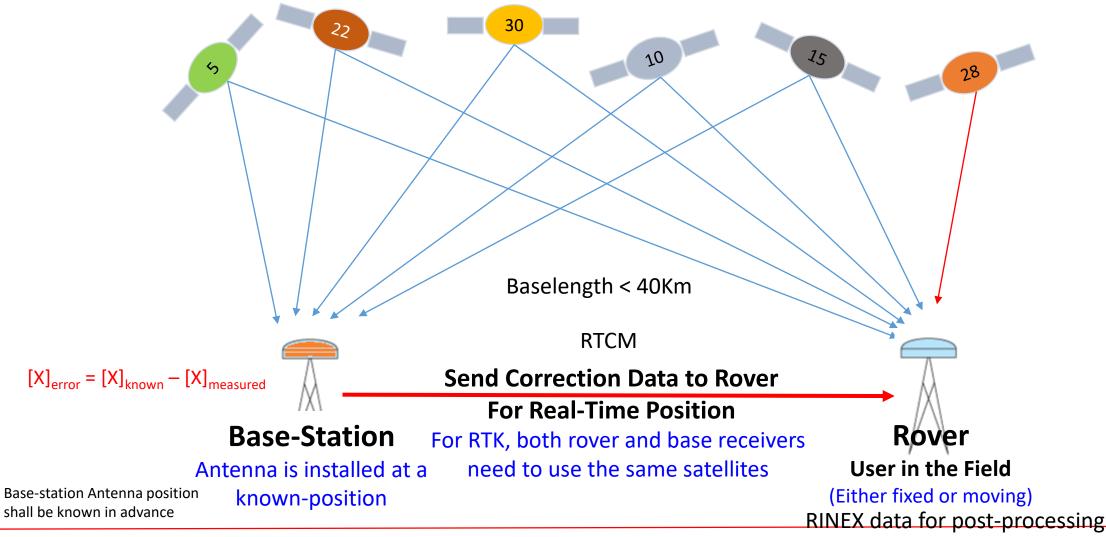
If we can remove common errors, position accuracy can be increased.

Common errors are: Satellite Orbit Errors, Satellite Clock Errors and Atmospheric Errors (within few km)

Values in the Table are just for illustrative purpose, not the exact measured values. Table Source : http://www.edu-observatory.org/gps/gps_accuracy.html#Multipath



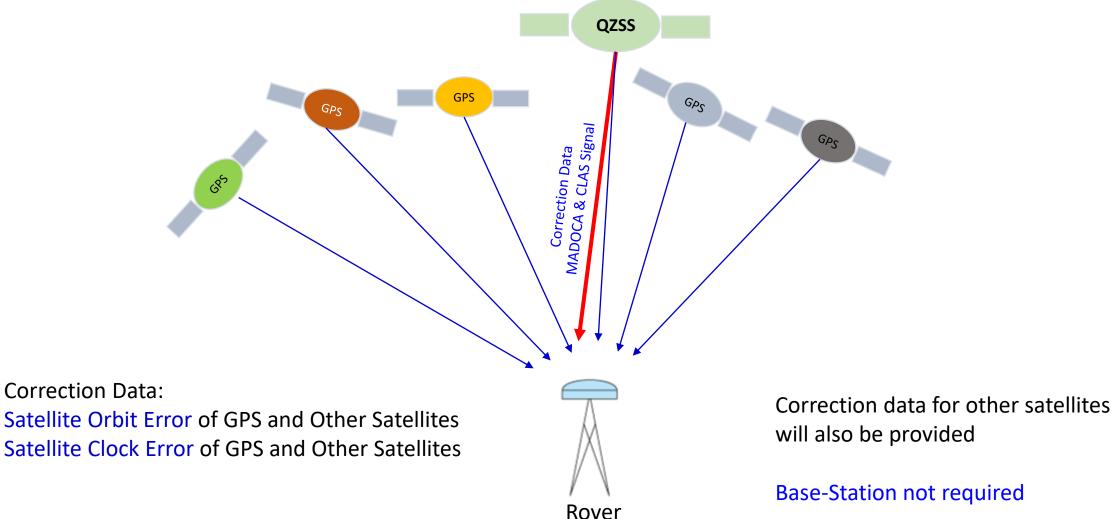
Center for Spatial Information Science The University of Tokyo How to Remove or Minimize Common Errors? Use Differential Correction

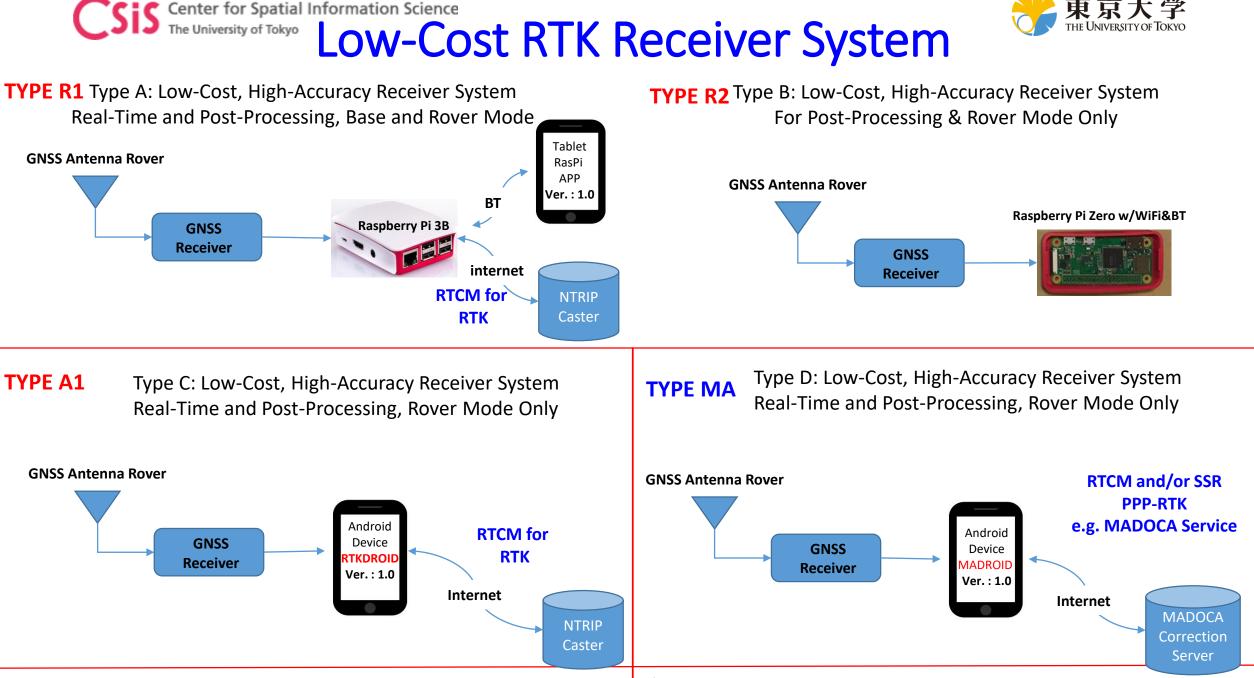




The University of Tokyo How to Remove or Minimize Common Errors? Principle of QZSS MADOCA and CLAS Services

Center for Spatial Information Science





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Туре	Receiver System	Usage	RTK Processing Engine	Mode	User Interface	Base- Station Data	Correction Data Format
Type R1 Beta Version	GNSS Antenna Rover GNSS Receiver WiFi NTRIP Caster	Real-time RTK Base and Rover Setting	Raspberry Pi 3B	Base or Rover	Android Device APP: RTKPI	NTRIP Server	RTCM 3
Type R2 Beta Version	GNSS Antenna Rover Raspberry Pi Zero w/WiFi&BT	Log Raw Data for Post- processing RTK	Raspberry Pi Zero/WiFi&BT Option: RaspberryPi Camera	Rover Only	None	Post- processing	User Defined
Type A1 Release 1.0	GNSS Antenna Rover GNSS GNSS Receiver Tablet RtkDroid APP Ver. : 1.0 WiFi NTRIP Caster		Android Device	Rover Only	Android Device APP: RTKDROID	NTRIP Server or VRS	RTCM 3
Type MA Release 1.0	GNSS Antenna Rover	Real-time PPP Based on MADOCA Correction Data from Internet	Android Device	Rover Only	APP: MADROID	MADOCA Correction Data Server	MADOCA Format

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Screen Shots of RTKDROID and MADROID

Connect GNSS receiver to Android device

(1) RTKDROID : For RTK or PPK

(2) MADROID: for MADOCA-PPP, MADOCA-PPP/AR (future)

10:35	100 lh."	16:16	.all 🔶 🚳	16:16	all 🥱 🚳
RtkDroid	ABOUT	🚴 MADROID	ABOUT	🚴 MADROID	ABOUT
Connection USB	Ψ	UTC Time: 07:16:19 Latitude: 35.68971662° N			
Device Format ubx Processing Settings Rover Mode Kinematic Elevation Mask 10 Ambiguity Res. Fix and Hold Antenna Height (m) 0.0 NTRIP Settings Address	τ τ τ τ τ τ τ τ τ τ τ τ τ τ τ τ τ τ τ	Latitude: 35.689/1652* N Longitude: 139.75281501* E Ellipsoidal Height: 56.785m Orthometric Height: 18.995m Speed: 0.15 km/hr Fix type: Fix RTK Satellites in view: 15 Satellites in use: 15 PDOP: 1.9 HDOP: 1.1 VDOP: 1.6 N	R780* R68 60* R78 67 60* 45* 30* E G5	Date: Sep 15, 2020 Time: 07:16:23 Latitude: 35.68971663° Longitude: 139.75281501° X: 54N 387152.640m E Y: 54N 3950250.977m N Ellipsoidal Height: 56.780m Orthometric Height: 18.990m Fix Type: Fix RTK Speed: 0.09 km/hr HDOP: 1.1 VDOP: 1.6 PDOP: 1.9 Satellites in View: 15 Satellites in Use: 15 Latitude Error: 0.065m	
Port 2101 Mount Point User Name		240 [*] 824 210 [*] 5		Longitude Error: 0.055m Altitude Error: 0.028m	
START ROVER		G G G G G G R R R 20 13 24 15 28 5 84		NMEA: 2020_09_15_16_08_35.txt(27 RAW: 2020_09_15_16_08_35.ubx(2N STOP RECORDI	ИВ)
Setup Status	Skyplot	Setup Status	Skyplot	Setup Status	Skyplot
	•		•		•



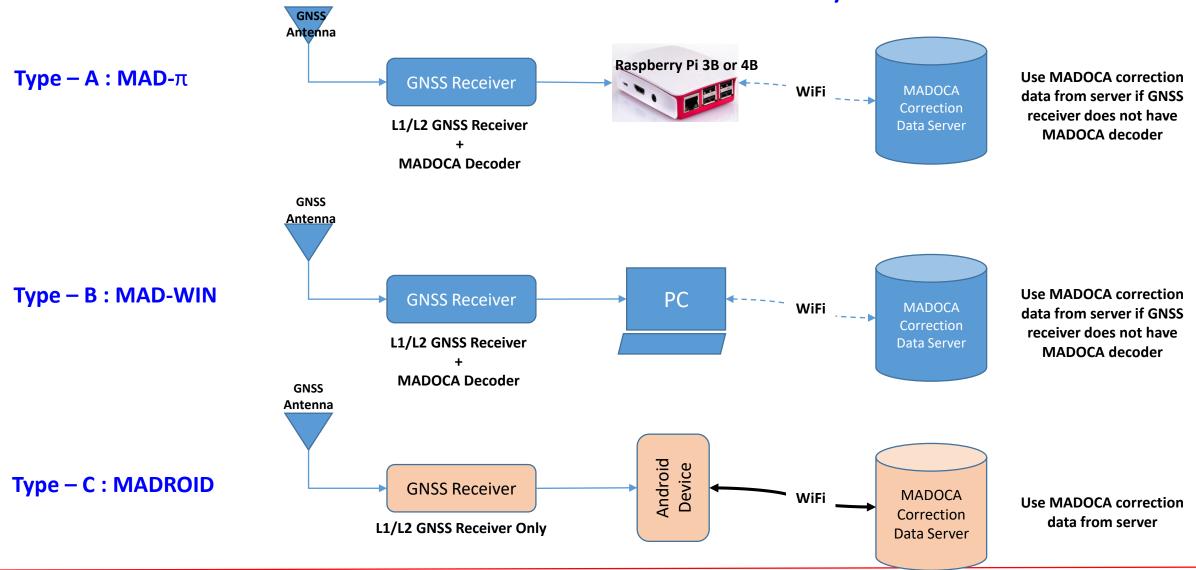


Low-Cost MADOCA PPP Receiver Systems

 Platform / OS : RaspberryPi Receiver : Dual Frequency Receiver Data Format : UBX, SBF or RTCM 3 Correction Data : UBX, RTCM3 or JAXA online Platform / OS : Windows Platform / OS : Android Device Receiver : Dual Frequency Receiver Data Format : UBX, SBF or RTCM 3 Correction Data : UBX, RTCM3 or JAXA online Platform / OS : Android Device Platform / OS : Android Device Receiver : Dual Frequency Receiver Data Format : UBX, SBF or RTCM 3 Correction Data : UBX, RTCM3 or JAXA online Platform / OS : Android Device Receiver : Dual Frequency Receiver Data Format : UBX, SBF or RTCM 3 Correction Data : UBX, RTCM3 or JAXA online 	Type A: MAD-π	Type B: MAD-WIN	Type C: MADROID
	RaspberryPi • Receiver : Dual Frequency Receiver • Data Format : UBX, SBF or RTCM 3 • Correction Data :	Windows Receiver : Dual Frequency Receiver Data Format : UBX, SBF or RTCM 3 Correction Data : 	Android Device • Receiver : Dual Frequency Receiver • Data Format : UBX or RTCM 3 • Correction Data :



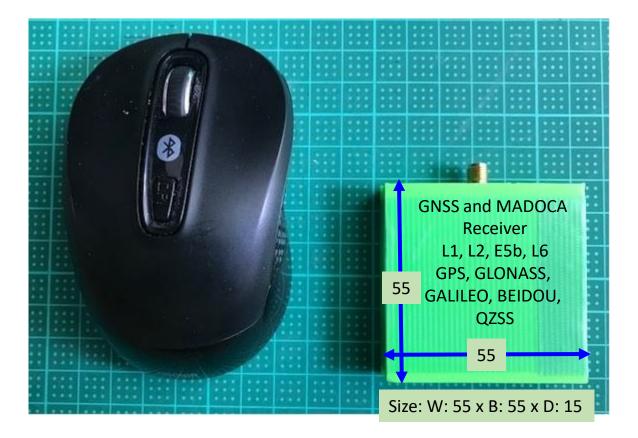
MADOCA Low-Cost Receiver Systems

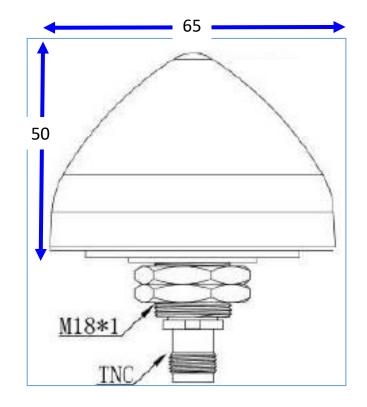






GNSS MADOCA Receiver and Antenna

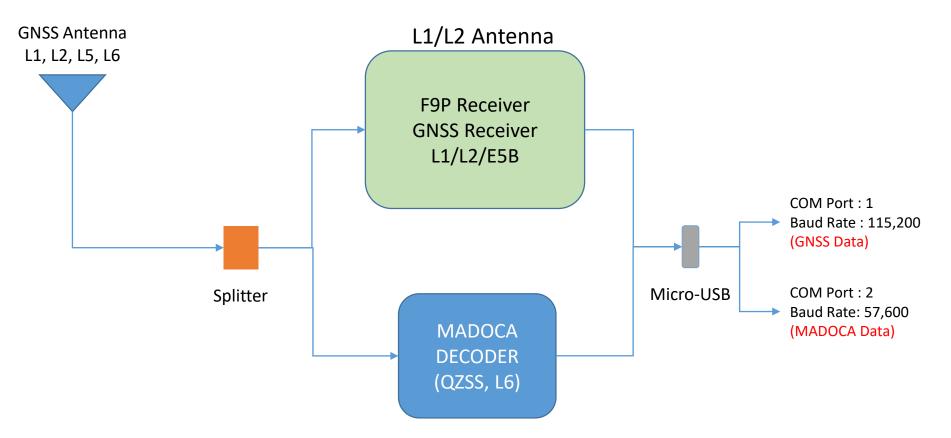








Receiver System Architecture







GNSS Raw Data, F9P Receiver Output

UBX - RXM (Receiver Manager) - RAWX (Multi-GNSS Raw Measurement Data) 471 :										UBX - F	RXM (Red	eiver l	Manager) - RAWX (M	ulti-GNSS Raw Meas	urement Da	ta)					1	119 s
Local Time	Local Time 2108:364155.001000000 [s]										ime [210	8:364155.001000000	[s]								
Leap seconds 18 (VALID) [s] Clock reset 🗖										Leap s	econds 🗌		18 (VALID] [s] Clock reset								
SV Sign.	G	Pseudo Range [m] C	Carrier Phase Ic	Dopple	Lock T	SNR F	PB Std	CP Std	D0 St P C H 🔨	SV	Sign	G	Pseudo Range [m]	Carrier Phase [c	Dopple	Lock T	SNR	PR Std	CP Std	D0 St P	C H	
G03 L1C//		21647431.89	113758026.20	1766.7	64500	47	0.08	0.004	0.064 • Y • Y • Y	R24		2	20561599.24	109952111.10	-571.8	0	24	5.12		2.048 • Y		_
G07 L1C//		24915724.27	130933010.83	-3266.5	64500	40	0.00	0.004	0.256 • Y • Y • Y	G11		-	21725325.52	114167355.90	-2393.9	ŏ	19	10.24		8.192 • Y		
G08 L1C//		23275226.57	122312137.25	-2627.7	64500	48	0.08	0.000	0.064	E09			25953366.03	136385811.26	2082.8	31320	31	0.64	0.020	0.512 • Y		
G22 L1C//		21510039.63	113036022.46	-299.5	64500	40 51	0.08	0.004		B07			36355217.75	146387393.88	-723.3	64500	46	0.08	0.004	0.128 • Y		
G30 L1C//		24278609.23	127584953.13	-2644.0	64500	39	0.32	0.012	0.512 • Y • Y • Y	B13			39143656.89	157615286.40	3.7	64500	41	0.08	0.008	0.256 • Y	• Y • Y	
Q01 L1C//		37653530.29	197870641.68	-73.0	64500	45	0.08	0.004	$0.064 \bullet Y \bullet Y \bullet Y$	B08	B2D1		37559865.78	151238004.56	-230.1	64500	36	0.32	0.012	0.512 😐 Y	• Y • Y	· · · · ·
B13 B1D1		39143654.13	203831280.88	4.6	64500	44	0.08	0.004	0.128 • Y • Y • Y	B14	B2D1		23562274.77	94875513.57	575.2	64500	47	0.08	0.004	0.128 🔍 Y	• Y • Y	
B23 B1D1		25258313.11	131526650.97	-3329.3	64500	45	0.08	0.004	0.128 • Y • Y • Y	E09	E5BQ		25953376.32	104503489.05	1595.4	7200	30	0.32	0.023	0.512 • Y	• Y • Y	
B33 B1D1		24290016.20	126484489.71	1997.9	64500	44	0.08	0.004	0.128 • Y • Y • Y	E25	E5BQ		25156838.06	101296166.80	-2103.6	64500	46	0.08	0.004	0.064 😐 Y	• Y • Y	
B07 B1D1		36355222.61	189311179.89	-935.5	64500	40	0.16	0.008	0.256 • Y • Y • Y	E04			27608614.87	111168447.66	603.2	64500	38	0.08	0.008	0.256 🔍 Y	• Y • Y	
B14 B1D1		23562278.42	122694967.85	744.2	64500	46	0.08	0.004	0.128 • Y • Y • Y	E24			27082389.38	109049567.15	-2761.8	64500	29	0.32	0.020	0.256 🔍 Y		
B08 B1D1		37559872.35	195584111.77	-297.2	64500	36	0.32	0.012	0.256 • Y • Y • Y	G03			21647433.43	88642630.21	1376.6	64500	42	0.16	0.008	0.128 🔍 Y		
R14 L10F		20799394.57	110872489.66	-1915.9	64500	41	1.28	0.008	0.128 • Y • Y • Y	G07		•	24915724.70	102025717.75	-2545.6	64500	31	0.64	0.027	1.024 🔍 Y		
R07 L10F	5	24916190.47	133378314.32	-3400.1	4880	31	2.56	0.023	0.512 • Y • Y • Y	G08		•	23275228.17	95308161.74	-2047.7	64500	43	0.08	0.004	0.128 🔍 Y		
R08 L10F	6	22339471.45	119626854.33	-756.2	0	22	10.24		8.192 • Y • N • N	G30		•	24278610.59	99416856.48	-2060.6	64500	39	0.32	0.008	0.256 🔍 Y		
R13 L10F	-2	22903427.46	122303024.15	-4716.8	64500	38	1.28	0.008	0.256 ● Y ● Y ● Y	Q01		•	37653530.82	154184923.80	-56.7	64500	39	0.32	0.008	0.256 🔍 Y		
R15 L10F		22497781.39	120221322.41	1857.6	900	30	1.28	0.027	1.024 • Y • Y • N	R13		-2	22903428.93	95124586.38	-3668.6	64500	33	1.28	0.020	0.512 🔍 Y		
R23 L10F		21577264.34	115423832.34	-2281.8	64500	39	1.28	0.008	0.256 ● Y ● Y ● Y	R14		-7	20799400.97	86234179.82	-1489.7	64500	30	1.28	0.027	1.024 🔍 Y		
Q02_L1C//	Α-	37387370.90	196471961.13	-586.0	64500	44	0.08	0.004	0.128 • Y • Y • Y	R07		5	24916072.27	103738199.24	-2645.2	0	24	5.12		2.048 🔍 Y		
E25 E1C		25156832.92	132200035.35	-2745.3	64500	47	0.16	0.004	0.064 ● Y ● Y ● Y	R08		6	22339431.21	93042941.92	-588.8	0	24	10.24		8.192 • Y		
Q07_L1C//	Α-	37723026.81	198235850.73	-456.2	64500	42	0.08	0.008	0.128 • Y • Y • Y	Q07		•	37723023.32	154469487.54	-355.4	64500	40	0.32	0.008	0.256 • Y		
E04 E1C	-	27608611.14	145084222.79	787.6	64500	40	0.32	0.008	0.128 • Y • Y • Y	Q02	L2CL	•	37387371.70	153095048.86	-456.7	64500	45	0.16	0.004	0.128 • Y	• Y • Y	
G32 L1C//	Α-	26205245.91	137709496.61	23.5	0	19	10.24	-	8.192 • Y • N • N													
E24 E1C	-	27082376.41	142318876.30	-3603.2	64500	30	1.28	0.023	0.512 • Y • Y • Y													1
B34 B1D1	I -	27305668.25	142187779.36	-2696.7	64500	40	0.16	0.008	0.256 • Y • Y • Y													
R17 L10F	: 4	22576755.59	120812779.20	1583.3	0	24	5.12	-	2.048 • Y • N • N													1
R24 L10F	2	20561599.24	109952111.10	-571.8	0	24	5.12		2.048 • Y • N • N													





GNSS Navigation Data Bits, F9P Receiver Output

UBX - RXM (Receiver Manager) - SFRBX (Subframe Data NG)

13 s

## denotes data receiv	ed on subChn	Strip Parity Bits	
SV	MSG	DATA (* denotes invalid words)	~
BDS 781D1 0	1	38901595 02980070 05E0B162 2289108A 06070A96 3D450F44 1DD669E1 18007A25 14EABF2E 2F05E156	
BDS 782D10	??	38901595 02980070 05E0B162 2289108A 06070A96 3D450F44 1DD669E1 18007A25 14EABF2E 2F05E156	
BDS 881D1 0	1	38901595 02980070 05E0B162 2286EFB5 36070AD6 3D450F44 1DD669E1 18006C2A 3C41FFEB 33B34166	
BDS 882D1 0	??	38901595 02980070 05E0B162 2286EFB5 36070AD6 3D450F44 1DD669E1 18006C2A 3C41FFEB 33B34166	
BDS 10B2D1 0	??	38901595 02980070 05E0B162 2283E0B1 1A070A56 3D450F44 1DD669E1 18006E2C 0C7CE03A 05A1C1D5	
BDS 11 B1D1 0	1	38901595 02981075 05E0B162 228280B3 0B070A26 3D450F44 1DD669E1 18006522 16DCFFFD 32BEA2F6	
BDS 11 B2D1 0	??	38901595 02981075 05E0B162 228280B3 0B070A26 3D450F44 1DD669E1 18006522 16DCFFFD 32BEA2F6	
BDS 13B1D1 0	1	38901595 02980070 05E0B162 22BA002D 18070A26 3D450F44 1DD669E1 18001E24 3B5500B6 0B14E149	
BDS 13B2D1 0	??	38901595 02980070 05E0B162 22BA002D 18070A26 3D450F44 1DD669E1 18001E24 3B5500B6 0B14E149	
BDS 14B1D1 0	1	38901595 0298607D 05E0B162 2283C0BB 09070C5C 3D04D0F5 0D8679E4 181E207E 00CDA0D2 1A4E47DA	
BDS 14B2D1 0	??	38901595 0298607D 05E0B162 2283C0BB 09070C5C 3D04D0F5 0D8679E4 181E207E 00CDA0D2 1A4E47DA	
BDS 23B1D1 0	1	38901595 02981075 05E0B162 228FD382 3D070AF6 3D450F44 1DD669E1 1800472E 27AF000B 0443615C	
BDS 33B1D1 0	1	38901595 02981075 05E0B162 22A57976 17070AE6 3D450F44 1DD669E1 18004A2A 0D37001B 04A26173	
BDS 34B1D1 0	2	38902597 00D09C8C 33ECCB8E 05C8F99E 232801B3 0A4DBB09 031AB08C 3C98F45A 10AA517C 141A296F	
GAL 2 E1B 0	EO	00955555 55555555 55555555 50F14000 A415C000 0000002A AAAA5BDA E9FF4000	
GAL 4 E1B O	EO	00955555 55555555 55555555 50F14000 A42E4000 0000002A AAAA6D4B BEFF4000	
GAL 4 E5BL 0	??	0217B097 823989B5 6CE3F207 B3830000 BC014000 0000002A AAAABF45 DC7F4000	
GAL 9 E1B O	EO	00955555 55555555 55555555 50F14000 A42E4000 0000002A AAAA6D4B BEFF4000	
GAL 9E5BLO	??	051CFFC4 05E07FBF E00878B2 118A8000 AAAA8000 0000002A AAAAAEDE 737F4000	
GAL 11 E1B O	E3	03177FF1 C8C61EBA FC868642 A1798000 955AC000 0000002A AAAA795D FC3F4000	
GAL 11 E5BL 0	??	00955555 55555555 55555555 50F14000 A4160000 00000015 5555608A B07F4000	
GAL 24 E1B 0	E7	07E25E4C 00E05304 3BCFE129 7F070000 ABD54000 0000002A AAAA4C78 9FFF4000	
GAL 24 E5BL 0	??	00955555 55555555 55555555 50F14000 A3F10000 0000002A AAAAB461 6CBF4000	
GAL 25 E1B 0	EO	00955555 55555555 55555555 50F14000 A42E4000 0000002A AAAA6D4B BEFF4000	
GAL 25 E5BL 0	??	021785E9 82624A02 2B8CABA1 EDA20000 82C74000 0000002A AAAA9472 F2BF4000	
GAL 30 E1B 0	EO	00955555 55555555 55555555 50F14000 A3D3C000 0000002A AAAA7FF5 6EFF4000	
GLO 1L10F1	2 3/2504	10A10006 74AC20D0 78711800	
GLO 2L10F-4	2 3/2504	10A10022 91CC07E5 65214000	





GNSS Navigation Data Bits, F9P Receiver Output

UBX - RXM (Receiver	Manager) - SFRBX (S	ubframe Data NG)	71
## denotes data rece	ived on subChn	Strip Parity Bits	
SV	MSG	DATA (* denotes invalid words)	^
GLO 2L10F-4	2 3/2504	10A10022 91CC07E5 65214000	
GLO 2 L20F -4	2 3/2504	10A10022 91CC07E5 65214000	
GLO 7L1OF 5	6 5/2501	35A842C3 4440F5BC 0EED 4800	
GLO 7L2OF 5	10 1/2501	551C096A 6F50889C 3E27D 800	
GLO 8L1OF6	2 3/2504	10A1040B 2CE0277F 380D 2000	
GLO 8L2OF 6	1 3/2504	08212942 7FF8AF7F 223CA800	
GLO 13L10F-2	2 3/2504	10A10486 0400930A 8830F800	
GLO 13L20F-2	2 3/2504	10A10486 0400930A 8830F800	
GLO 14 L10F -7	2 3/2504	10A10093 CE099683 2074A800	
GL0 14 L20F -7	2 3/2504	10A10093 CE099683 2074A800	
GLO 15L10F 0	2 3/2504	10A10152 2E914D06 669C7000	
GLO 15L2OF 0	14 3/2503	757C390F B86090C4 16F93000	
GLO 17 L10F 4	2 3/2504	10A104E4 A2A19390 B3843000	
GLO 17 L20F 4	5 2/2504	289B0000 00001C00 0266D000	
GLO 23L10F 3	2 3/2504	10A10524 BE8864C2 D88C7000	
GLO 23L20F 3	11 1/2500	5EA47CC2 5F74C01A 1A57B000	
GLO 24 L10F 2	1 3/2504	08212CD7 68C06759 09094800	
GPS 3L1C/A 0	3	22C03C33 1DAE8BB3 000228A7 1FB3BA61 800149FD 960AD940 07C6477A 8118C462 BFE9CB02 8846D75B	
GPS 3L2CM 0	45 ??	8B0CB76B A260D13F 7E0C89D6 09F9800F B1B62001 0001E003 2CC01FAD C01C9800 2D9A0EDC 3EA8B0DE	
GPS 7L1C/A 0	3	22C03C33 1DAE8BB3 3FFDBE0D 9183B133 001B49A8 3675A4E1 84A227A7 20971BBB 3FE9BFEB 15BC0E58	
GPS 7L2CM 0	45 ??	8B1CB76B A2617C23 1ABB89B6 75FF9FFE 6F15C014 A002A007 E2E01388 00307500 72D8AEC9 EBC8B1DE	
GPS 8L1C/A 0	3	22C03C33 1DAE88B3 0000132F 21E748D7 000849DB 1FCE65D1 8AA27F7C 11A57C92 BFE93AA9 827C5AE3	
GPS 8L2CM 0	45 ??	8B20B76B A2612643 E28C49DF CED97FCE 0F18A006 4002BFF2 ADC02B04 400941FF 45D451F5 7A18B21E	
GPS 11 L1C/A 0	4/57/1	22C03C33 1DA72CE7 1E46BC59 8976A283 1AD5A5FA ADE00DCB 2529F154 0B0C412F 00DC3CB9 8150FBC7	
GPS 14 L1C/A 0	2	22C03C33 1DA96AE7 06BEDCD9 8D4B5D04 14D45B4F 3F000179 B8393A99 8407686C 034AD445 96699F8B	
GPS 17 L1C/A 0	3	22C03C33 1DACABFB 000F93CC 1FD0BA3B 3FF70A26 852DBA93 0A1B2F58 04D8B2F2 BFEAB01F 0C7CBD97	
GPS 22L1C/A 0	3	22C03C33 1DAE88B3 001127AF 3D911B6C 3FFA095F 3B03EA06 87083477 1D4CD7C4 3FE922F8 0806C397	
GPS 27 L1C/A 0	1	22C03C33 1DAD094F 03C40037 095100B9 9C3CAE5E B8B6246E 90488135 85966957 003FEA16 B5CB19BC	





106 s

GNSS Navigation Data Bits, F9P Receiver Output

UBX - RXM (Receiver Manager) - SFRBX (Subframe Data NG)

SV	MSG	DATA (* denotes invalid words)	~
GLO 17L1OF 4	2 3/2504	10A104E4 A2A19390 B3843000	
GLO 17 L2OF 4	5 2/2504	289B0000 00001 C00 0266D 000	
GLO 23L1OF 3	2 3/2504	10A10524 BE8864C2 D88C7000	
GLO 23L2OF 3	11 1/2500	5EA47CC2 5F74C01A 1A57B000	
GLO 24 L10F 2	1 3/2504	08212CD7 68C06759 09094800	
GPS 3L1C/A 0	3	22C03C33 1DAE8BB3 000228A7 1FB3BA61 800149FD 960AD940 07C6477A 8118C462 BFE9CB02 8846D75B	
GPS 3L2CM 0	45 ??	8B0CB76B A260D13F 7E0C89D6 09F9800F B1B62001 0001E003 2CC01FAD C01C9800 2D9A0EDC 3EA8B0DE	
GPS 7L1C/A 0	3	22C03C33 1DAE8BB3 3FFDBE0D 9183B133 001B49A8 3675A4E1 84A227A7 20971BBB 3FE9BFEB 15BC0E58	
GPS 7 L2CM 0	45 ??	8B1CB76B A2617C23 1ABB89B6 75FF9FFE 6F15C014 A002A007 E2E01388 00307500 72D8AEC9 EBC8B1DE	
GPS 8L1C/A 0	3	22C03C33 1DAE8BB3 0000132F 21E748D7 000849DB 1FCE65D1 8AA27F7C 11A57C92 BFE93AA9 827C5AE3	
PS 8L2CM 0	45 ??	8B20B76B A2612643 E28C49DF CED97FCE 0F18A006 4002BFF2 ADC02B04 400941FF 45D451F5 7A18B21E	
PS 11 L1C/A 0	4/57/1	22C03C33 1DA72CE7 1E46BC59 8976A283 1AD5A5FA ADE00DCB 2529F154 0B0C412F 00DC3CB9 8150FBC7	
GPS 14 L1C/A 0	2	22C03C33 1DA96AE7 06BEDCD9 8D4B5D04 14D45B4F 3F000179 B8393A99 8407686C 034AD445 96699F8B	
GPS 17 L1C/A 0	3	22C03C33 1DACABFB 000F93CC 1FD0BA3B 3FF70A26 852DBA93 0A1B2F58 04D8B2F2 BFEAB01F 0C7CBD97	
PS 22 L1C/A 0	3	22C03C33 1DAE8BB3 001127AF 3D911B6C 3FFA095F 3B03EA06 87083477 1D4CD7C4 3FE922F8 0806C397	
PS 27 L1C/A 0	1	22C03C33 1DAD094F 03C40037 095100B9 9C3CAE5E 8886246E 90488135 85966957 003FEA16 85C819BC	
GPS 30L1C/A 0	3	22C03C33 1DAE8BB3 00043E5C 0C51D14C 0003C9A5 902E535C 044EA2FC 210F9F12 BFE9C6CA 8F3C845B	
PS 30 L2CM 0	45 ??	8B78B76B A2617C98 B7334990 2EC4A015 8F1EE005 A0072007 DCC0126C 802FD500 6D9E0B57 AA78B79E	
iPS 32 L1C/A 0	1	22C03C33 1DAD094F 03C40037 095100B9 9C3CAE5E B8B6246E 9048806D 89966986 80000FF7 099E73F0	
iPS_32L2CM_0	45 ??	8B80B76A 2261666E 242549BD E8917FFA BE593FEF 60071FFB 68A01D6A E01E99FF C094FB52 9148B81E	
ZSS 1L1C/A 0	3	22C0AA24 1DAE835C 013F2D52 8F43A1DC 3EFE477D A38B4E4D 8884B03B 1F97CD75 BFFAF44D AD458C97	
ZSS 1L2CM 0	??	8B04B76B A2645A9E 8F1B8763 81E965F7 30741FD1 BFEA200F EC0022A0 5FED0500 7088081D E568B05F	
ZSS 2L1C/A 0	3	22C0AA81 9DAE8383 0034848A 91413ED8 00A98799 A75FE251 8214EFF4 1F3CE46E BFFA75FC 2D413300	
ZSS 2L2CM 0	??	8B08B76B A2640922 7E75C7A7 5CC5A780 50C9A039 1FE0E051 814015D2 A009FA03 1B680231 1B98B09F	
ZSS 3L1C/A 0	1	22C0AA81 9DADA1E3 03C840C6 A0000003 00000000 00000000 00000053 2D56698E 803FFF2A BFE0F804	
ZSS 3L2CM 0	??	8B0CA76B 11078264 62640472 E3202A5D A10C1FFC 6C68CFEB FCF931B1 63C702C6 5CEB04CD 1958B0CB	
ZSS 7L1C/A 0	3	22C0AA81 9DAE8383 01F52A2B 28751B08 00F8801D 82F38171 90DAF61A 8A9167D5 800335EF 2D400037	
ZSS 7L2CM 0	??	8B1CB76B A2645450 EA35C002 F3814CC5 900000F8 81F4E053 6340436B 5FB4EE02 D8F00DFE EF08B1DF	





Satellite System & Signal Settings

F9P Receiver

MADOCA Decoder

UBX - (UBX - CFG (Config) - GNSS (GNSS Config)													
	Channels													
ID	GNSS	Configure	Enable	min	max	Signals								
0	GPS	V	✓	8	16	🔽 L1C/A								
1	SBAS			0	0	🗖 L1C/A								
2	Galileo		\checkmark	10	18	🔽 E1								
3	BeiDou	\checkmark	\checkmark	4	5	✓ B1								
4	IMES			0	0	🗖 L1C/A								
5	QZSS	\checkmark		0	4	🔽 L1C/A 🔲 L1S								
6	GLONASS	V	\checkmark	8	12	🔽 L10F								
7	IRNSS													
Number of channels available 60														
Number of channels to use 60 🗖 Auto set														

UBX - C	UBX - CFG (Config) - GNSS (GNSS Config)											
				Channe	els							
ID	GNSS	Configure	Enable	min	max	Signals						
0	GPS			0	0	🗖 L1C/A						
1	SBAS			0	0	🗖 L1C/A						
2	Galileo			0	0	🗖 E1						
3	BeiDou			0	0	🗖 B1						
4	IMES			0	0	🗖 L1C/A						
5	QZSS	$\overline{\mathbf{v}}$		0	54	🗖 L1C/A 🔲 L1S						
6	GLONASS			0	0	🗖 L10F						
7	IRNSS											
Number of channels available 60												
Number	of channels	to use		60	🗌 Aut	o set						





Satellite System and Signal Settings

F9P Receiver

MADOCA Decoder

Basic			Advanced —					Basic			Advanced				
ID	System	Enable	Signals Co	ntrol				ID	System	Enable	Signals Co	ntrol			
0	GPS	$\overline{\mathbf{v}}$	☑ L1C/A	🗖 L1C	☑ L2C	🗖 L5		0	GPS	•	🗖 L1C/A	🗖 L1C	🗖 L2C	🗖 L5	
1	SBAS		🗖 L1C/A					1	SBAS		🗖 L1C/A				
2	Galileo	V	✓ E1	🗖 E5a	🔽 E5b	🗖 E6		2	Galileo		🗖 E1	🔲 E5a	🔲 ЕБЬ	🗖 E6	
3	BeiDou	v	▼ B1	🗖 B1C	✓ B2	🗖 B2a		3	BeiDou		🗖 В1	🗖 B1C	🗖 В2	🔲 B2a	
		_						4	IMES		D 11				
4	IMES		🗖 L1					5	QZSS	$\overline{\mathbf{v}}$	L1C/A	🗖 L1C	🗖 L1S	✓ L2C	
5	QZSS		☑ L1C/A	🗖 L1C	🗖 L1S	✓ L2C	🗖 LS	6	GLONASS			🗖 L10C	F 12	🗖 L3	
6	GLONASS	$\overline{\mathbf{v}}$	✓ L1	🗖 L10C	✓ L2	🗖 L3		1				L LIUC	L L2		
_		_						7	IRNSS	1	L LO				
7	IRNSS		🗖 L5					Show	Hex						





MADOCA Correction Data Output Received Directly from QZSS L6E Channel

[14:27:58.559]	0000 0010 0020 0030 0040 0050 0060 0070 0080 0090 0080 0080 0080 0060 0060 006	64 B8 1 FF FF A CC FF F 01 D5 F 5F FF 4 7C D1 E FF 0C 8 9E 20 0 64 B4 7 64 A8 4 00 00 0 00 00 0	0 00 1 6 C0 0 9 60 4 F F9 6 1 FF F 0 1C 2 4 FF 1 7 83 F 6 80 0 8 00 0 0 00 0 3 13 8	A CF 00 00 0F 7F A8 DF FF 4 01 27 FF 8 FF 28 FF 28 FF 29 00 00 000000	FC 1D 20 C4 FF 79 80 03 96 FF FF 93 40 00 DC C0 FF 30 9F FF 41 84 00 00 00 00 00 00 F2 1B	D1 40 12 13 FB FF 4C 01 80 8C 9A 00 00 00 CC	21 AC 09 C6 7F F8 86 BF 5E B1 5D 90 00 1E E7 FF 04 DF FF D4 49 C4 00 00 00 00 00 00 AD 1F	97 FF 98 F5 80 2A 22 9E FF 60 9E 00 00 00 00 77	12 OF D8 97 00 6D BF 00 35 CF FF D4 62 00 4D 9C 36 01 00 1C 8D 04 00 00 00 00 00 23 8C 1D	10 89 FF DC D8 04 43 71 FF E9 E8 00 F3 4F 01 B3 47 FE F6 99 22 44 00 00 82 20 34 59	<pre>. e ïü. Ñ!¬ d . A Ä@. ÆÿØ. ÿÜ ÿÿ® ÿy. ømØ. ĵÿù ¨B¿õ¿. Cq . Ŏÿùoÿ. ÿû^±. 5ïÿå _ÿAÿô. ÿ.ÿ]. *ÿôè. [Nì.ÿí@.L "b. óo ÿ 'ÿÜA. çÿ.M³ ÿØ¿ÿOBÿ6.Gp ÿÆ.ÿ.ÿôö. d´vAIÄ"J d¨H</pre>
[14:27:59.510]	0000 0010 0020 0030 0040 0050 0060 0070 0080 0090 0080 0080 0060 0060 0060 006	36 00 0	0 00 1 5 60 0 E F8 8 9 9F F 4 61 A D FF 3 0 C3 8 F FB E 0 59 1 B 91 E 1 FB 8 7 AF F 3 FF 0 0 00 0 A C8 F	A CF 00 00 31 1F 51 CF 33 FF 36 7B 30 2A 31 90 4F C7 66 CF 35 9A 56 88 30 00 52 6C	FC 1D D8 5F F9 07 1A 00 22 A2 1F F0 75 BB B0 EE 4C E4 C8 D0 5F B2 E6 3E 00 00 00 00 D7 B9	CC F2 93 DA 7F 88 FF 04 F8 5B AB C2 00 00 49	21 AC C3 87 FF 7D D9 C0 F4 6D B2 00 F1 4B 2A 00 BC 98 F7 EA CF F0 BE 13 00 00 00 00 5E 21	97 FF 29 12 A8 9E C0 00 BF F3 26 8D 00 00 00 02	22 OF B0 08 40 07 21 9F 00 B8 63 5F 08 F3 67 4D BF 3F 3A 7E 64 B9 00 00 00 00 65 D8	10 99 BF FC 25 90 FF A0 62 A0 FD D0 3F FF F9 08 1F EC 3A 7F 71 71 05 40 00 00 A1 53 86 FE	<pre>ïü.1!¬." d'.`ø_òÄ.ÿ°.¿ýbøùÿ})@.%Bé.ñïúÙÀ.!.ÿ¦ Eafÿ"⊄.ôm".b/-ÿ?{.ð.²c_ýÜ 6A.*u»ÿñKA.ó?ÿ 01.û±.°î.*ù¿OY.ÇLäø¼.¿gM.í ÿT{.ÖÎÈĐ[÷êó¿?:. à\$.û²«ïð&:~qq@÷û.æ>¾d'.@#ÿÆ;S .æ°Èòlx'I^!.eØ.þ </pre>

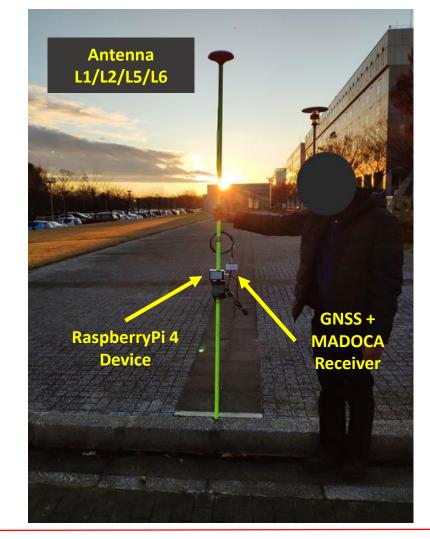




Type A: MAD-PI

MADOCA PPP based on RaspberryPi / Dual Frequency Receiver + MADOCA Decoder









Type B: MAD-WIN

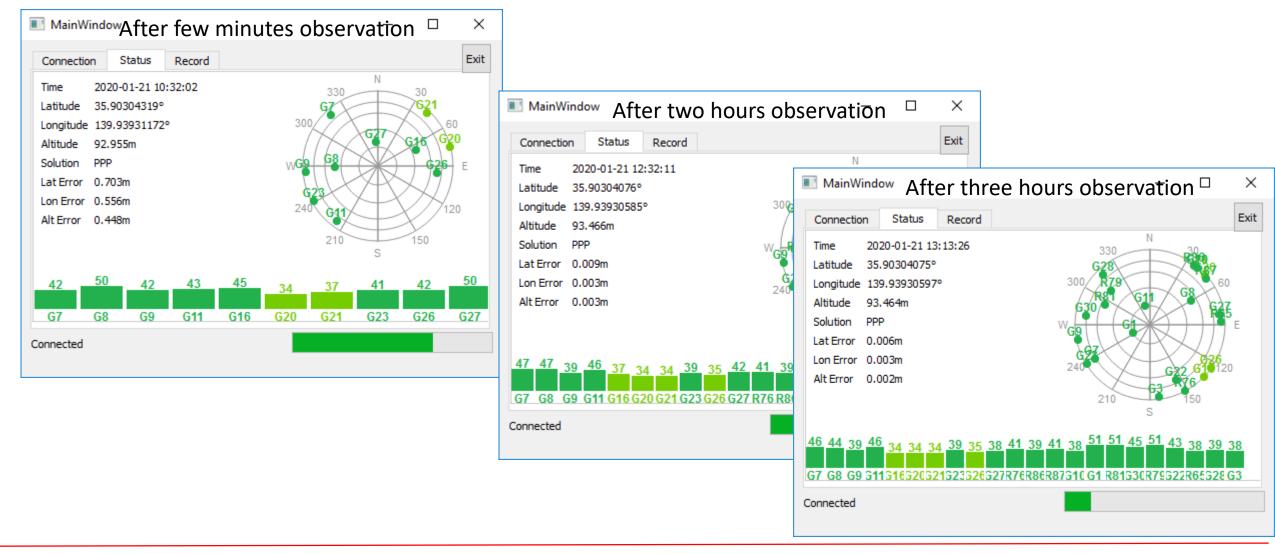
MainWindow		_		×
Connection Statu	us Record		1	Exit
Rover RX Correction	() Online	Setup		
DX Processing Mode	Online (MADOCA)	Setup		
PPP-Static	O PPP-Kinema	atic		
	Start/Stop			
Connected				

The position accuracy improves to cm (10 - 30 cm) level after initialization time of about 15min.



Type B: MAD-WIN

Receiver: Online receiver access in Kashiwa / Correction Data: MADOCA Receiver in Bali



Center for Spatial Information Science



Type C: MADROID / MADOCA PPP based on Android Dual Frequency Receiver + Online MADOCA Data

START ROVER			START ROVER		START ROVER		
2101 Mount Point			2101 Meaner Dealer		2101		
Port			Port		Port		
NTRIP Settings Address madoca.ntrip-mgm.net			NTRIP Settings Address madoca.ntrip-mgm.net		NTRIP Settings Address madoca.ntrip-mgm.net		
Antenna Height (m) 0.0			Antenna Height (m) 0.0	¢	Antenna Height (m) 0.0		
Elevation Mask 10 ~ Antenna Model TWIVP6000			Elevation Mask 10 Antenna Model TWIVP6000	·	Elevation Mask PPP-Kinematic Antenna Model PPP-Static		
Processin Rover Mode	ng Settings PPP-Static	÷	Processin sbf Rover Mode rtcm3		Processing Settings Rover Mode Single	-	
Format	ubx *		Format ubx	-	Format ubx	*	
Device	Bluetooth	Φ	Device	- 0	Device	- 0	
Connection	USB	*	Connection USB	-	Connection USB	-	



is Center for Spatial Information Science The University of Tokyo Type C: MADROID / MADOCA PPP based on Android Dual Frequency Receiver + Online MADOCA Data

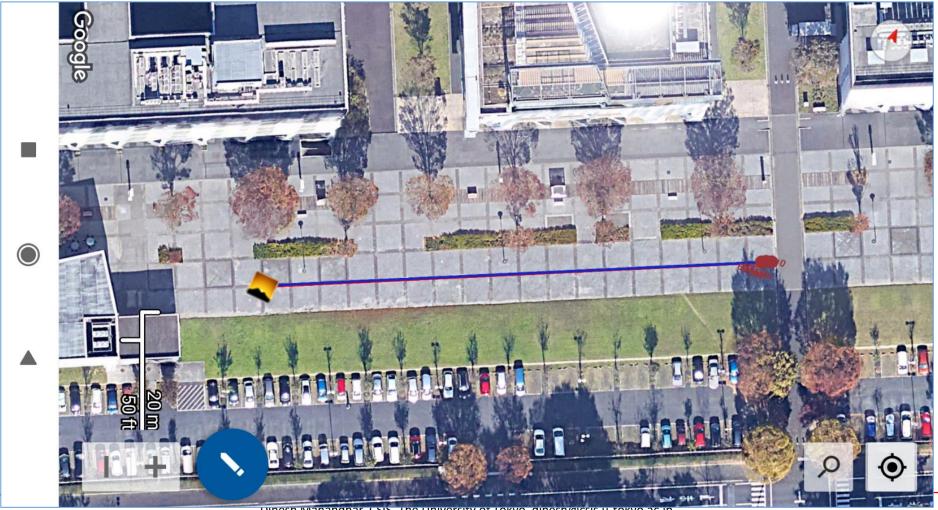
MADROID MADO	*	Latitude: 35.90202657" N Longitude: 139.93857286" E Ellipsoidal Height: 59.349m		Date: Dec 25, 2019		
evice u-blox GNSS receiver	- 0	Orthometric Height: 21.385m Speed: 0.15 km/hr Fix type: PPP Satellites in view: 13		Time: 05:34:17 Latitude: 35.902023 Longitude: 139.9385		
ormat ubx	*	Satellites in use: 13 PDOP: 3.4 HDOP: 1.8 MDOP: 3.0		X: 54N 404216.762n Y: 54N 3973601.765 Ellipsoidal Height: 55	im N	
rocessing Settings		330° N	30"	Orthometric Height: Fix Type: PPP		
tover Mode PPP-Static	*		an ar	Speed: 0.11 km/hr HDOP: 1.9 VDOP: 3.0		
levation Mask 10	-	w W	75° 60° 45° 30° E	PDOP: 3.5		
Antenna Model TWIVP6000				Satellites in View: 13 Satellites in Use: 13 Latitude Error: 0.191		
NTRIP Settings Iddress madoca.ntrip-mgm.net		240	Str.	Longitude Error: 0.1 Altitude Error: 0.104		
Port 2101						
Mount Point MDC0				NMEA: 2019_12_25 UBX: 2019_12_25_1		
START ROVER					STOP RECORDIN	G
Setup Status	skyplot	Setuo Status	Skyplot	¢ Setup	Status	Skyplot
oratory status	any prot	Status	owyprot	serup	510105	owkhing

Dinesh Manandhar, CSIS, The University of Tokyo, dinesh@csis.u-tokyo.ac.jp





We walked straight along the concrete tiles (30cmx30cm) and PPP results showed perfect straight line. Accuracy is about 15cm. Receiver : F9 + Online MADOCA Correction Data



Dinesn Manananar, CSIS, The University of Tokyo, dinesn@csis.u-tokyo.ac.jp



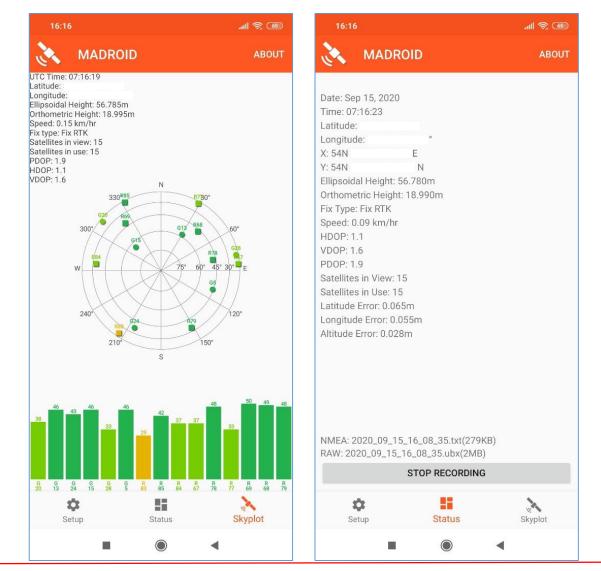


MADROID PPP-AR with Local Correction Data

Test Area GNSS Receiver Used MADOCA Correction Data

Local Correction Data

: Tokyo
: u-blox F9P
: u-blox D9
(Received online via NTRIP Server)
: Service provided by GPAS
(Received online via NTRIP Server)







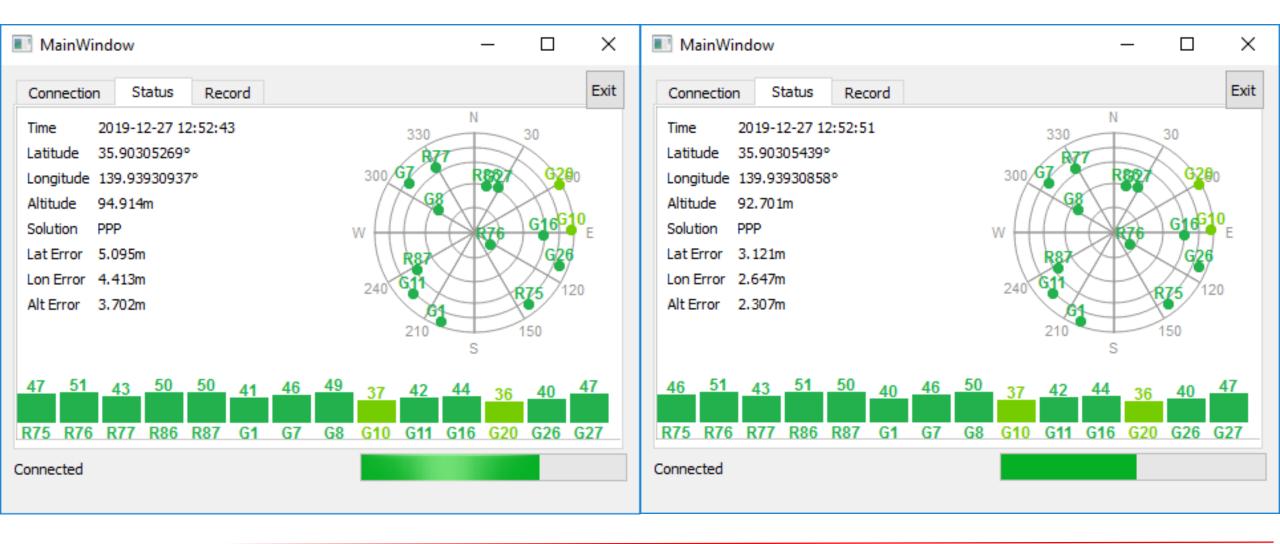
Output from MADOCA PPP Device: RaspberryPi



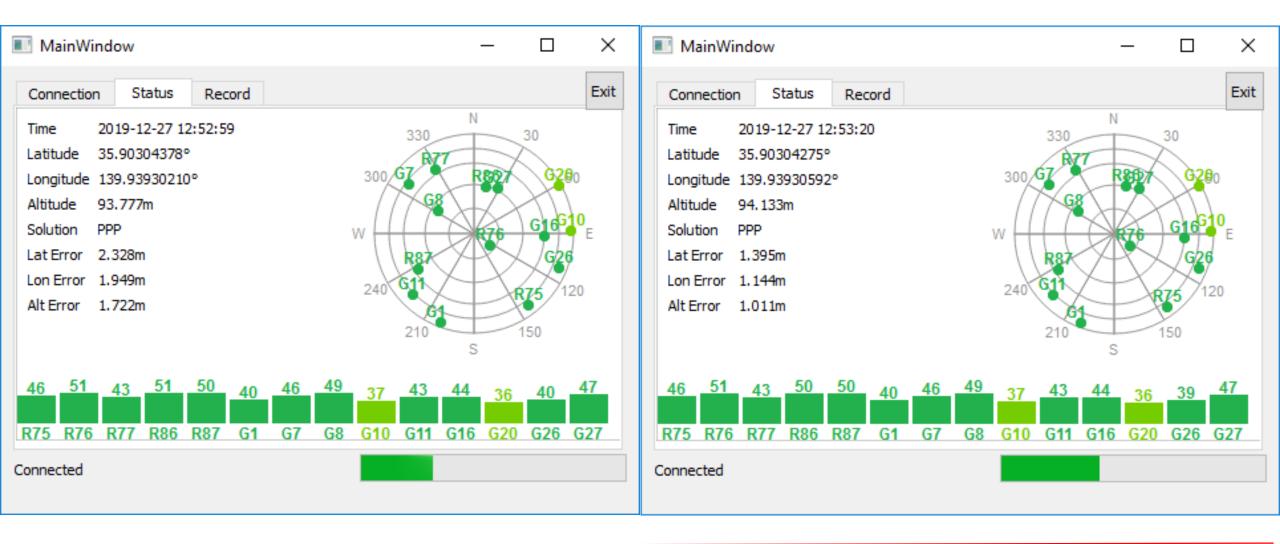
MADOCA PPP Observation

MainWindow	_		MainWindow —	o ×
Connection Status Record		Exit	Connection Status Record	Exit
Rover			Device OS	\sim
O RX Online	Setup		Solution 2019-12-27_125516.nmea(482304) Rover 2019-12-27_125516.ubx(3896320)	
Correction			Correction 2019-12-27_125516.rtcm3(1553408)	
O DX Online (MADOCA)	Setup		Record On/Off	
Processing Mode				
PPP-Static O PPP-Kine	matic			
Start/Stop				
Connected			Connected	





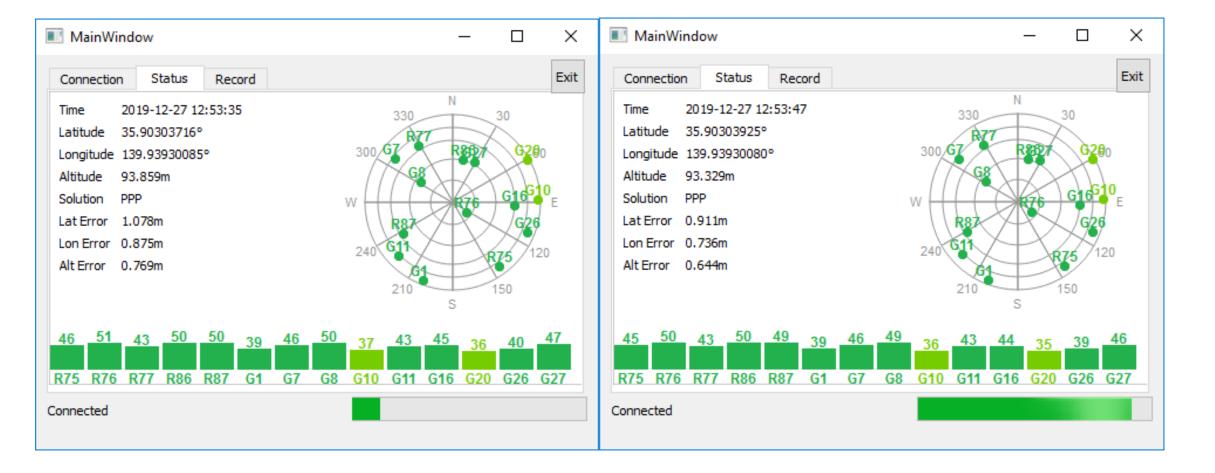




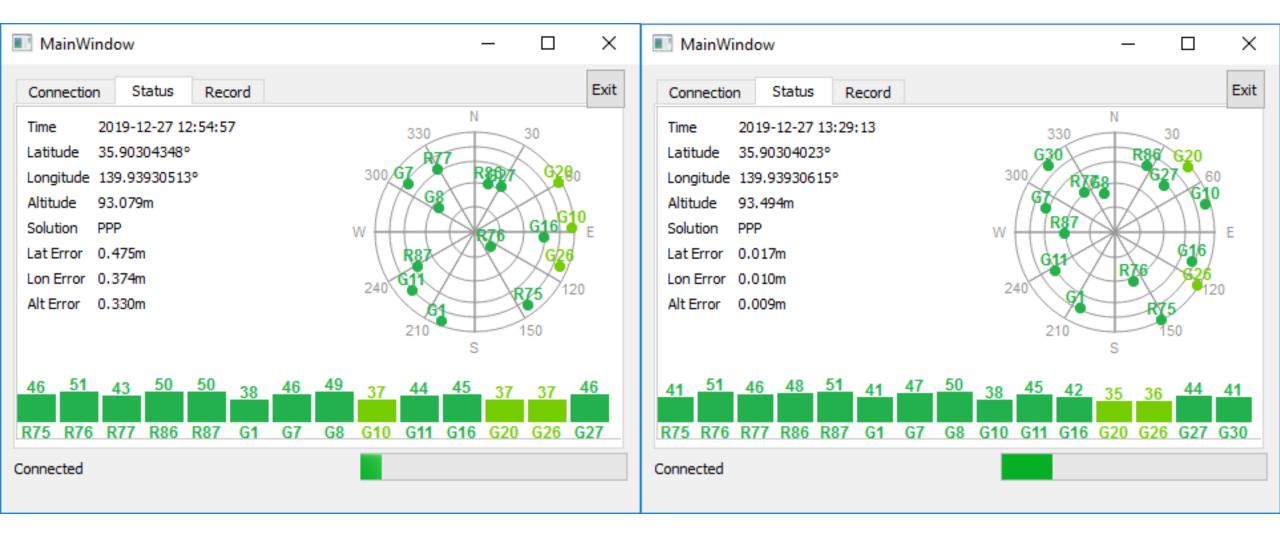
Dinesh Manandhar, CSIS, The University of Tokyo, dinesh@csis.u-tokyo.ac.jp







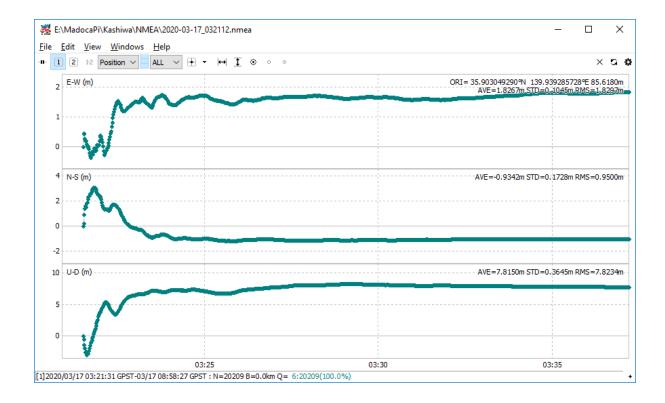








MADOCA PPP at Kashiwa Campus

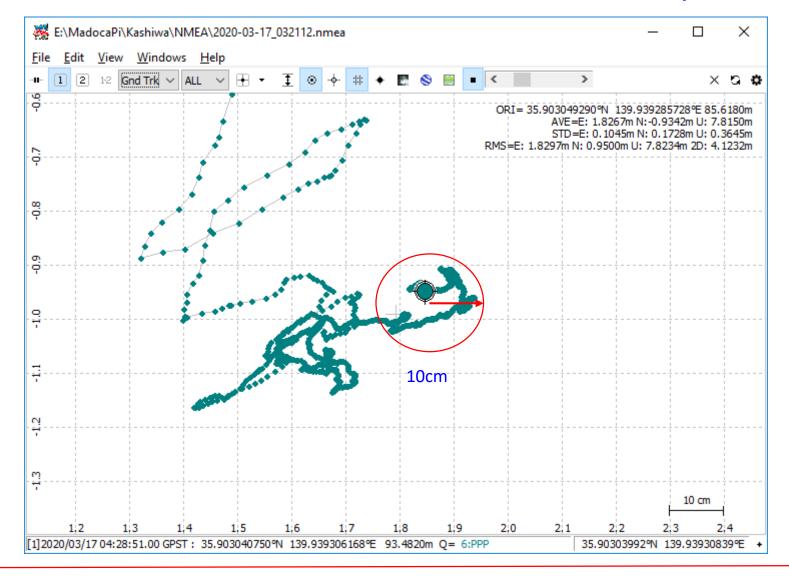


	Measured Values	True Values	Difference meter
LAT	35.90304079	35.90304065	-0.02
LON	139.93930587	139.93930614	0.03
Ht	93.446	93.463	0.02





MADOCA PPP at Kashiwa Campus





Contact and Additional Information

- Homepage
 - Main Page : <u>https://home.csis.u-tokyo.ac.jp/~dinesh/</u>
 - Webinar Page : <u>https://home.csis.u-tokyo.ac.jp/~dinesh/WEBINAR.htm</u> _https://gnss.peatix.com/
 - Training Data etc. : <u>https://home.csis.u-tokyo.ac.jp/~dinesh/GNSS_Train.htm</u>
 - Low-Cost Receiver : <u>https://home.csis.u-tokyo.ac.jp/~dinesh/LCHAR.htm</u>
 - : <u>https://www.facebook.com/gnss.lab/</u>

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•

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- Skype
 - : mobilemap