GNSS Data Processing for High-Accuracy Positioning using Low-Cost Receiver Systems

UTOKYO/ICG Workshop on GNSS for Policy and Decision Makers
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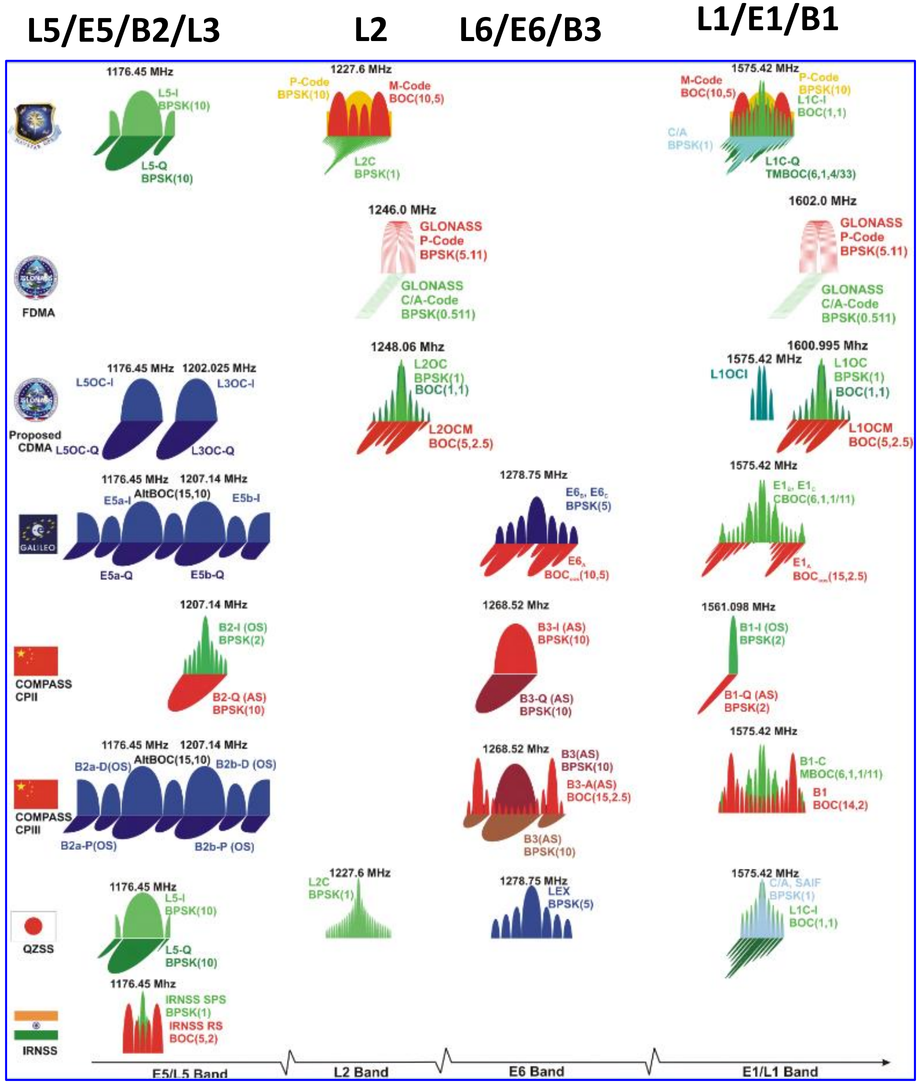
Quiz

- What is the Price of a GNSS Receiver?
  - $10? / $100? / $500 / $1,000 / $3,000 / $10,000 or more?
- What is the Accuracy that you can get from a GNSS receiver?
  - mm, cm, dm, few meters or 10 – 30m
- But, what are your requirements?
  - Types of Applications
  - Accuracy Requirements
  - Data Logging Methods
    - Static Mode on a Tripod
    - Dynamic Mode on a Car, Tractor or Machine?
  - Real-Time or Post-Processing

Low-Cost Receiver Systems

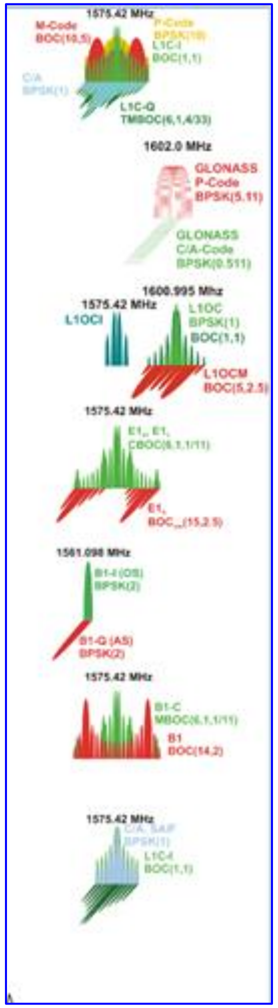
High-End Survey Grade Receivers

- Multi-frequency
  - GPS : L1/L2/L5
  - GLONASS : L1/L2/L3
  - GALILEO : E1/E5/E6
  - BDS : B1/B2/B3
  - QZSS : L1/L2/L5/L6
  - NAVIC : L5/S
- Multi-system
  - GPS, GLONASS, GALILEO, BeiDou, QZSS, NAVIC, SBAS etc
- Price varies from $3, 000 to $30,000 or more



Low-Cost Receivers

L1/E1/B1*



- Multi-System
  - GPS, GLONASS, GALILEO, BeiDou, QZSS, SBAS etc
- Basically Single Frequency
  - L1/E1/B1-Band
  - Very soon: Multi-System, Multi Frequency, L1/L2 or L1/L5
    - Future trend for Mass Market System will be L1/L5
  - Some chip makers have already announced Multi-System, Multi-Frequency GNSS Chips for Mass Market
- Low Cost:
  - Less than $300 (Multi-GNSS, L1 Only) including Antenna and all necessary Hardware, Software
    - Our target is within $100 or less including everything

*Note: Only one signal type from each system is processed
e.g. GPS has L1C/A and L1C in L1, ,but only L1C/A is used in Low-Cost Receiver

Our Definition of Low-Cost Receiver

- Price : $100 or less
- Accuracy : Better than 100cm
- Weight : 100g or less (Without Battery)

100^3

$100 x 100cm x 100g

Will it be possible?

Many Applications require
Low-Cost, Small-Size & Low-Power
Receiver System

But, is it possible to get
High-Accuracy with Low-Cost Receivers?

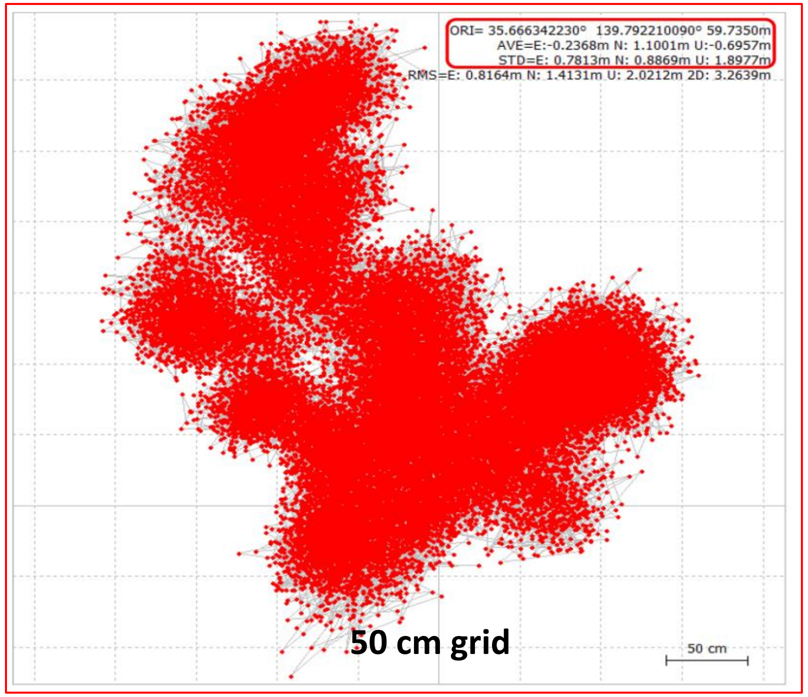
Question?

Although the Normal Accuracy of GPS is about 10m, why can we get Centimeter Level Accuracy?

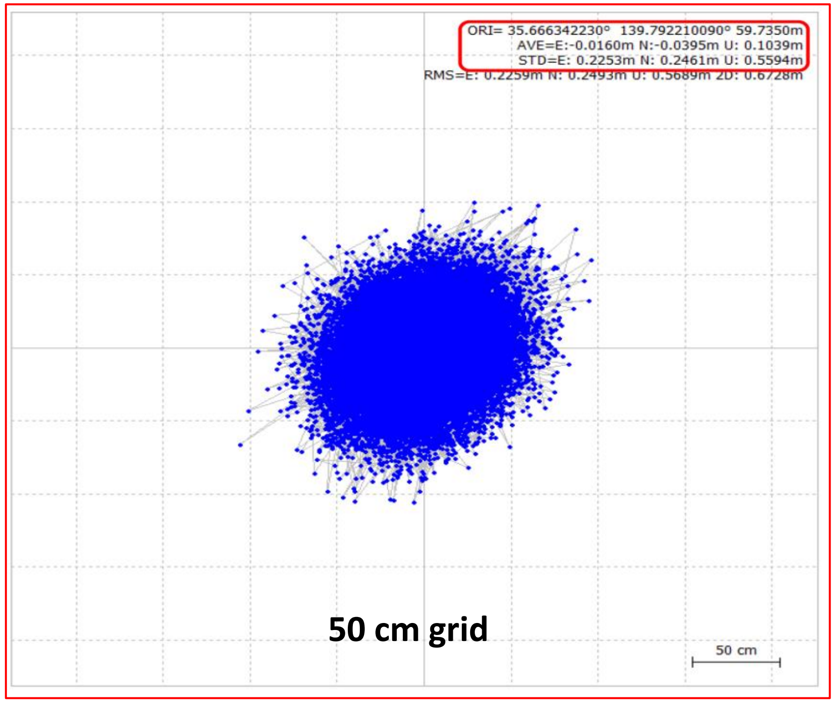
GPS Position Accuracy

How to achieve accuracy from few meters to few centimeters?

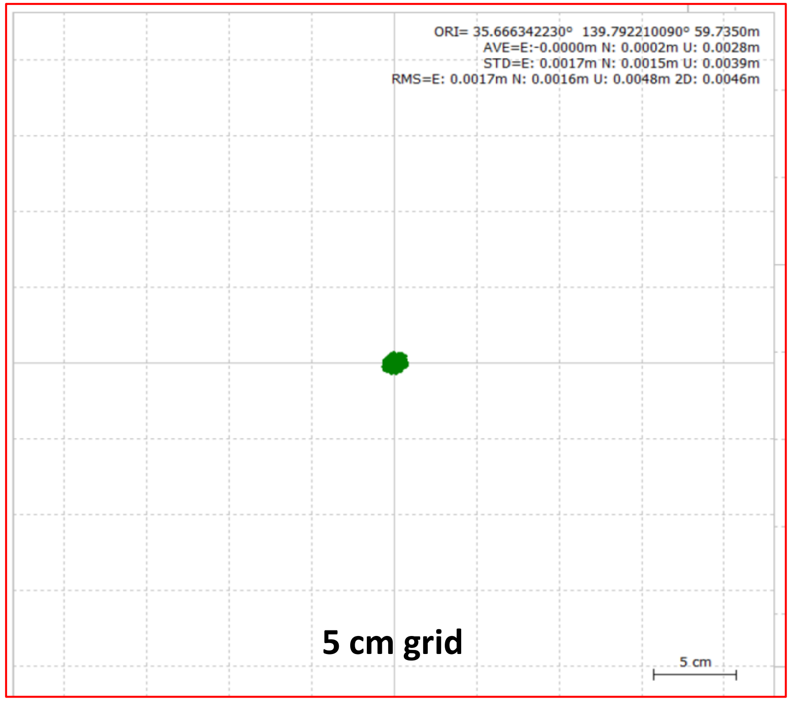
meter → centimeter



SPP (Single Point Position)



DGPS (Differential GPS)
Code-phase observation



RTK (Real Time Kinematic)
Carrier-phase observation

Errors in GPS Observation (L1C/A Signal)

Error Sources	One-Sigma Error , m		Comments
	Total	DGPS	
Satellite Orbit	2.0	0.0	Common errors are removed
Satellite Clock	2.0	0.0	
Ionosphere Error	4.0	0.4	Common errors are reduced
Troposphere Error	0.7	0.2	
Multipath	1.4	1.4	
Receiver Circuits	0.5	0.5	

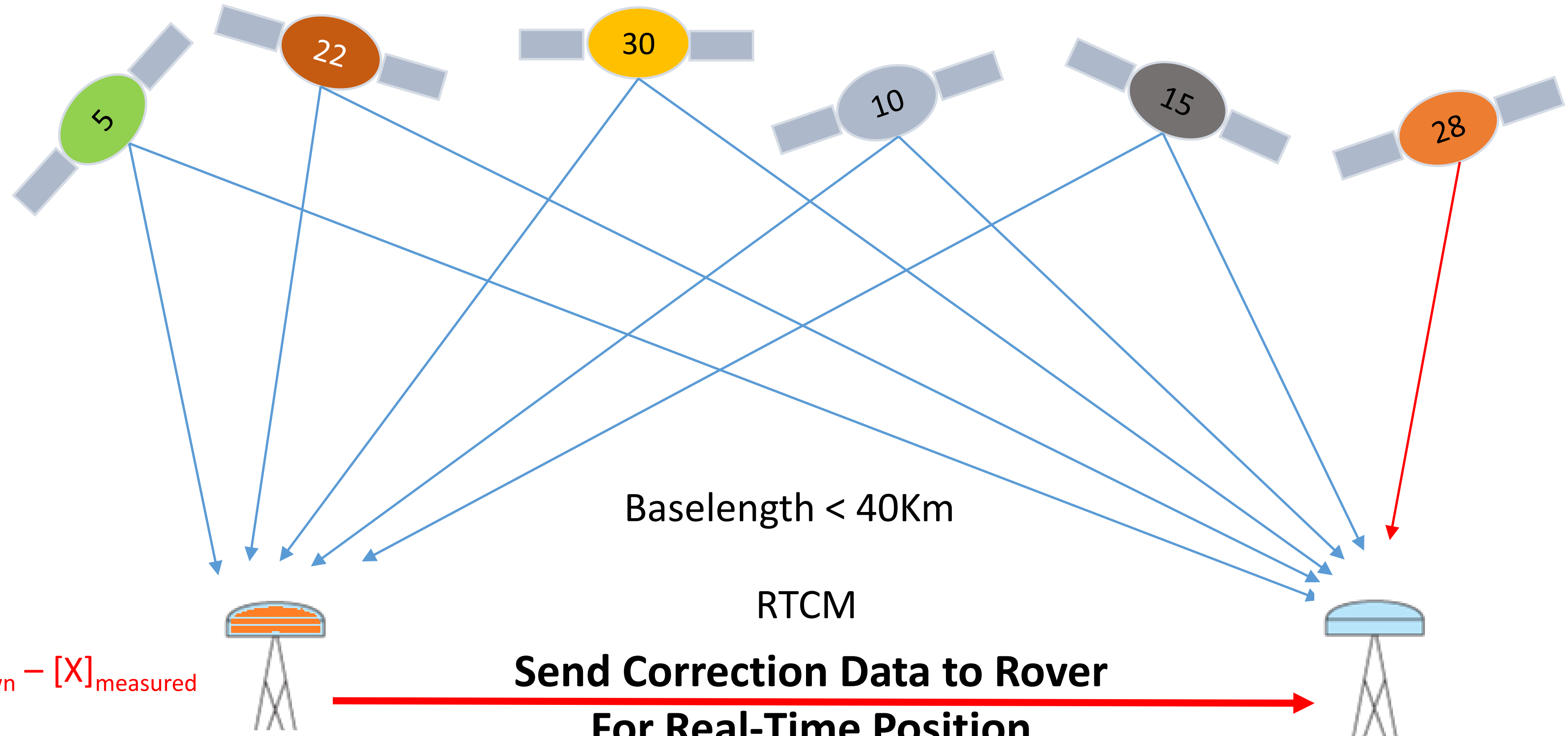
If we can remove common errors, position accuracy can be increased.

Common errors are: Satellite Orbit Errors, Satellite Clock Errors and Atmospheric Errors (within few km)

Values in the Table are just for illustrative purpose, not the exact measured values.
Table Source : http://www.edu-observatory.org/gps/gps_accuracy.html#Multipath

How to Remove or Minimize Common Errors?

Use Differential Correction



$[X]_{error} = [X]_{known} - [X]_{measured}$

For Real-Time Position

Base-Station

Antenna is installed at a known-position

Base-station Antenna position shall be known in advance

For RTK, both rover and base receivers need to use the same satellites

Rover

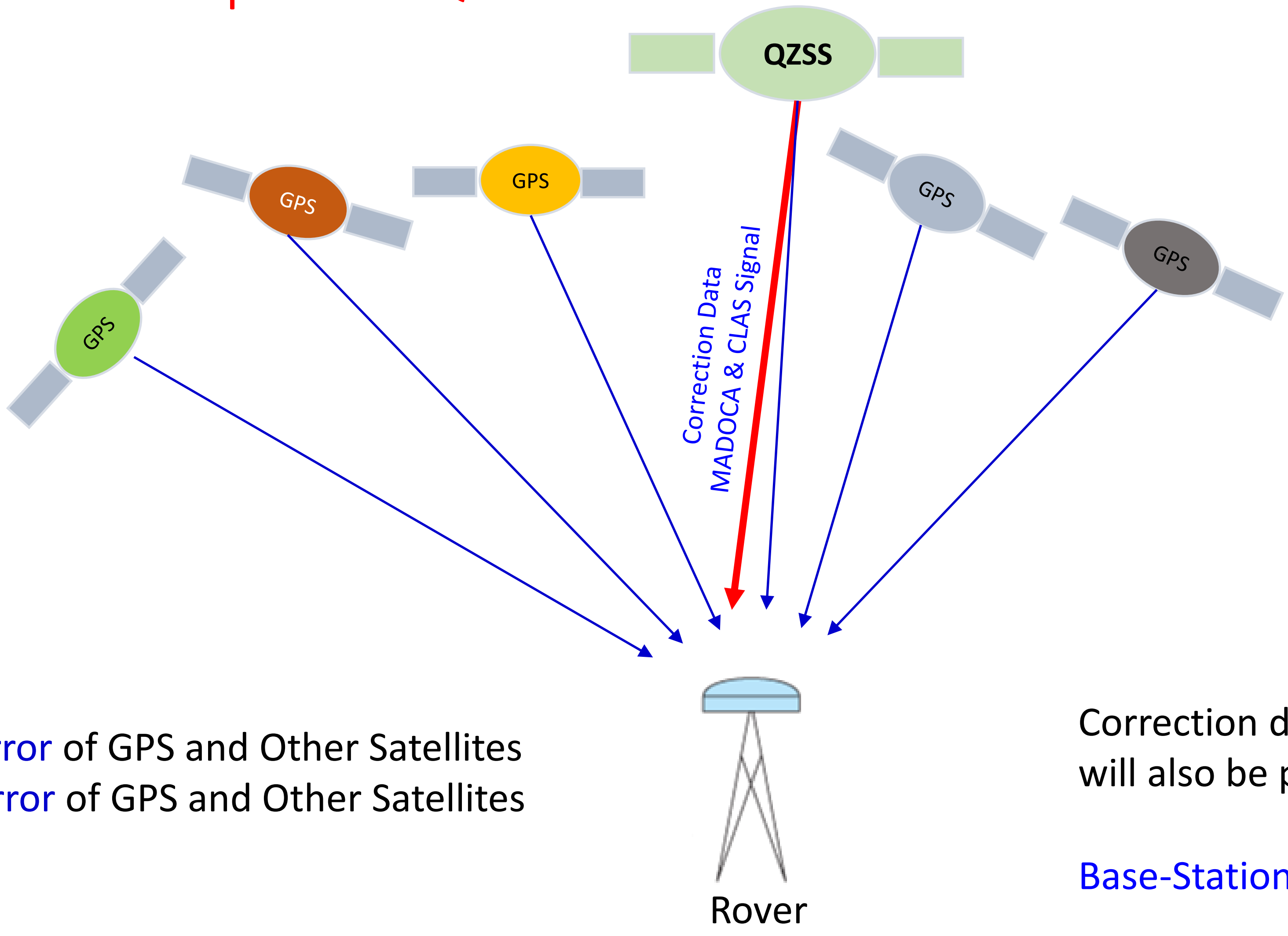
User in the Field

(Either fixed or moving)

RINEX data for post-processing

How to Remove or Minimize Common Errors?

Principle of QZSS MADOCA and CLAS Services



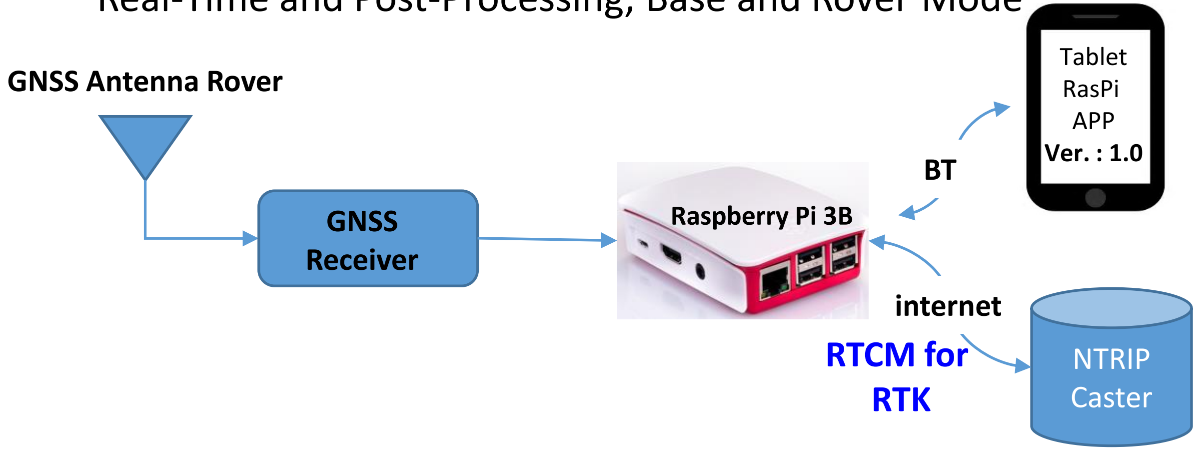
Correction Data:
Satellite Orbit Error of GPS and Other Satellites
Satellite Clock Error of GPS and Other Satellites

Correction data for other satellites will also be provided

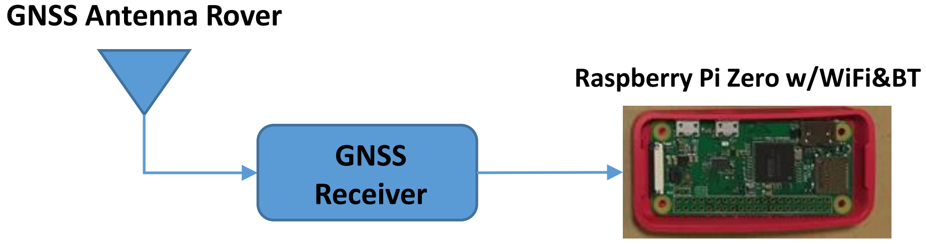
Base-Station not required

Low-Cost RTK Receiver System

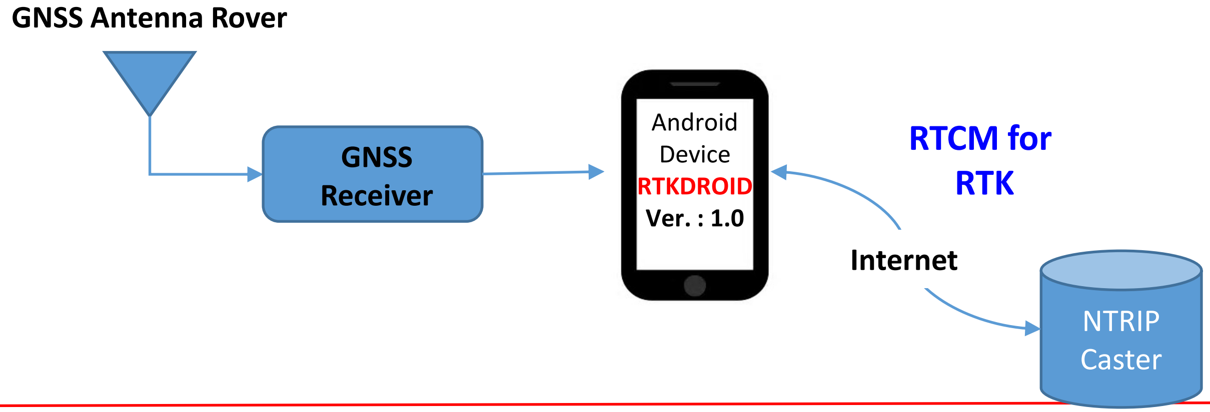
TYPE R1 Type A: Low-Cost, High-Accuracy Receiver System
Real-Time and Post-Processing, Base and Rover Mode



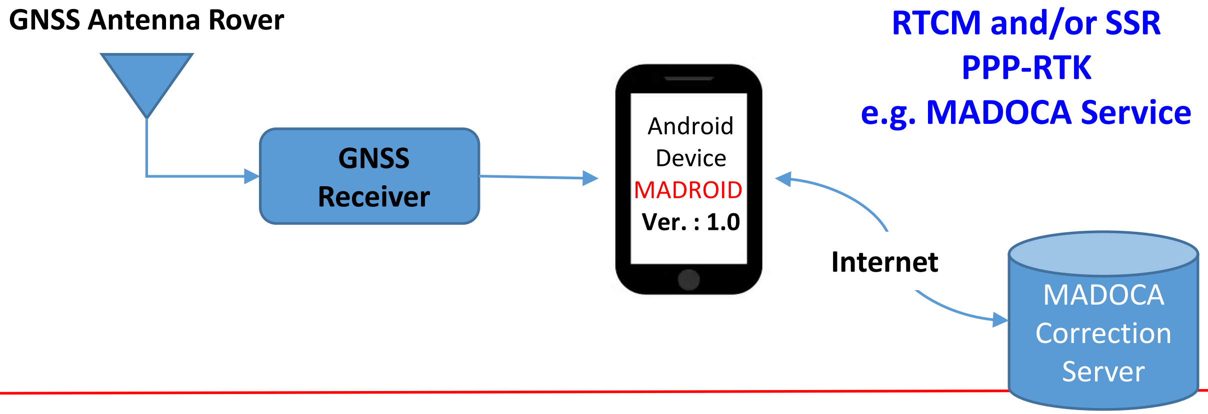
TYPE R2 Type B: Low-Cost, High-Accuracy Receiver System
For Post-Processing & Rover Mode Only



TYPE A1 Type C: Low-Cost, High-Accuracy Receiver System
Real-Time and Post-Processing, Rover Mode Only



TYPE MA Type D: Low-Cost, High-Accuracy Receiver System
Real-Time and Post-Processing, Rover Mode Only



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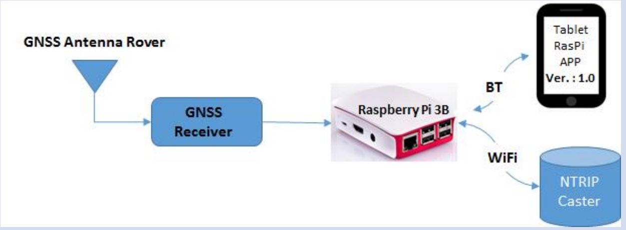
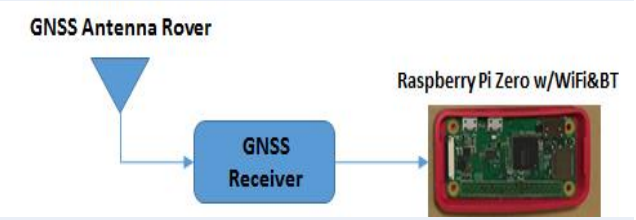
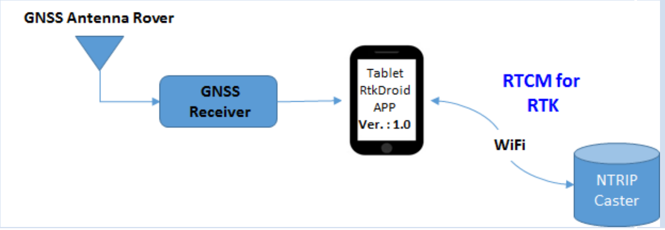
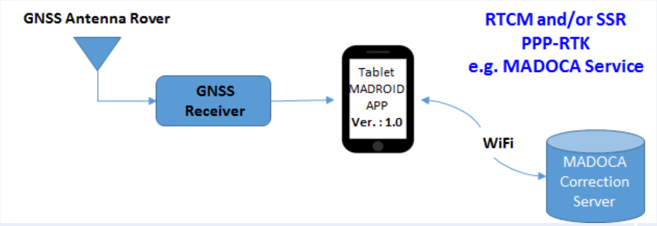
Low-Cost RTK Receiver System

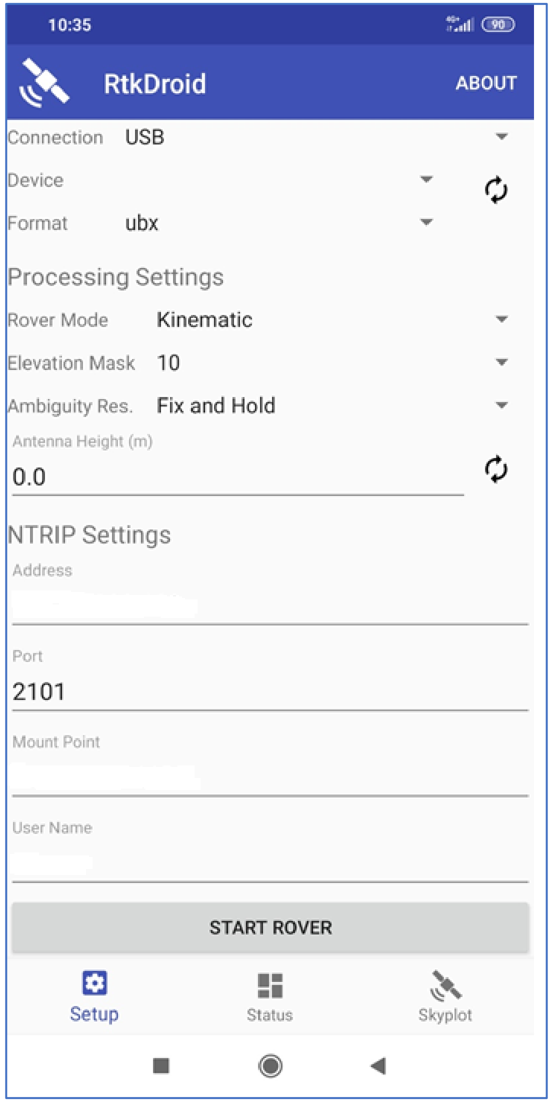
Type	Receiver System	Usage	RTK Processing Engine	Mode	User Interface	Base-Station Data	Correction Data Format
Type R1 **Beta Version**		Real-time RTK Base and Rover Setting	Raspberry Pi 3B	Base or Rover	Android Device APP: RTKPI	NTRIP Server	RTCM 3
Type R2 **Beta Version**		Log Raw Data for Post-processing RTK	Raspberry Pi Zero/WiFi&BT Option: RaspberryPi Camera	Rover Only	None	Post-processing	User Defined
Type A1 **Release 1.0**		Real-time RTK Simultaneous Log of Raw Data	Android Device	Rover Only	Android Device APP: RTKDROID	NTRIP Server or VRS	RTCM 3
Type MA **Release 1.0**		Real-time PPP Based on MADOCA Correction Data from Internet	Android Device	Rover Only	APP: MADROID	MADOCA Correction Data Server	**MADOCA Format**

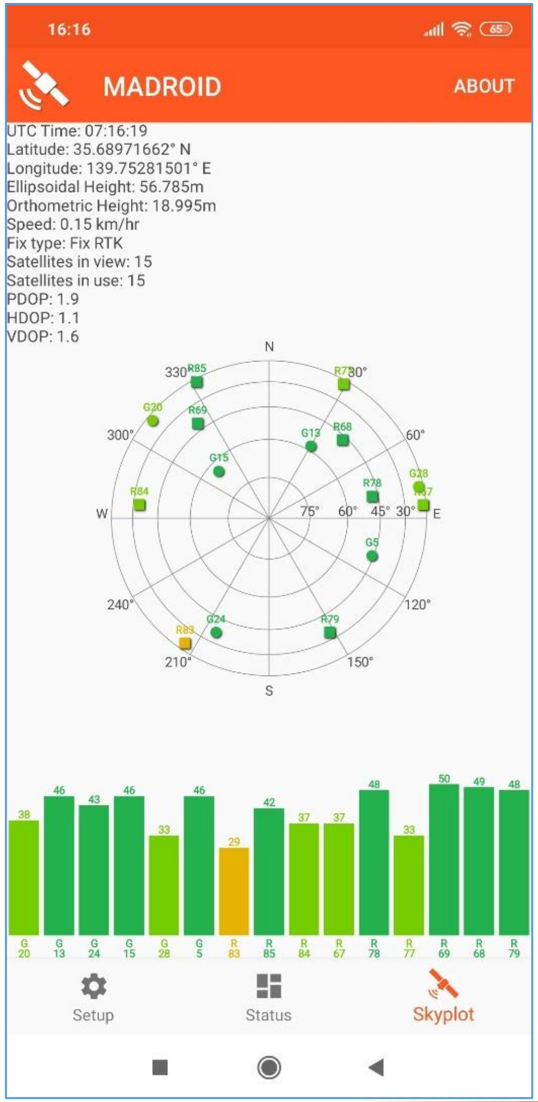
Screen Shots of RTKDROID and MADROID

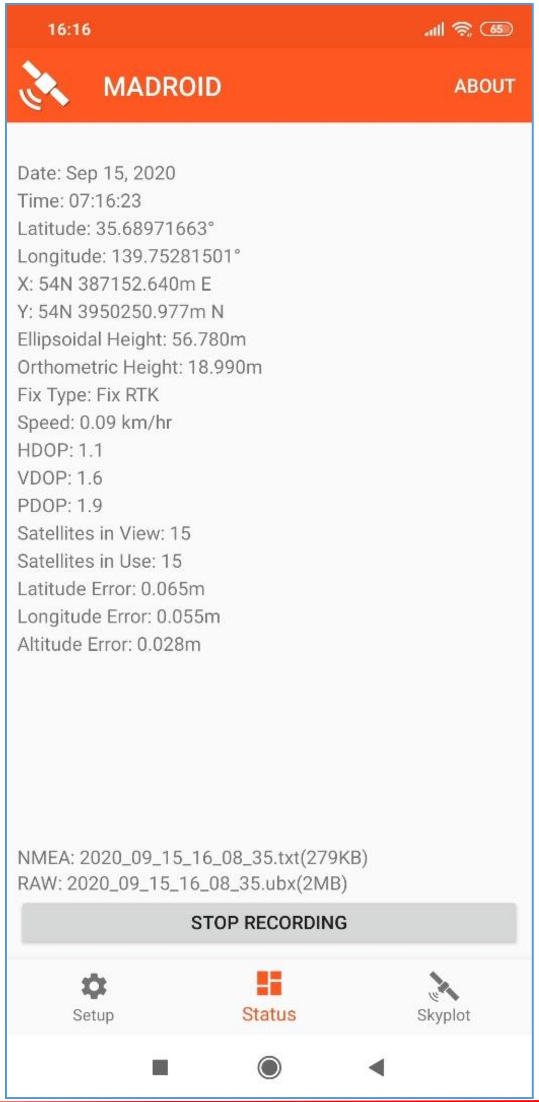
Connect GNSS receiver to Android device

(1) RTKDROID :
For RTK or PPK

(2) MADROID:
for MADOCA-PPP,
MADOCA-PPP/AR (future)



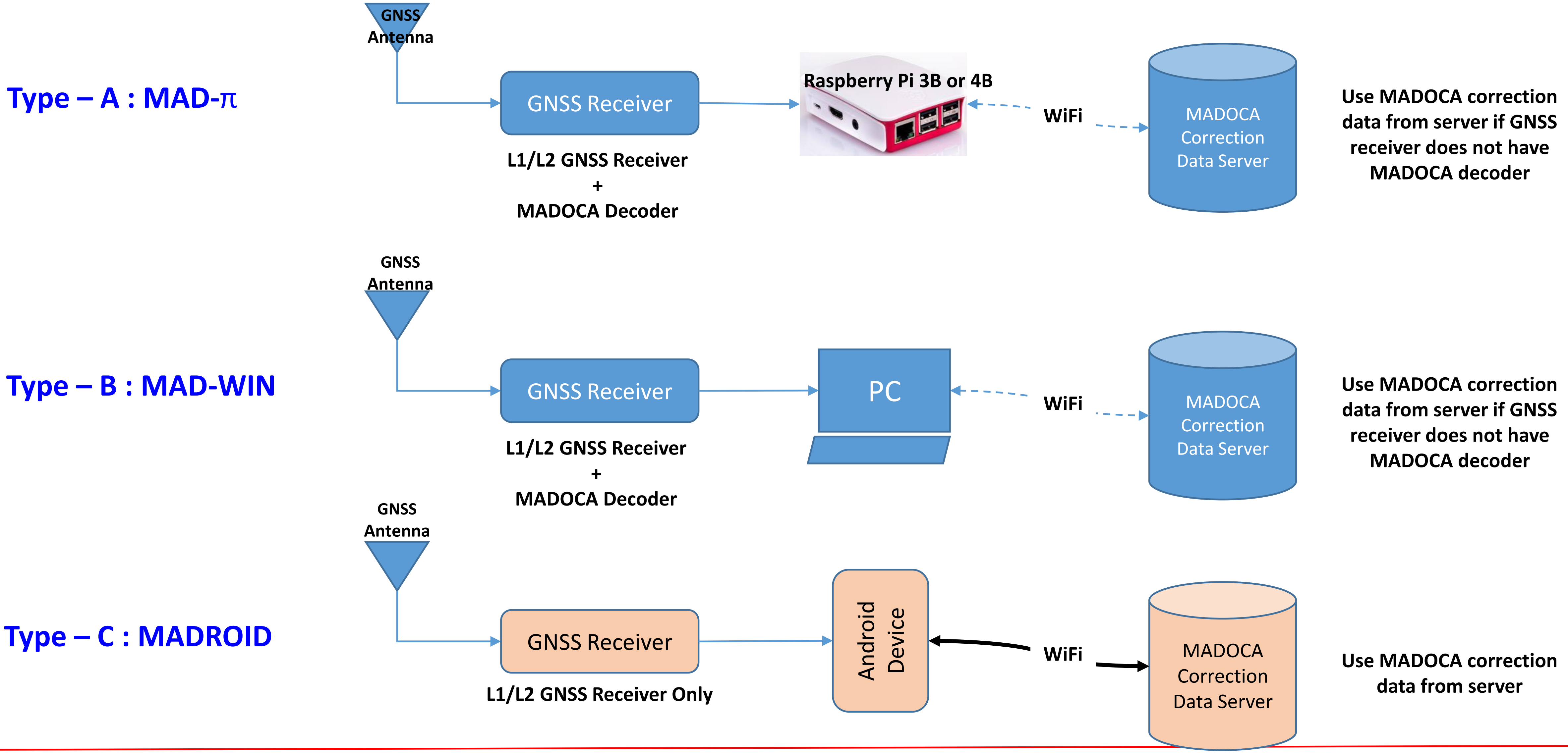




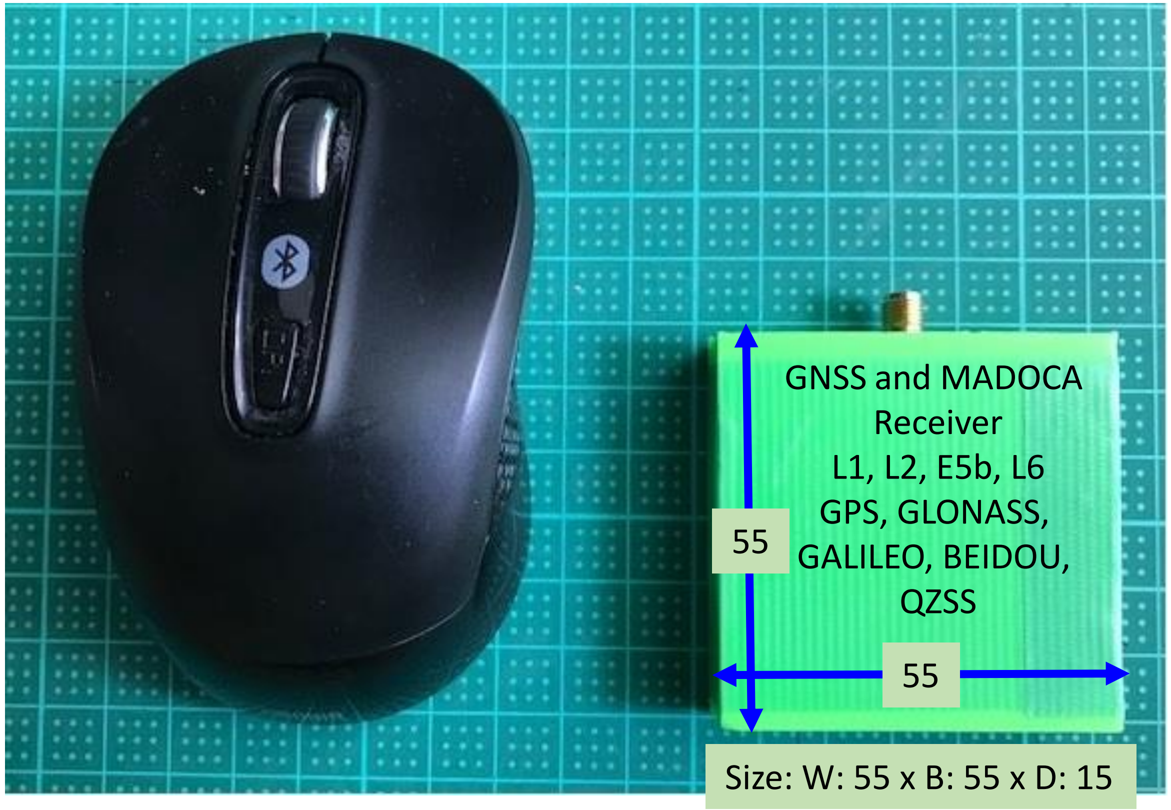
Low-Cost MADOCA PPP Receiver Systems

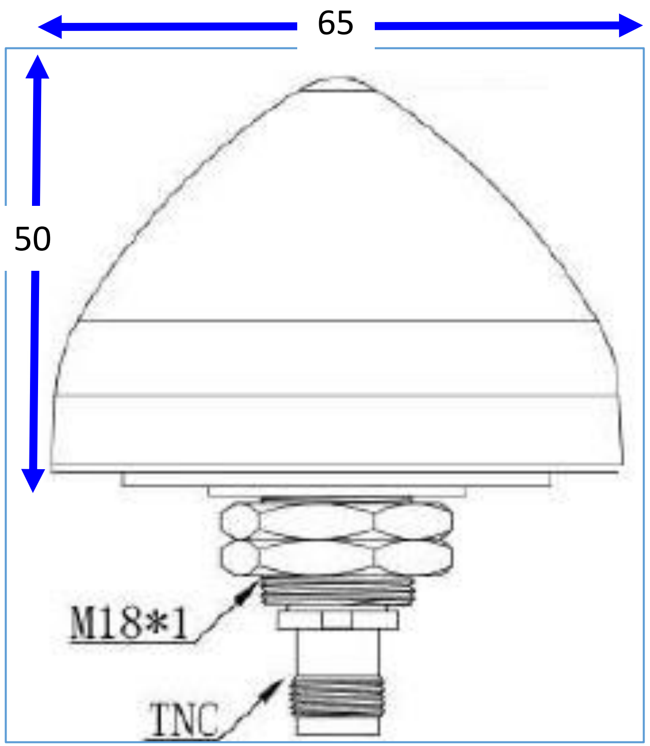
Type A: MAD-π	Type B: MAD-WIN	Type C: MADROID
• Platform / OS : RaspberryPi • Receiver : Dual Frequency Receiver • Data Format : UBX, SBF or RTCM 3 • Correction Data : UBX, RTCM3 or JAXA online	• Platform / OS : Windows • Receiver : Dual Frequency Receiver • Data Format : UBX, SBF or RTCM 3 • Correction Data : UBX, RTCM3 or JAXA online	• Platform / OS : Android Device • Receiver : Dual Frequency Receiver • Data Format : UBX or RTCM 3 • Correction Data : JAXA online

MADOCA Low-Cost Receiver Systems

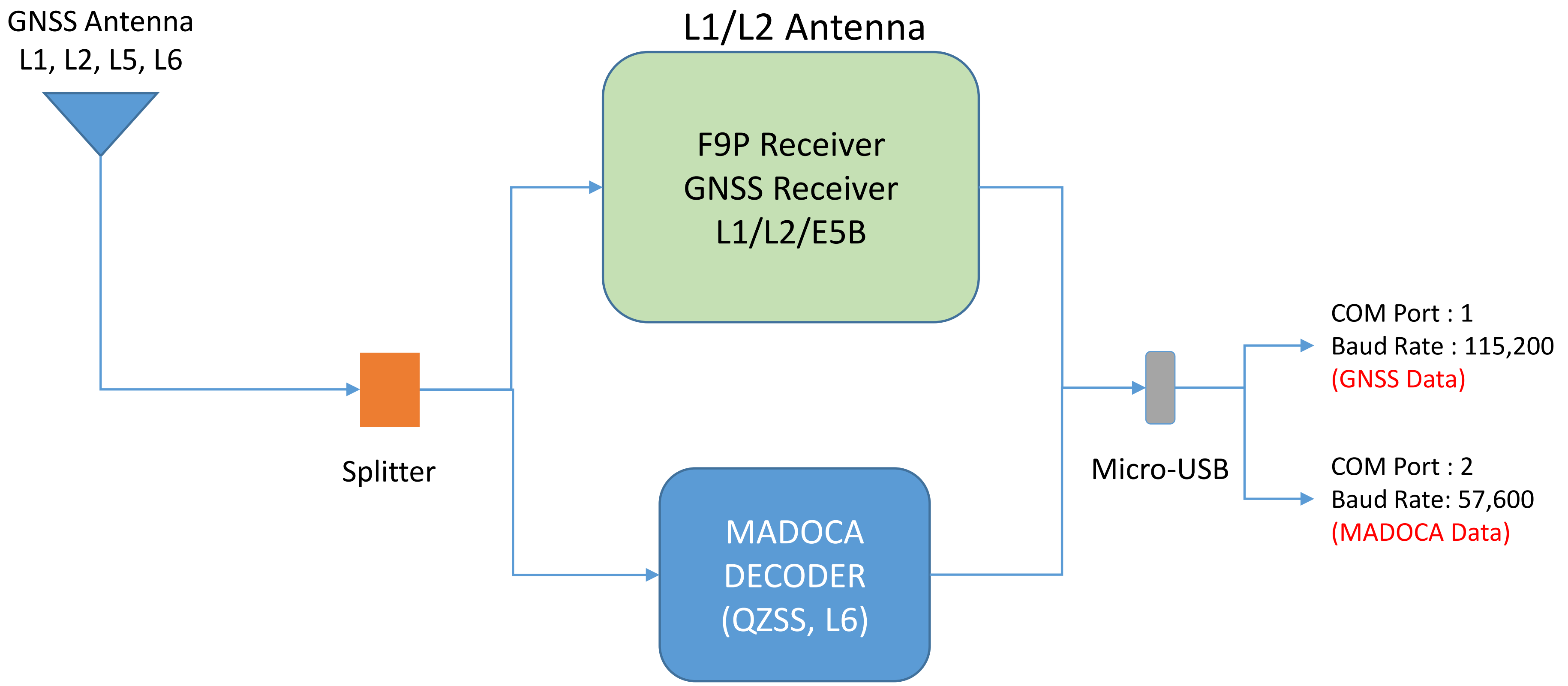


GNSS MADOCA Receiver and Antenna





Receiver System Architecture



GNSS Raw Data, F9P Receiver Output

UBX - RXM (Receiver Manager) - RAWX (Multi-GNSS Raw Measurement Data) 471 s

Local Time 2108:364155.001000000 [s]

Leap seconds 18 (VALID) [s] Clock reset

SV	Sign...	G...	Pseudo Range [m]	Carrier Phase [c...	Dopple...	Lock T...	SNR	PR Std...	CP Std...	DO St...	P...	C...	H...
G03	L1C/A	-	21647431.89	113758026.20	1766.7	64500	47	0.08	0.004	0.064	Y	Y	Y
G07	L1C/A	-	24915724.27	130933010.83	-3266.5	64500	40	0.16	0.008	0.256	Y	Y	Y
G08	L1C/A	-	23275226.57	122312137.25	-2627.7	64500	48	0.08	0.004	0.064	Y	Y	Y
G22	L1C/A	-	21510039.63	113036022.46	-299.5	64500	51	0.08	0.004	0.032	Y	Y	Y
G30	L1C/A	-	24278609.23	127584953.13	-2644.0	64500	39	0.32	0.012	0.512	Y	Y	Y
Q01	L1C/A	-	37653530.29	197870641.68	-73.0	64500	45	0.08	0.004	0.064	Y	Y	Y
B13	B1D1	-	39143654.13	203831280.88	4.6	64500	44	0.08	0.004	0.128	Y	Y	Y
B23	B1D1	-	25258313.11	131526650.97	-3329.3	64500	45	0.08	0.004	0.128	Y	Y	Y
B33	B1D1	-	24290016.20	126484489.71	1997.9	64500	44	0.08	0.004	0.128	Y	Y	Y
B07	B1D1	-	36355222.61	189311179.89	-935.5	64500	40	0.16	0.008	0.256	Y	Y	Y
B14	B1D1	-	23562278.42	122694967.85	744.2	64500	46	0.08	0.004	0.128	Y	Y	Y
B08	B1D1	-	37559872.35	195584111.77	-297.2	64500	36	0.32	0.012	0.256	Y	Y	Y
R14	L1OF	-7	20799394.57	110872489.66	-1915.9	64500	41	1.28	0.008	0.128	Y	Y	Y
R07	L1OF	5	24916190.47	133378314.32	-3400.1	4880	31	2.56	0.023	0.512	Y	Y	Y
R08	L1OF	6	22339471.45	119626854.33	-756.2	0	22	10.24	-	8.192	Y	N	N
R13	L1OF	-2	22903427.46	122303024.15	-4716.8	64500	38	1.28	0.008	0.256	Y	Y	Y
R15	L1OF	0	22497781.39	120221322.41	1857.6	900	30	1.28	0.027	1.024	Y	Y	N
R23	L1OF	3	21577264.34	115423832.34	-2281.8	64500	39	1.28	0.008	0.256	Y	Y	Y
Q02	L1C/A	-	37387370.90	196471961.13	-586.0	64500	44	0.08	0.004	0.128	Y	Y	Y
E25	E1C	-	25156832.92	132200035.35	-2745.3	64500	47	0.16	0.004	0.064	Y	Y	Y
Q07	L1C/A	-	37723026.81	198235850.73	-456.2	64500	42	0.08	0.008	0.128	Y	Y	Y
E04	E1C	-	27608611.14	145084222.79	787.6	64500	40	0.32	0.008	0.128	Y	Y	Y
G32	L1C/A	-	26205245.91	137709496.61	23.5	0	19	10.24	-	8.192	Y	N	N
E24	E1C	-	27082376.41	142318876.30	-3603.2	64500	30	1.28	0.023	0.512	Y	Y	Y
B34	B1D1	-	27305668.25	142187779.36	-2696.7	64500	40	0.16	0.008	0.256	Y	Y	Y
R17	L1OF	4	22576755.59	120812779.20	1583.3	0	24	5.12	-	2.048	Y	N	N
R24	L1OF	2	20561599.24	109952111.10	-571.8	0	24	5.12	-	2.048	Y	N	N

UBX - RXM (Receiver Manager) - RAWX (Multi-GNSS Raw Measurement Data) 119 s

Local Time 2108:364155.001000000 [s]

Leap seconds 18 (VALID) [s] Clock reset

SV	Sign...	G...	Pseudo Range [m]	Carrier Phase [c...	Dopple...	Lock T...	SNR	PR Std...	CP Std...	DO St...	P...	C...	H...
R24	L1OF	2	20561599.24	109952111.10	-571.8	0	24	5.12	-	2.048	Y	N	N
G11	L1C/A	-	21725325.52	114167355.90	-2393.9	0	19	10.24	-	8.192	Y	N	N
E09	E1C	-	25953366.03	136385811.26	2082.8	31320	31	0.64	0.020	0.512	Y	Y	Y
B07	B2D1	-	36355217.75	146387393.88	-723.3	64500	46	0.08	0.004	0.128	Y	Y	Y
B13	B2D1	-	39143656.89	157615286.40	3.7	64500	41	0.08	0.008	0.256	Y	Y	Y
B08	B2D1	-	37559865.78	151238004.56	-230.1	64500	36	0.32	0.012	0.512	Y	Y	Y
B14	B2D1	-	23562274.77	94875513.57	575.2	64500	47	0.08	0.004	0.128	Y	Y	Y
E09	E5BQ	-	25953376.32	104503489.05	1595.4	7200	30	0.32	0.023	0.512	Y	Y	Y
E25	E5BQ	-	25156838.06	101296166.80	-2103.6	64500	46	0.08	0.004	0.064	Y	Y	Y
E04	E5BQ	-	27608614.87	111168447.66	603.2	64500	38	0.08	0.008	0.256	Y	Y	Y
E24	E5BQ	-	27082389.38	109049567.15	-2761.8	64500	29	0.32	0.020	0.256	Y	Y	Y
G03	L2CL	-	21647433.43	88642630.21	1376.6	64500	42	0.16	0.008	0.128	Y	Y	Y
G07	L2CL	-	24915724.70	102025717.75	-2545.6	64500	31	0.64	0.027	1.024	Y	Y	Y
G08	L2CL	-	23275228.17	95308161.74	-2047.7	64500	43	0.08	0.004	0.128	Y	Y	Y
G30	L2CL	-	24278610.59	99416856.48	-2060.6	64500	39	0.32	0.008	0.256	Y	Y	Y
Q01	L2CL	-	37653530.82	154184923.80	-56.7	64500	39	0.32	0.008	0.256	Y	Y	Y
R13	L2OF	-2	22903428.93	95124586.38	-3668.6	64500	33	1.28	0.020	0.512	Y	Y	Y
R14	L2OF	-7	20799400.97	86234179.82	-1489.7	64500	30	1.28	0.027	1.024	Y	Y	Y
R07	L2OF	5	24916072.27	103738199.24	-2645.2	0	24	5.12	-	2.048	Y	N	N
R08	L2OF	6	22339431.21	93042941.92	-588.8	0	24	10.24	-	8.192	Y	N	N
Q07	L2CL	-	37723023.32	154469487.54	-355.4	64500	40	0.32	0.008	0.256	Y	Y	Y
Q02	L2CL	-	37387371.70	153095048.86	-456.7	64500	45	0.16	0.004	0.128	Y	Y	Y

GNSS Navigation Data Bits, F9P Receiver Output

UBX - RXM (Receiver Manager) - SFRBX (Subframe Data NG) 13 s

denotes data received on subChn   Strip Parity Bits

SV	MSG	DATA (* denotes invalid words)
BDS 7 B1D1 0	1	38901595 02980070 05E0B162 2289108A 06070A96 3D450F44 1DD669E1 18007A25 14EABF2E 2F05E156
BDS 7 B2D1 0	??	38901595 02980070 05E0B162 2289108A 06070A96 3D450F44 1DD669E1 18007A25 14EABF2E 2F05E156
BDS 8 B1D1 0	1	38901595 02980070 05E0B162 2286EFB5 36070AD6 3D450F44 1DD669E1 18006C2A 3C41FFEB 33B34166
BDS 8 B2D1 0	??	38901595 02980070 05E0B162 2286EFB5 36070AD6 3D450F44 1DD669E1 18006C2A 3C41FFEB 33B34166
BDS 10 B2D1 0	??	38901595 02980070 05E0B162 2283E0B1 1A070A56 3D450F44 1DD669E1 18006E2C 0C7CE03A 05A1C1D5
BDS 11 B1D1 0	1	38901595 02981075 05E0B162 228280B3 0B070A26 3D450F44 1DD669E1 18006522 16DCFFFD 32BEA2F6
BDS 11 B2D1 0	??	38901595 02981075 05E0B162 228280B3 0B070A26 3D450F44 1DD669E1 18006522 16DCFFFD 32BEA2F6
BDS 13 B1D1 0	1	38901595 02980070 05E0B162 22BA002D 18070A26 3D450F44 1DD669E1 18001E24 3B5500B6 0B14E149
BDS 13 B2D1 0	??	38901595 02980070 05E0B162 22BA002D 18070A26 3D450F44 1DD669E1 18001E24 3B5500B6 0B14E149
BDS 14 B1D1 0	1	38901595 0298607D 05E0B162 2283C0BB 09070C5C 3D04D0F5 0D8679E4 181E207E 00CDA0D2 1A4E47DA
BDS 14 B2D1 0	??	38901595 0298607D 05E0B162 2283C0BB 09070C5C 3D04D0F5 0D8679E4 181E207E 00CDA0D2 1A4E47DA
BDS 23 B1D1 0	1	38901595 02981075 05E0B162 228FD382 3D070AF6 3D450F44 1DD669E1 1800472E 27AF000B 0443615C
BDS 33 B1D1 0	1	38901595 02981075 05E0B162 22A57976 17070AE6 3D450F44 1DD669E1 18004A2A 0D37001B 04A26173
BDS 34 B1D1 0	2	38902597 00D09C8C 33ECCB8E 05C8F99E 232801B3 0A4DBB09 031AB08C 3C98F45A 10AA517C 141A296F
GAL 2 E1B 0	E0	00955555 55555555 55555555 50F14000 A415C000 0000002A AAAA5BDA E9FF4000
GAL 4 E1B 0	E0	00955555 55555555 55555555 50F14000 A42E4000 0000002A AAAA6D4B BEFF4000
GAL 4 E5BI 0	??	0217B097 823989B5 6CE3F207 B3830000 BC014000 0000002A AAAABF45 DC7F4000
GAL 9 E1B 0	E0	00955555 55555555 55555555 50F14000 A42E4000 0000002A AAAA6D4B BEFF4000
GAL 9 E5BI 0	??	051CFFC4 05E07FBF E00878B2 118A8000 AAAA8000 0000002A AAAAAEDE 737F4000
GAL 11 E1B 0	E3	03177FF1 C8C61EBA FC868642 A1798000 955AC000 0000002A AAAA795D FC3F4000
GAL 11 E5BI 0	??	00955555 55555555 55555555 50F14000 A4160000 00000015 5555608A B07F4000
GAL 24 E1B 0	E7	07E25E4C 00E05304 3BCFE129 7F070000 ABD54000 0000002A AAAA4C78 9FFF4000
GAL 24 E5BI 0	??	00955555 55555555 55555555 50F14000 A3F10000 0000002A AAAAB461 6CBF4000
GAL 25 E1B 0	E0	00955555 55555555 55555555 50F14000 A42E4000 0000002A AAAA6D4B BEFF4000
GAL 25 E5BI 0	??	021785E9 82624A02 2B8CABA1 EDA20000 82C74000 0000002A AAAA9472 F2BF4000
GAL 30 E1B 0	E0	00955555 55555555 55555555 50F14000 A3D3C000 0000002A AAAA7FF5 6EFF4000
GLO 1 L1OF 1	2 3/2504	10A10006 74AC20D0 78711800
GLO 2 L1OF -4	2 3/2504	10A10022 91CC07E5 65214000

GNSS Navigation Data Bits, F9P Receiver Output

UBX - RXM (Receiver Manager) - SFRBX (Subframe Data NG) 71 s

denotes data received on subChn

☐ Strip Parity Bits

SV	MSG	DATA (* denotes invalid words)
GLO 2 L1OF -4	2 3/2504	10A10022 91CC07E5 65214000
GLO 2 L2OF -4	2 3/2504	10A10022 91CC07E5 65214000
GLO 7 L1OF 5	6 5/2501	35A842C3 4440F5BC 0EED4800
GLO 7 L2OF 5	10 1/2501	551C096A 6F50889C 3E27D800
GLO 8 L1OF 6	2 3/2504	10A1040B 2CE0277F 380D2000
GLO 8 L2OF 6	1 3/2504	08212942 7FF8AF7F 223CA800
GLO 13 L1OF -2	2 3/2504	10A10486 0400930A 8830F800
GLO 13 L2OF -2	2 3/2504	10A10486 0400930A 8830F800
GLO 14 L1OF -7	2 3/2504	10A10093 CE099683 2074A800
GLO 14 L2OF -7	2 3/2504	10A10093 CE099683 2074A800
GLO 15 L1OF 0	2 3/2504	10A10152 2E914D06 669C7000
GLO 15 L2OF 0	14 3/2503	757C390F B86090C4 16F93000
GLO 17 L1OF 4	2 3/2504	10A104E4 A2A19390 B3843000
GLO 17 L2OF 4	5 2/2504	289B0000 00001C00 0266D000
GLO 23 L1OF 3	2 3/2504	10A10524 BE8864C2 D88C7000
GLO 23 L2OF 3	11 1/2500	5EA47CC2 5F74C01A 1A57B000
GLO 24 L1OF 2	1 3/2504	08212CD7 68C06759 09094800
GPS 3 L1C/A 0	3	22C03C33 1DAE8BB3 000228A7 1FB3BA61 800149FD 960AD940 07C6477A 8118C462 BFE9CB02 8846D75B
GPS 3 L2CM 0	45 ??	8B0CB76B A260D13F 7E0C89D6 09F9800F B1B62001 0001E003 2CC01FAD C01C9800 2D9A0EDC 3EA8B0DE
GPS 7 L1C/A 0	3	22C03C33 1DAE8BB3 3FFDBE0D 9183B133 001B49A8 3675A4E1 84A227A7 20971BBB 3FE9BFEB 15BC0E58
GPS 7 L2CM 0	45 ??	8B1CB76B A2617C23 1ABB89B6 75FF9FFE 6F15C014 A002A007 E2E01388 00307500 72D8AEC9 EBC8B1DE
GPS 8 L1C/A 0	3	22C03C33 1DAE8BB3 0000132F 21E748D7 000849DB 1FCE65D1 8AA27F7C 11A57C92 BFE93AA9 827C5AE3
GPS 8 L2CM 0	45 ??	8B20B76B A2612643 E28C49DF CED97FCE 0F18A006 4002BFF2 ADC02B04 400941FF 45D451F5 7A18B21E
GPS 11 L1C/A 0	4/57/1	22C03C33 1DA72CE7 1E46BC59 8976A283 1AD5A5FA ADE00DCB 2529F154 0B0C412F 00DC3CB9 8150FBC7
GPS 14 L1C/A 0	2	22C03C33 1DA96AE7 06BEDCD9 8D4B5D04 14D45B4F 3F000179 B8393A99 8407686C 034AD445 96699F8B
GPS 17 L1C/A 0	3	22C03C33 1DACABFB 000F93CC 1FD0BA3B 3FF70A26 852DBA93 0A1B2F58 04D8B2F2 BFEAB01F 0C7CBD97
GPS 22 L1C/A 0	3	22C03C33 1DAE8BB3 001127AF 3D911B6C 3FFA095F 3B03EA06 87083477 1D4CD7C4 3FE922F8 0806C397
GPS 27 L1C/A 0	1	22C03C33 1DAD094F 03C40037 095100B9 9C3CAE5E B8B6246E 90488135 85966957 003FEA16 B5CB19BC

GNSS Navigation Data Bits, F9P Receiver Output

UBX - RXM (Receiver Manager) - SFRBX (Subframe Data NG) 106 s

denotes data received on subChn

☐ Strip Parity Bits

SV	MSG	DATA (* denotes invalid words)
GLO 17 L1OF 4	2 3/2504	10A104E4 A2A19390 B3843000
GLO 17 L2OF 4	5 2/2504	289B0000 00001C00 0266D000
GLO 23 L1OF 3	2 3/2504	10A10524 BE8864C2 D88C7000
GLO 23 L2OF 3	11 1/2500	5EA47CC2 5F74C01A 1A57B000
GLO 24 L1OF 2	1 3/2504	08212CD7 68C06759 09094800
GPS 3 L1C/A 0	3	22C03C33 1DAE8BB3 000228A7 1FB3BA61 800149FD 960AD940 07C6477A 8118C462 BFE9CB02 8846D75B
GPS 3 L2CM 0	45 ??	8B0CB76B A260D13F 7E0C89D6 09F9800F B1B62001 0001E003 2CC01FAD C01C9800 2D9A0EDC 3EA8B0DE
GPS 7 L1C/A 0	3	22C03C33 1DAE8BB3 3FFDBE0D 9183B133 001B49A8 3675A4E1 84A227A7 20971BBB 3FE9BFEB 15BC0E58
GPS 7 L2CM 0	45 ??	8B1CB76B A2617C23 1ABB89B6 75FF9FFE 6F15C014 A002A007 E2E01388 00307500 72D8AEC9 EBC8B1DE
GPS 8 L1C/A 0	3	22C03C33 1DAE8BB3 0000132F 21E748D7 000849DB 1FCE65D1 8AA27F7C 11A57C92 BFE93AA9 827C5AE3
GPS 8 L2CM 0	45 ??	8B20B76B A2612643 E28C49DF CED97FCE 0F18A006 4002BFF2 ADC02B04 400941FF 45D451F5 7A18B21E
GPS 11 L1C/A 0	4/57/1	22C03C33 1DA72CE7 1E46BC59 8976A283 1AD5A5FA ADE00DCB 2529F154 0B0C412F 00DC3CB9 8150FBC7
GPS 14 L1C/A 0	2	22C03C33 1DA96AE7 06BEDCD9 8D4B5D04 14D45B4F 3F000179 B8393A99 8407686C 034AD445 96699F8B
GPS 17 L1C/A 0	3	22C03C33 1DACABFB 000F93CC 1FD0BA3B 3FF70A26 852DBA93 0A1B2F58 04D8B2F2 BFEAB01F 0C7CBD97
GPS 22 L1C/A 0	3	22C03C33 1DAE8BB3 001127AF 3D911B6C 3FFA095F 3B03EA06 87083477 1D4CD7C4 3FE922F8 0806C397
GPS 27 L1C/A 0	1	22C03C33 1DAD094F 03C40037 095100B9 9C3CAE5E B8B6246E 90488135 85966957 003FEA16 B5CB19BC
GPS 30 L1C/A 0	3	22C03C33 1DAE8BB3 00043E5C 0C51D14C 0003C9A5 902E535C 044EA2FC 210F9F12 BFE9C6CA 8F3C845B
GPS 30 L2CM 0	45 ??	8B78B76B A2617C98 B7334990 2EC4A015 8F1EE005 A0072007 DCC0126C 802FD500 6D9E0B57 AA78B79E
GPS 32 L1C/A 0	1	22C03C33 1DAD094F 03C40037 095100B9 9C3CAE5E B8B6246E 9048806D 89966986 80000FF7 099E73F0
GPS 32 L2CM 0	45 ??	8B80B76A 2261666E 242549BD E8917FFA BE593FEF 60071FFB 68A01D6A E01E99FF C094FB52 9148B81E
QZSS 1 L1C/A 0	3	22C0AA24 1DAE835C 013F2D52 8F43A1DC 3EFE477D A38B4E4D 8884B03B 1F97CD75 BFFAF44D AD458C97
QZSS 1 L2CM 0	??	8B04B76B A2645A9E 8F1B8763 81E965F7 30741FD1 BFEA200F EC0022A0 5FED0500 7088081D E568B05F
QZSS 2 L1C/A 0	3	22C0AA81 9DAE8383 0034848A 91413ED8 00A98799 A75FE251 8214EFF4 1F3CE46E BFFA75FC 2D413300
QZSS 2 L2CM 0	??	8B08B76B A2640922 7E75C7A7 5CC5A780 50C9A039 1FE0E051 814015D2 A009FA03 1B680231 1B98B09F
QZSS 3 L1C/A 0	1	22C0AA81 9DADA1E3 03C840C6 A0000003 00000000 00000000 00000053 2D56698E 803FFF2A BFE0F804
QZSS 3 L2CM 0	??	8B0CA76B 11078264 62640472 E3202A5D A10C1FFC 6C68CFEB FCF931B1 63C702C6 5CEB04CD 1958B0CB
QZSS 7 L1C/A 0	3	22C0AA81 9DAE8383 01F52A2B 28751B08 00F8801D 82F38171 90DAF61A 8A9167D5 800335EF 2D400037
QZSS 7 L2CM 0	??	8B1CB76B A2645450 EA35C002 F3814CC5 900000F8 81F4E053 6340436B 5FB4EE02 D8F00DFE EF08B1DF

Satellite System & Signal Settings

F9P Receiver

UBX - CFG (Config) - GNSS (GNSS Config)

ID	GNSS	Configure	Enable	Channels min	Channels max	Signals
0	GPS	[x]	[x]	8	16	[x] L1C/A
1	SBAS	[ ]	[ ]	0	0	[ ] L1C/A
2	Galileo	[x]	[x]	10	18	[x] E1
3	BeiDou	[x]	[x]	4	5	[x] B1
4	IMES	[ ]	[ ]	0	0	[ ] L1C/A
5	QZSS	[x]	[x]	0	4	[x] L1C/A [ ] L1S
6	GLONASS	[x]	[x]	8	12	[x] L1OF
7	IRNSS					

Number of channels available: 60

Number of channels to use: 60 [ ] Auto set

MADOCA Decoder

UBX - CFG (Config) - GNSS (GNSS Config)

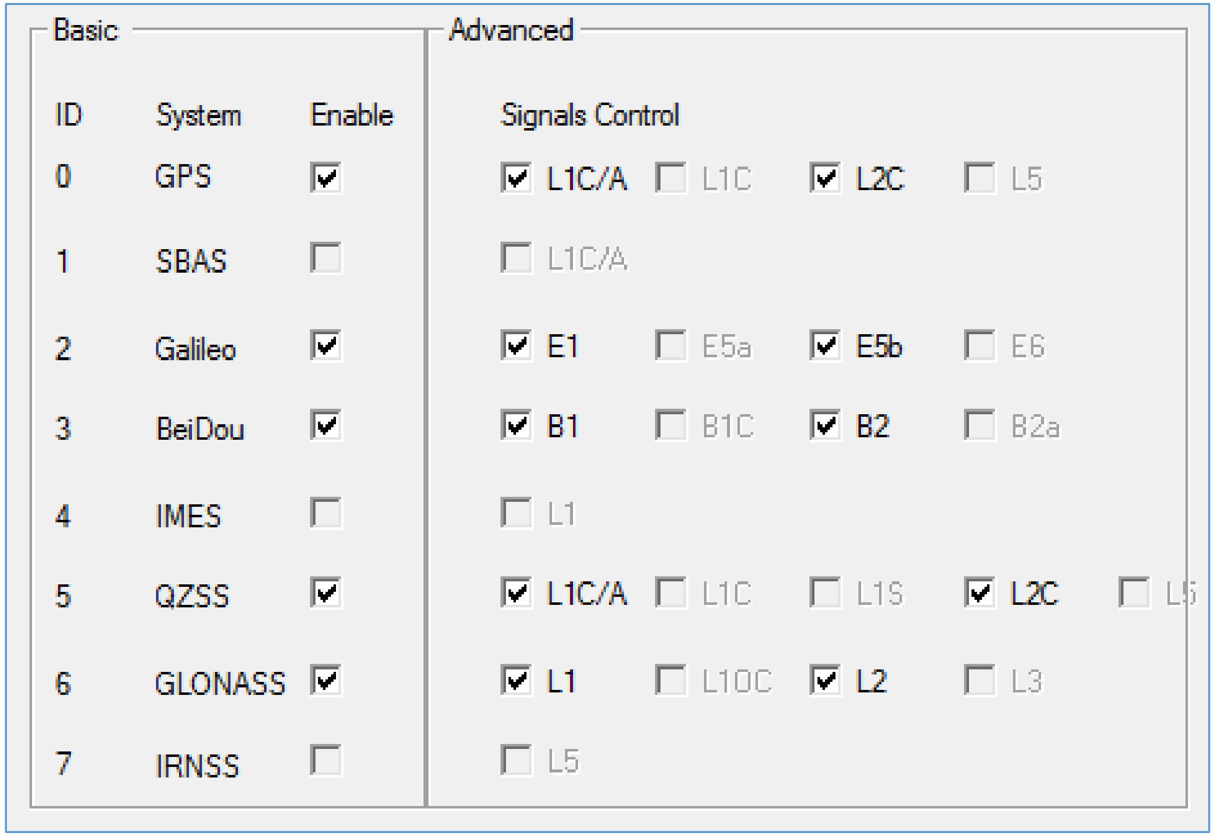
ID	GNSS	Configure	Enable	Channels min	Channels max	Signals
0	GPS	[ ]	[ ]	0	0	[ ] L1C/A
1	SBAS	[ ]	[ ]	0	0	[ ] L1C/A
2	Galileo	[ ]	[ ]	0	0	[ ] E1
3	BeiDou	[ ]	[ ]	0	0	[ ] B1
4	IMES	[ ]	[ ]	0	0	[ ] L1C/A
5	QZSS	[x]	[x]	0	54	[ ] L1C/A [ ] L1S
6	GLONASS	[ ]	[ ]	0	0	[ ] L1OF
7	IRNSS					

Number of channels available: 60

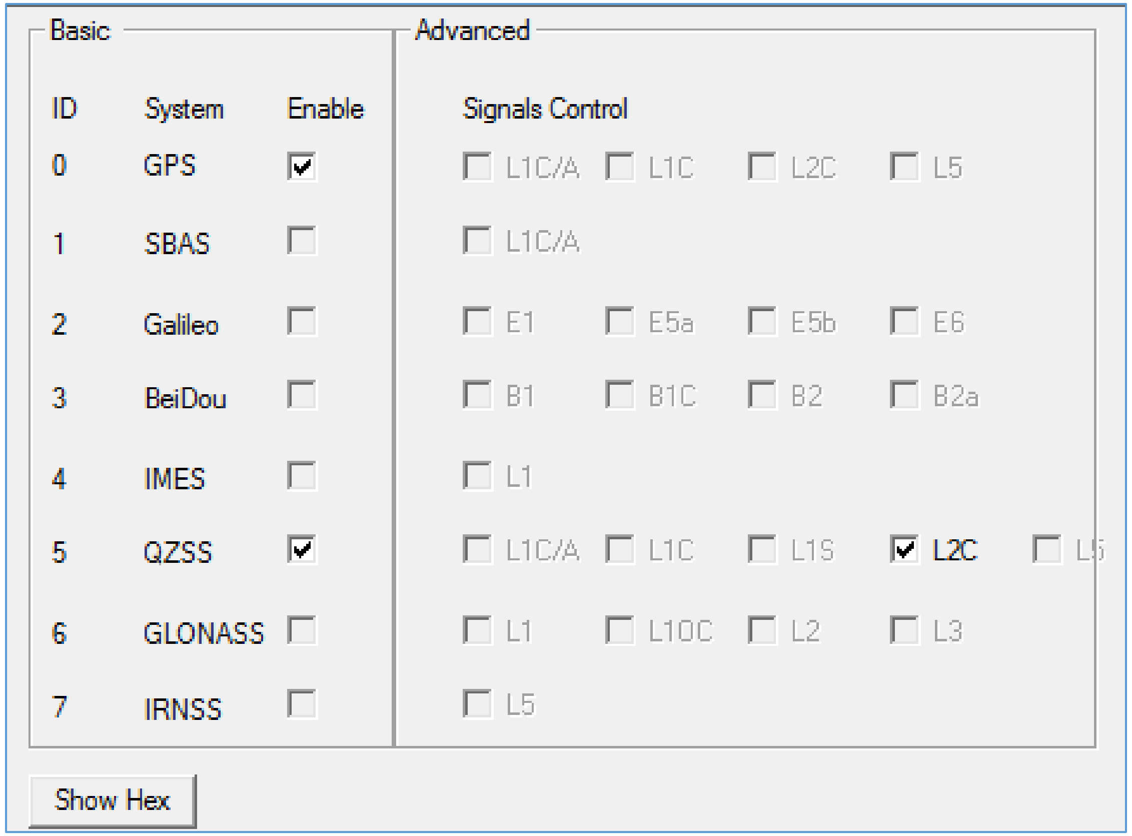
Number of channels to use: 60 [ ] Auto set

Satellite System and Signal Settings

F9P Receiver



MADOCA Decoder

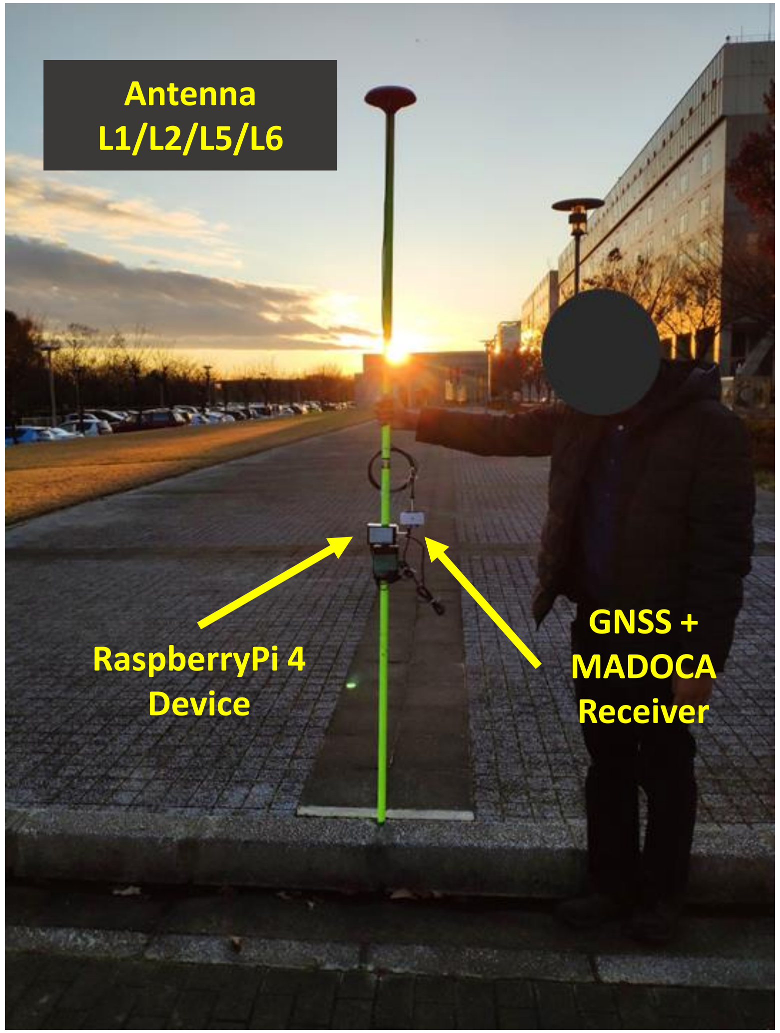


MADOCA Correction Data Output Received Directly from QZSS L6E Channel

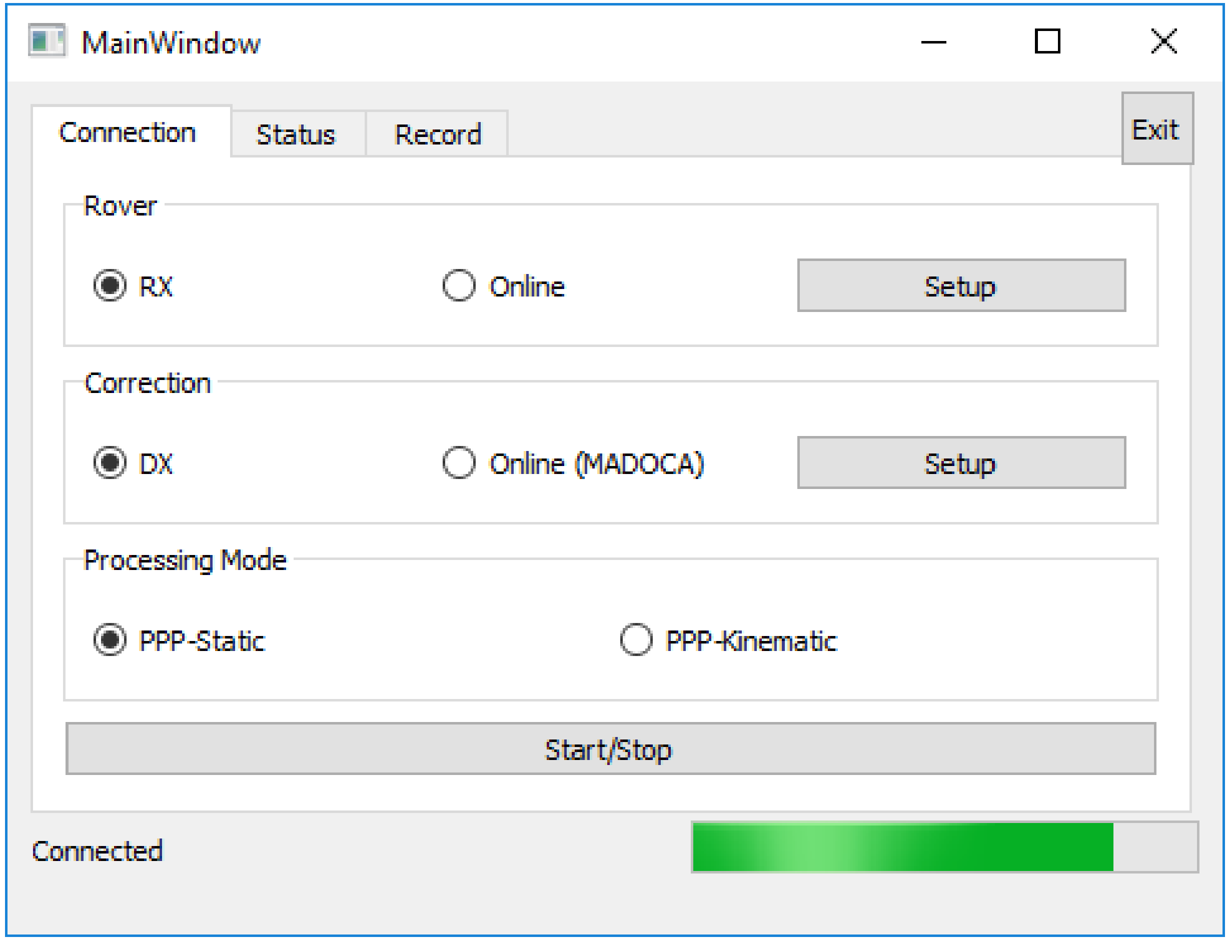

```
[14:27:58.559] 0000   B5 62 02 73 08 01 01 07 5D 23 0C D0 04 00 0A 00   µb.s....]#.Ð....
               0010   00 65 00 00 1A CF FC 1D D1 21 AC 97 12 0F 10 85   .e...Ïü.Ñ!¬.....
               0020   64 B8 16 C0 00 00 20 C4 40 09 C6 FF D8 97 FF DC   d¸.À.. Ä@.ÆÿØ.ÿÜ
               0030   FF FF AE 00 0F 7F FF 79 12 7F F8 98 00 6D D8 04   ÿÿ®...ÿy..ø..mØ.
               0040   CC FF F9 60 A8 DF 80 03 13 86 BF F5 BF 00 43 71   Ìÿù`¨ß....¿õ¿.Cq
               0050   01 D5 FF F9 6F FF 96 FF FB 5E B1 80 35 CF FF E5   .Õÿùoÿ.ÿû^±.5Ïÿå
               0060   5F FF 41 FF F4 01 FF 93 FF 5D 90 2A FF D4 E8 00   _ÿAÿô.ÿ.ÿ].*ÿÔè.
               0070   7C D1 EC 97 FF ED 40 00 4C 00 1E 22 62 00 F3 4F   |Ñì.ÿí@.L.."b.óO
               0080   FF 0C 80 1C 27 FF DC C0 01 E7 FF 9E 4D 9C 01 B3   ÿ...'ÿÜÀ.çÿ.M..³
               0090   A0 10 84 FF D8 BF FF 30 80 04 DF FF 36 01 47 FE    ..ÿØ¿ÿ0..ßÿ6.Gþ
               00A0   9E 20 07 83 FF C6 9F FF 8C FF D4 60 00 1C F6 95   . ..ÿÆ.ÿ.ÿÔ`..ö.
               00B0   64 B4 76 80 00 00 41 84 9A 49 C4 9E 8D 04 22 4A   d´v...A..IÄ..."J
               00C0   64 A8 48 00 00 00 00 00 00 00 00 00 00 00 00 00   d¨H.............
               00D0   00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00   ................
               00E0   00 00 00 00 00 00 00 00 00 00 00 00 00 23 82 2C   .............#.,
               00F0   0A 87 D3 13 8D F9 F2 1B CC AD 1F 77 8C 1D 34 59   ..Ó..ùò.Ì.w..4Y
               0100   2D 09 B1 19 05 CD 99 BA C3 BE DC 55 5B 76 83 08   -.±..Í.ºÃ¾ÜU[v..

[14:27:59.510] 0000   B5 62 02 73 08 01 01 02 9A 25 F3 D3 04 00 0F 02   µb.s.....%óÓ....
               0010   00 14 00 00 1A CF FC 1D CC 21 AC 97 22 0F 10 99   .....Ïü.Ì!¬."...
               0020   64 B9 05 60 00 00 D8 5F F2 C3 87 FF B0 08 BF FD   d¹.`..Ø_òÃ.ÿ°.¿ý
               0030   83 0F FE F8 81 1F F9 07 93 FF 7D 29 40 07 25 96   ..þø..ù..ÿ})@.%.
               0040   01 42 E9 9F F1 CF 1A 00 DA D9 C0 12 21 9F FF A6   .Bé.ñÏ..ÚÙÀ.!.ÿ¦
               0050   CA 00 04 61 A3 FF 22 A2 7F F4 6D A8 00 B8 62 A0   Ê..a£ÿ"¢.ôm¨.¸b 
               0060   01 2F AD FF 3F 7B 1F F0 88 B2 00 9E 63 5F FD DC   ./ÿ?{.ð.².c_ýÜ
               0070   36 00 00 C3 80 2A 75 BB FF F1 4B C0 08 F3 3F FF   6..Ã.*u»ÿñKÀ.ó?ÿ
               0080   D5 6C 1F FB B1 90 B0 EE 04 2A 00 00 04 83 F9 08   Õl.û±.°î.*....ù.
               0090   98 BF 30 59 1F C7 4C E4 F8 BC 98 BF 67 4D 1F ED   .¿0Y.ÇLäø¼.¿gM.í
               00A0   FF 54 7B 91 D6 CF C8 D0 5B F7 EA F3 BF 3F 3A 7F   ÿT{.ÖÏÈÐ[÷êó¿?:.
               00B0   E0 24 11 FB 85 9A 5F B2 AB CF F0 26 3A 7E 71 71   à$.û.._²«Ïð&:~qq
               00C0   5F AE F7 AF FB 18 E6 3E C2 BE 13 8D 64 B9 05 40   _®÷¯û.æ>Â¾..d¹.@
               00D0   00 00 23 FF C6 88 00 00 00 00 00 00 00 00 00 00   ..#ÿÆ...........
               00E0   00 00 00 00 00 00 00 00 00 00 00 00 00 00 A1 53   ..............¡S
               00F0   91 E6 BA C8 F2 6C D7 B9 49 5E 21 02 65 D8 86 FE   .æºÈòl×¹I^!.eØ.þ
               0100   54 FD 64 0D BE 60 64 07 B2 DE 9F A2 69 22 10 3E   Týd.¾`d.²Þ.¢i".>
```

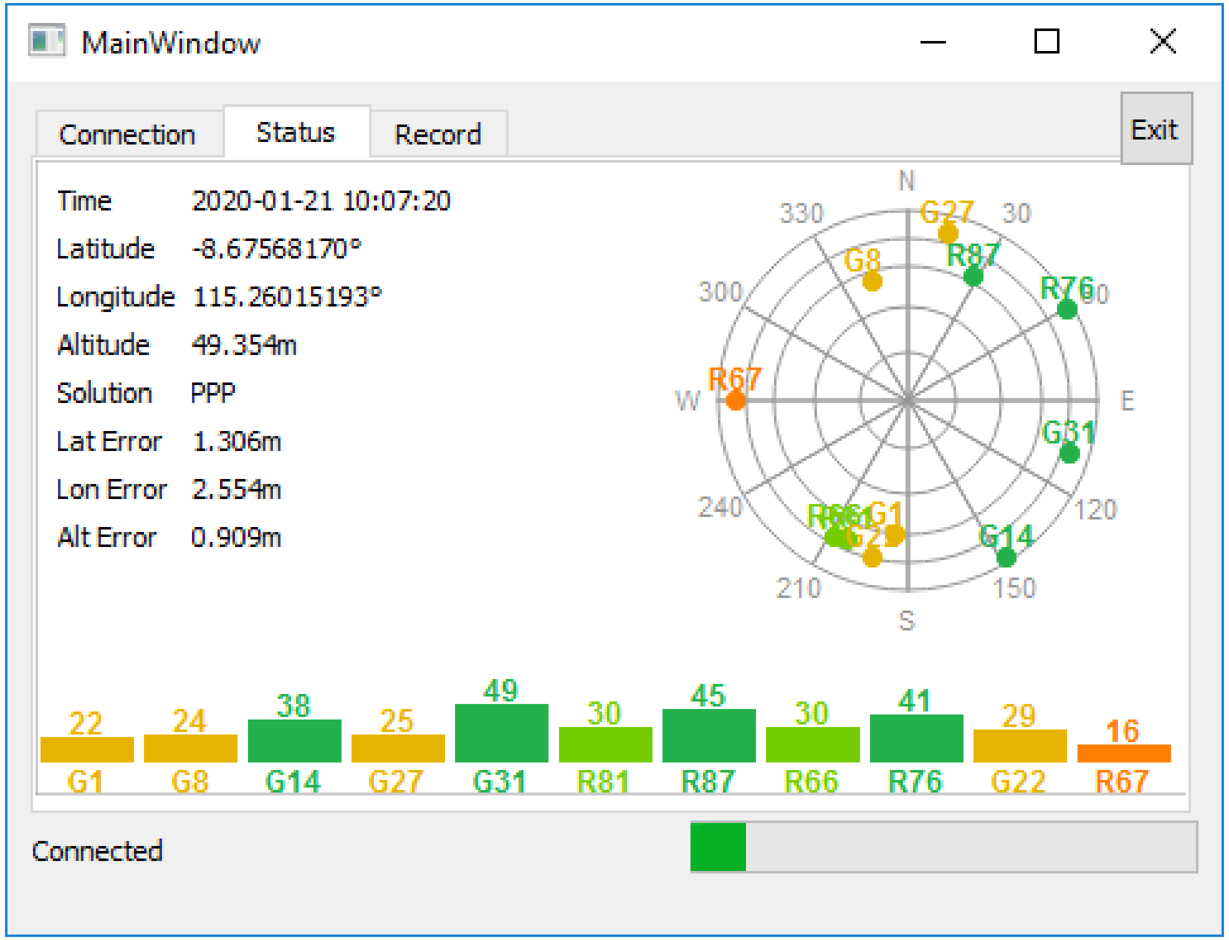
Type A: MAD-PI

MADOCA PPP based on RaspberryPi / Dual Frequency Receiver + MADOCA Decoder



Type B: MAD-WIN





The position accuracy improves to cm (10 – 30 cm) level after initialization time of about 15min.

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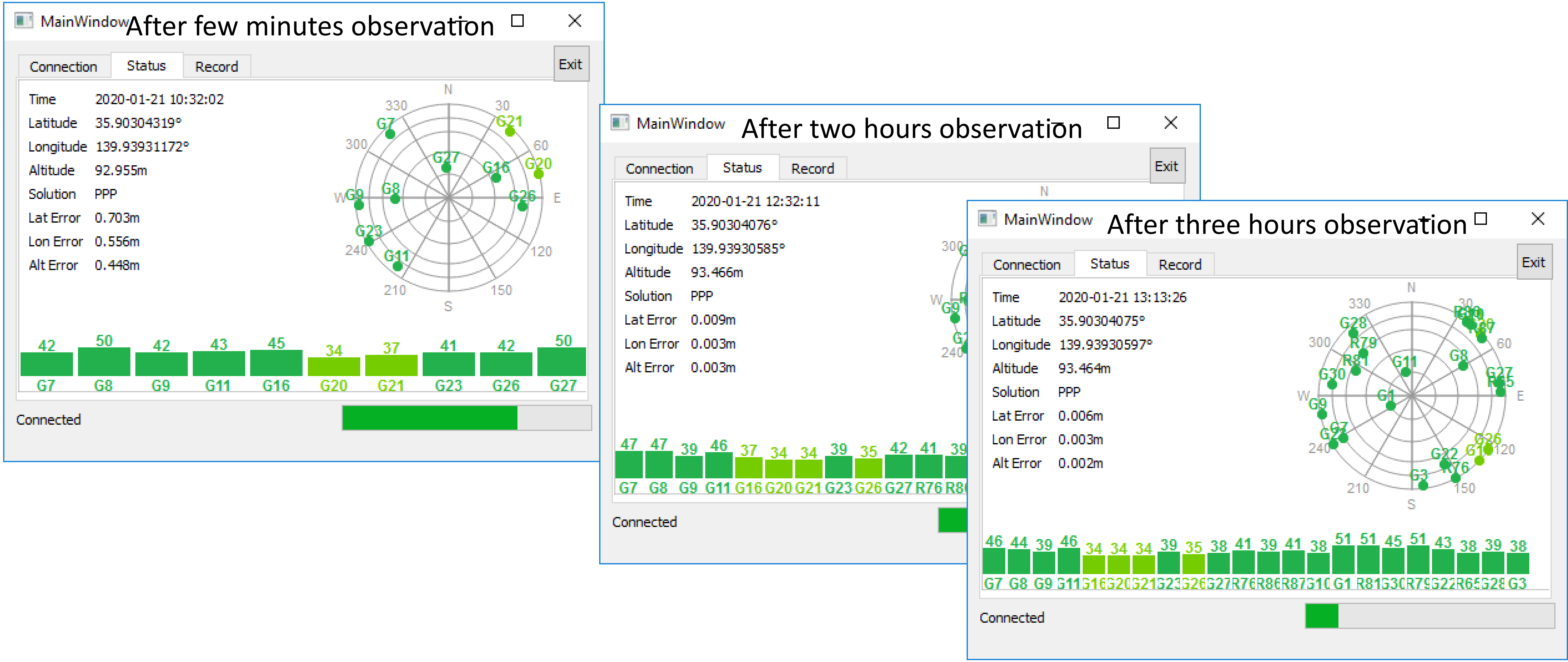
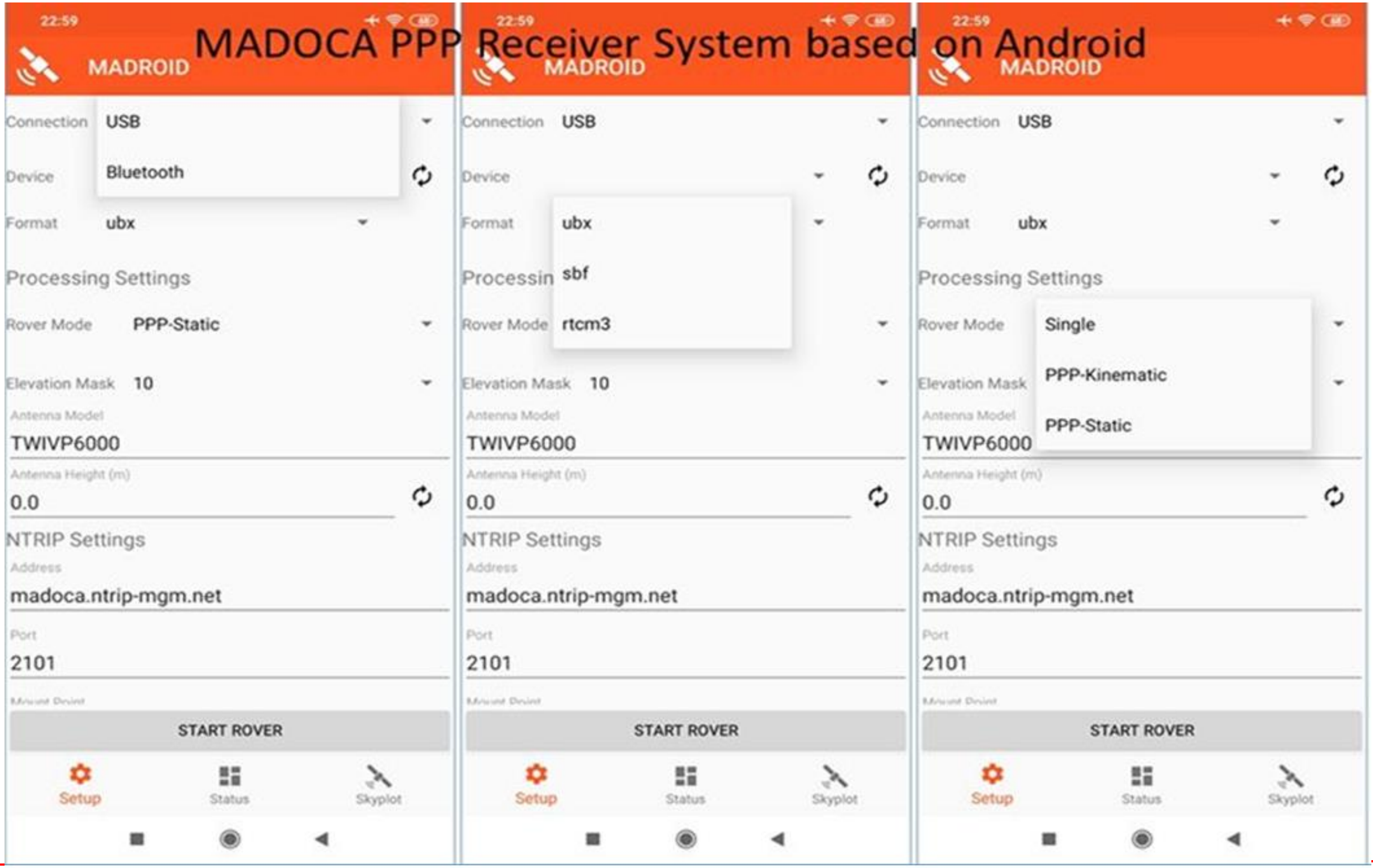
Type B: MAD-WIN

Receiver: Online receiver access in Kashiwa / Correction Data: MADOCA Receiver in Bali



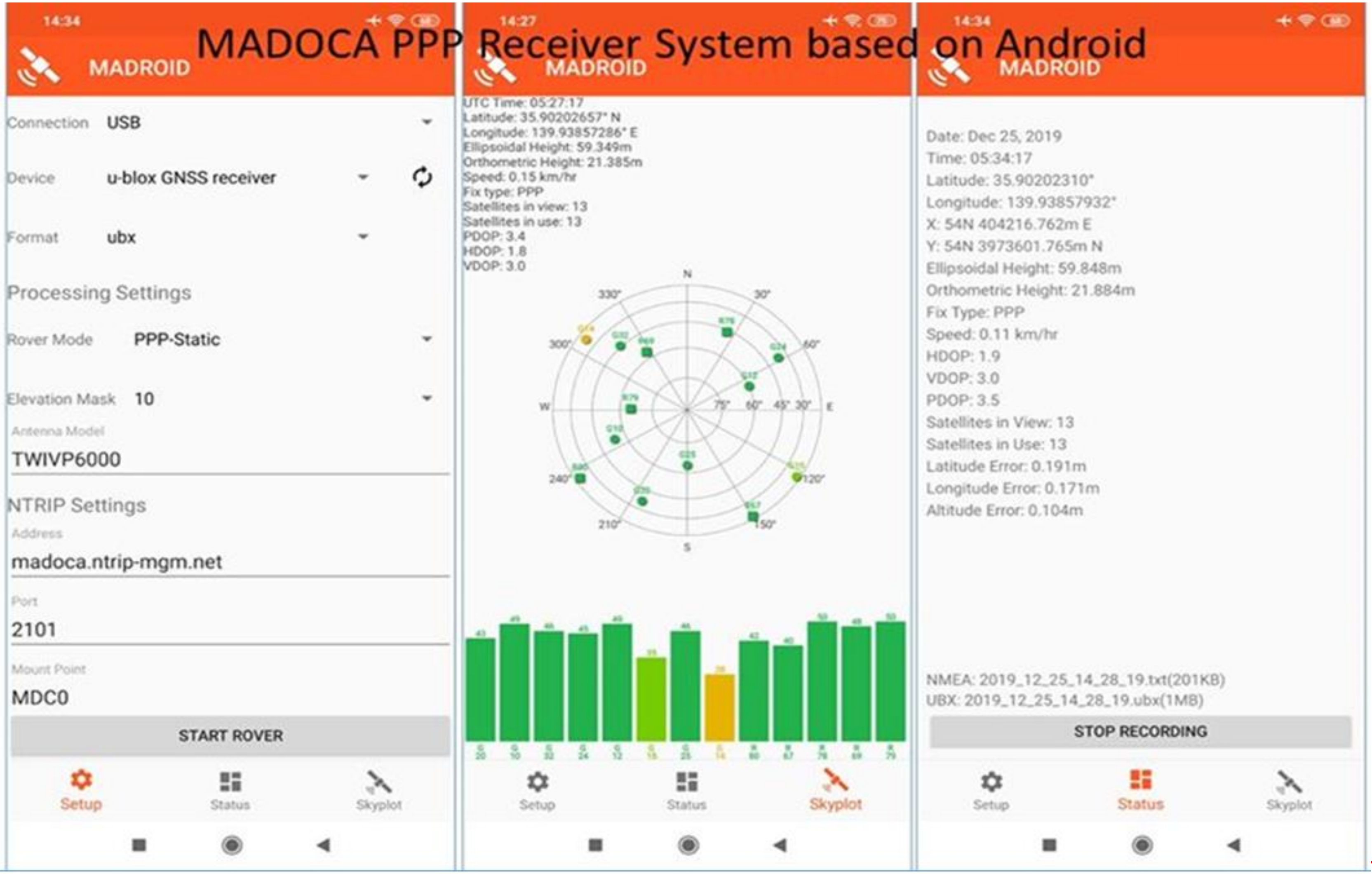
Type C: MADROID / MADOCA PPP based on Android

Dual Frequency Receiver + Online MADOCA Data



Type C: MADROID / MADOCA PPP based on Android

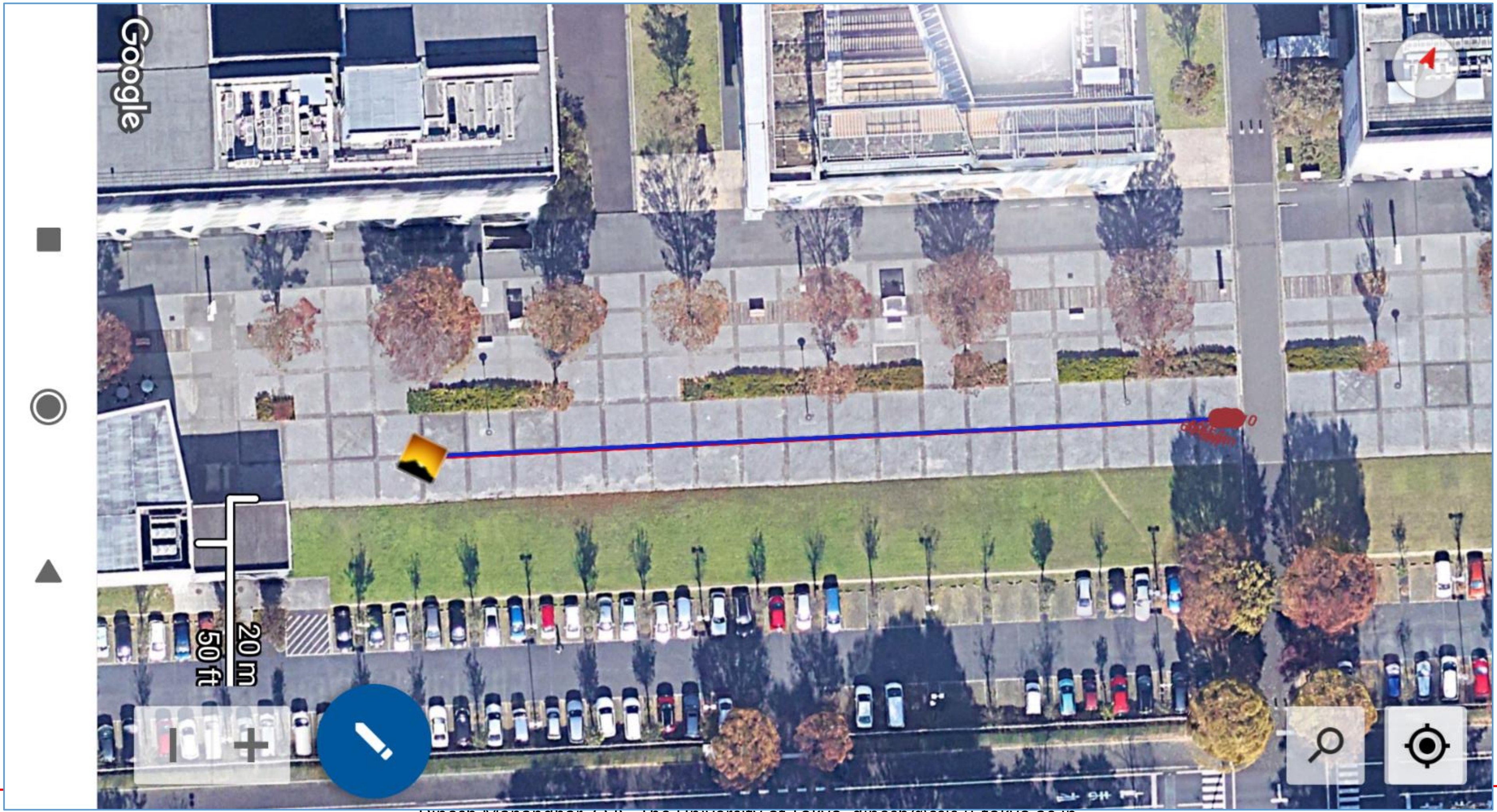
Dual Frequency Receiver + Online MADOCA Data



MADOCA PPP Receiver System based on Android

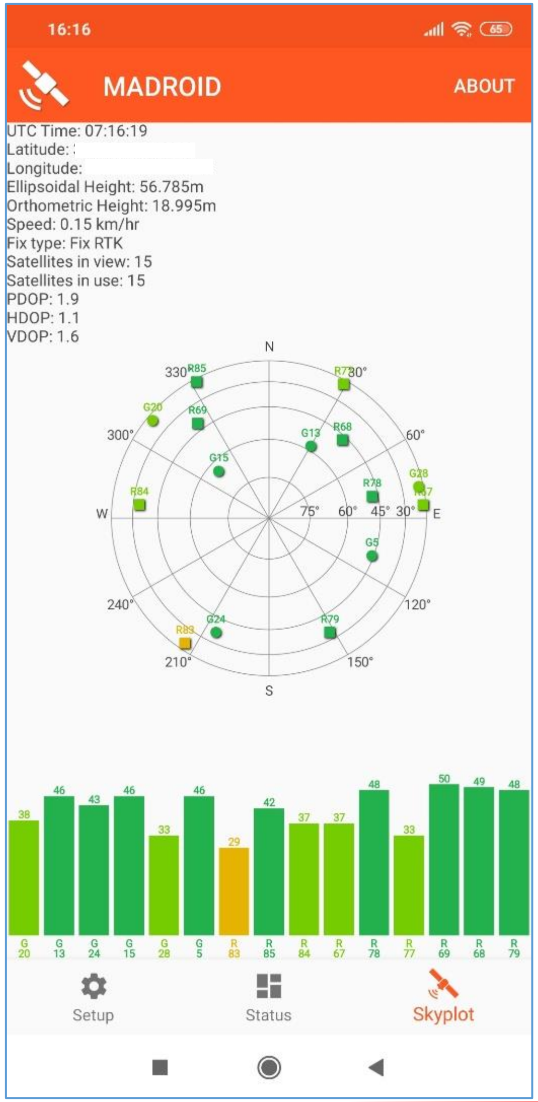
Position Data from MADOCA PPP

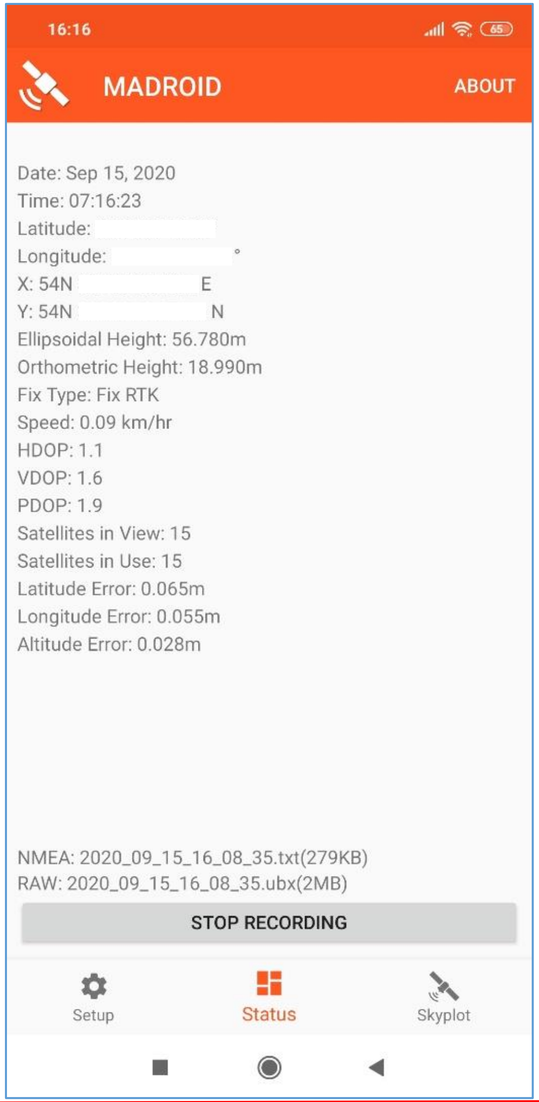
We walked straight along the concrete tiles (30cmx30cm) and
PPP results showed perfect straight line. Accuracy is about 15cm.
Receiver : F9 + Online MADOCA Correction Data



MADROID PPP-AR with Local Correction Data

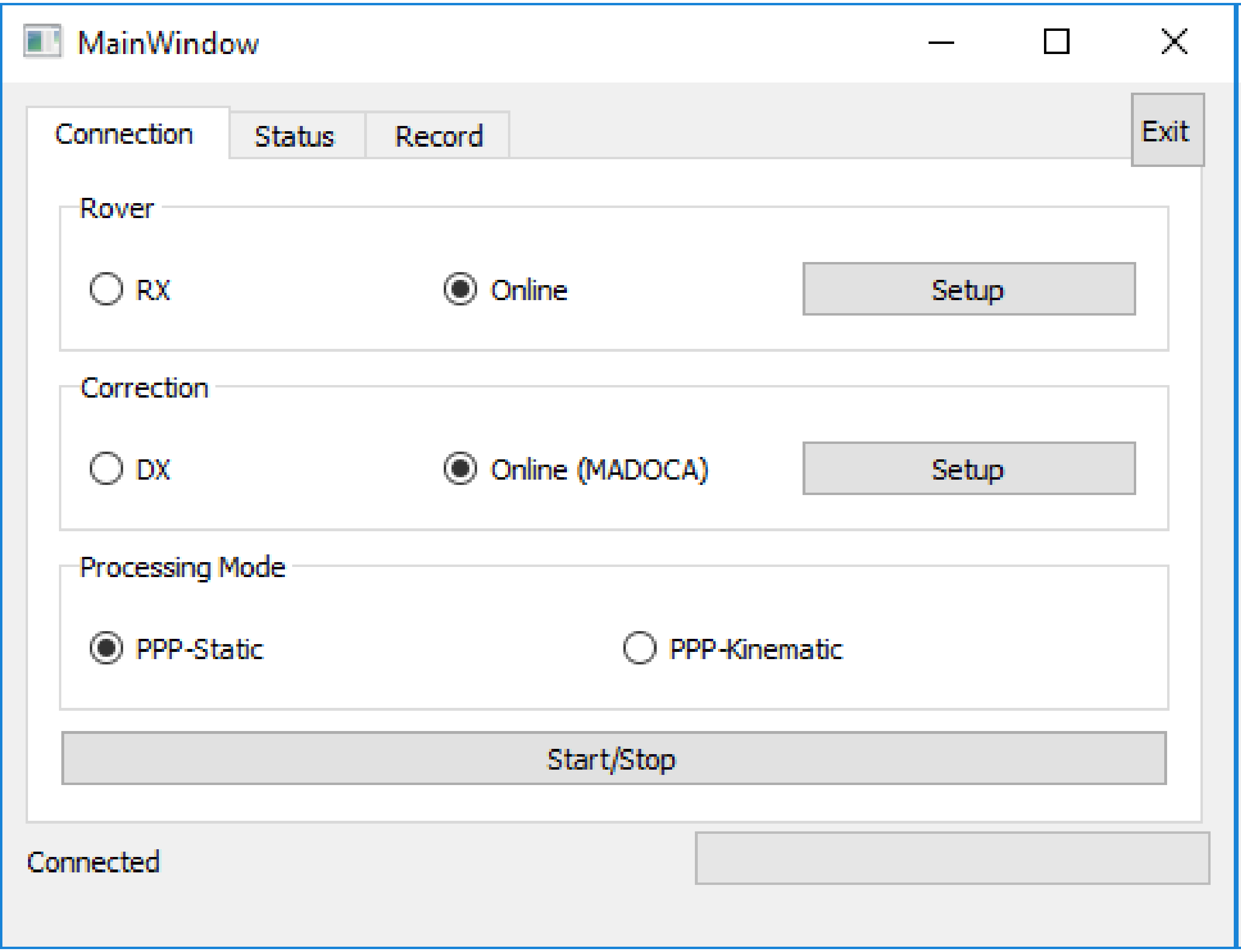
Test Area	: Tokyo
GNSS Receiver Used	: u-blox F9P
MADOCA Correction Data	: u-blox D9
	(Received online via NTRIP Server)
Local Correction Data	: Service provided by GPAS
	(Received online via NTRIP Server)

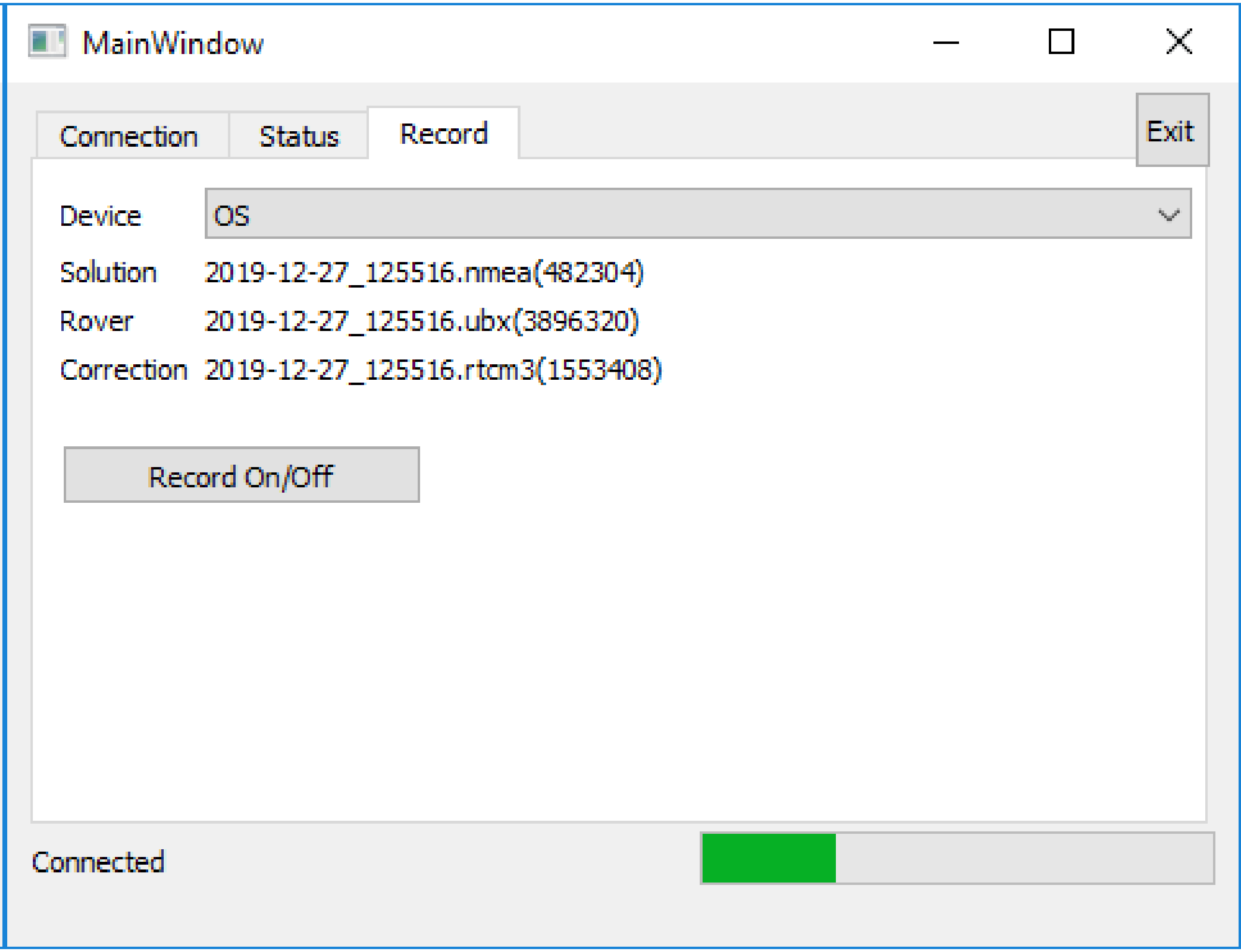


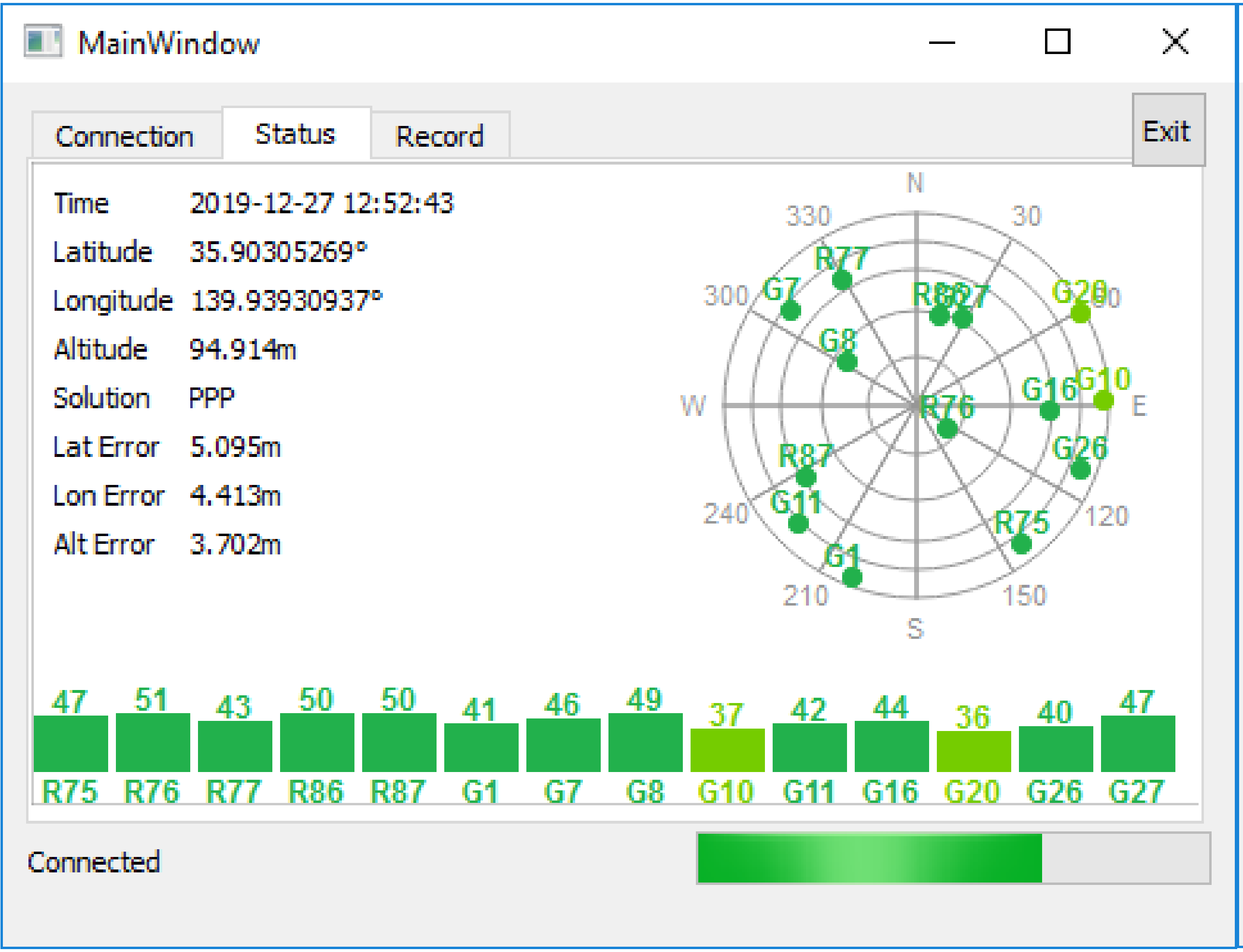


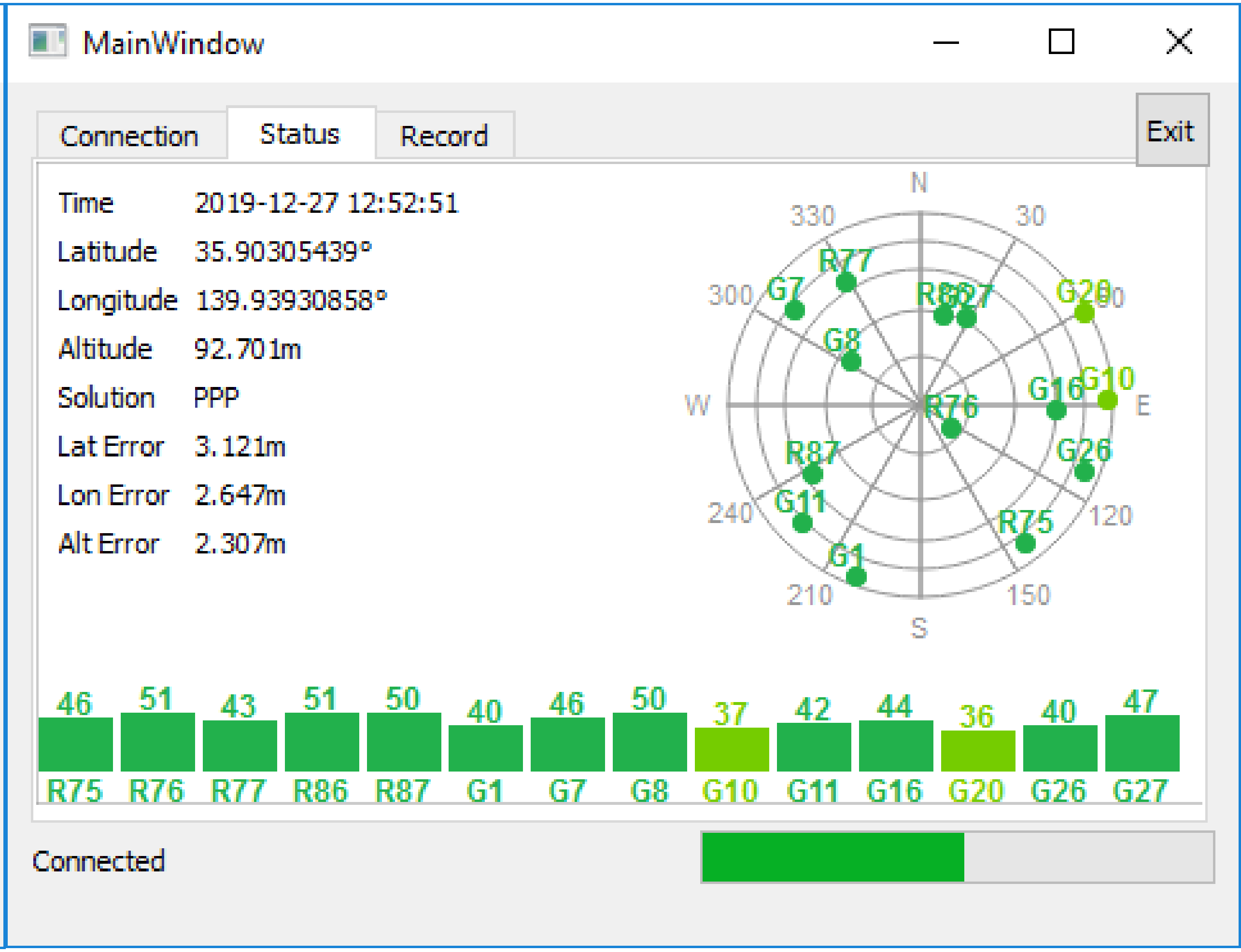
Output from MADOCA PPP
Device: RaspberryPi

MADOCA PPP Observation






MainWindow
Connection
Status
Record
Exit
Time 2019-12-27 12:52:43
Latitude 35.90305269°
Longitude 139.93930937°
Altitude 94.914m
Solution PPP
Lat Error 5.095m
Lon Error 4.413m
Alt Error 3.702m
N
S
E
W
47 51 43 50 50 41 46 49 37 42 44 36 40 47
R75 R76 R77 R86 R87 G1 G7 G8 G10 G11 G16 G20 G26 G27
Connected


MainWindow
Connection
Status
Record
Exit
Time 2019-12-27 12:52:51
Latitude 35.90305439°
Longitude 139.93930858°
Altitude 92.701m
Solution PPP
Lat Error 3.121m
Lon Error 2.647m
Alt Error 2.307m
N
S
E
W
46 51 43 51 50 40 46 50 37 42 44 36 40 47
R75 R76 R77 R86 R87 G1 G7 G8 G10 G11 G16 G20 G26 G27
Connected

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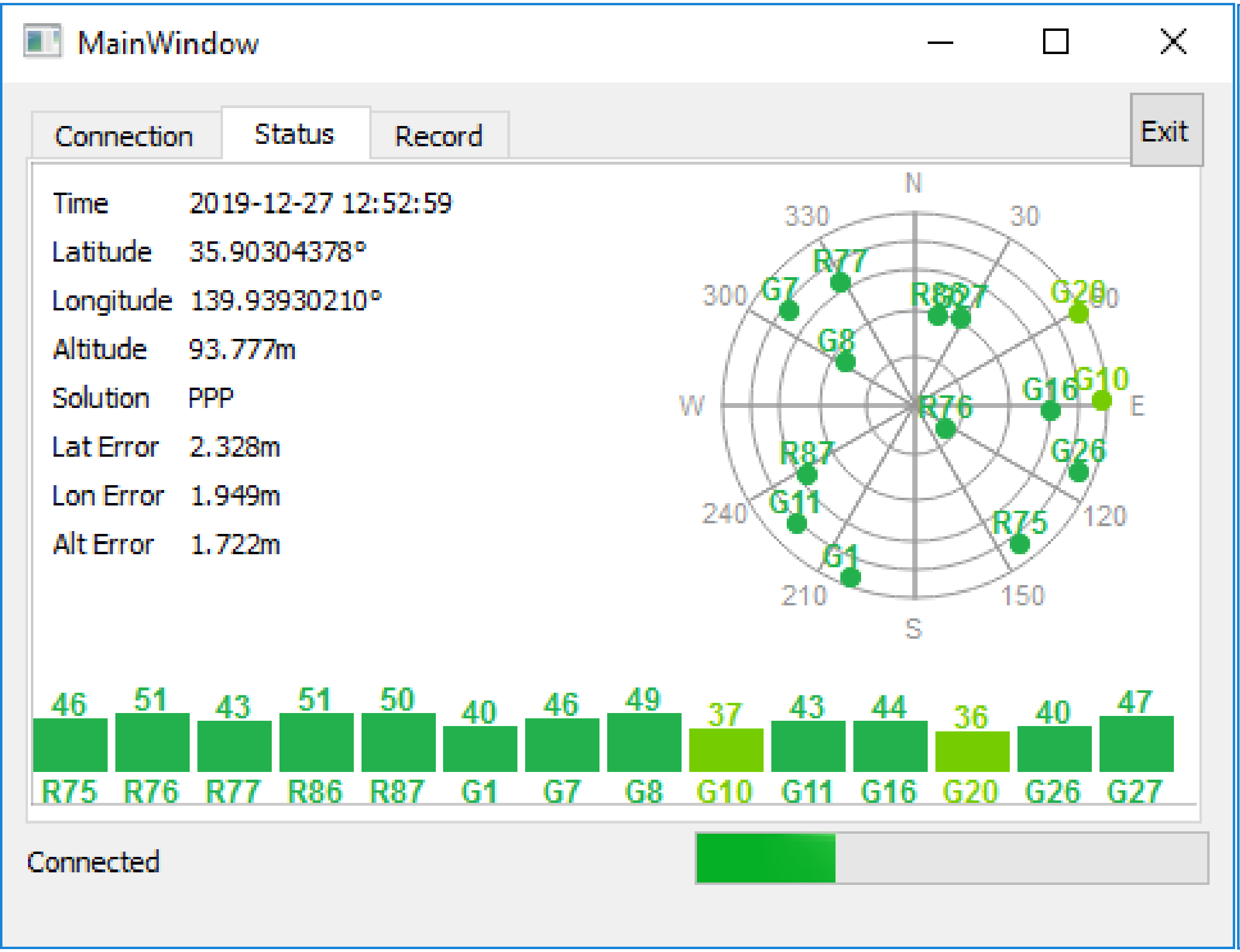
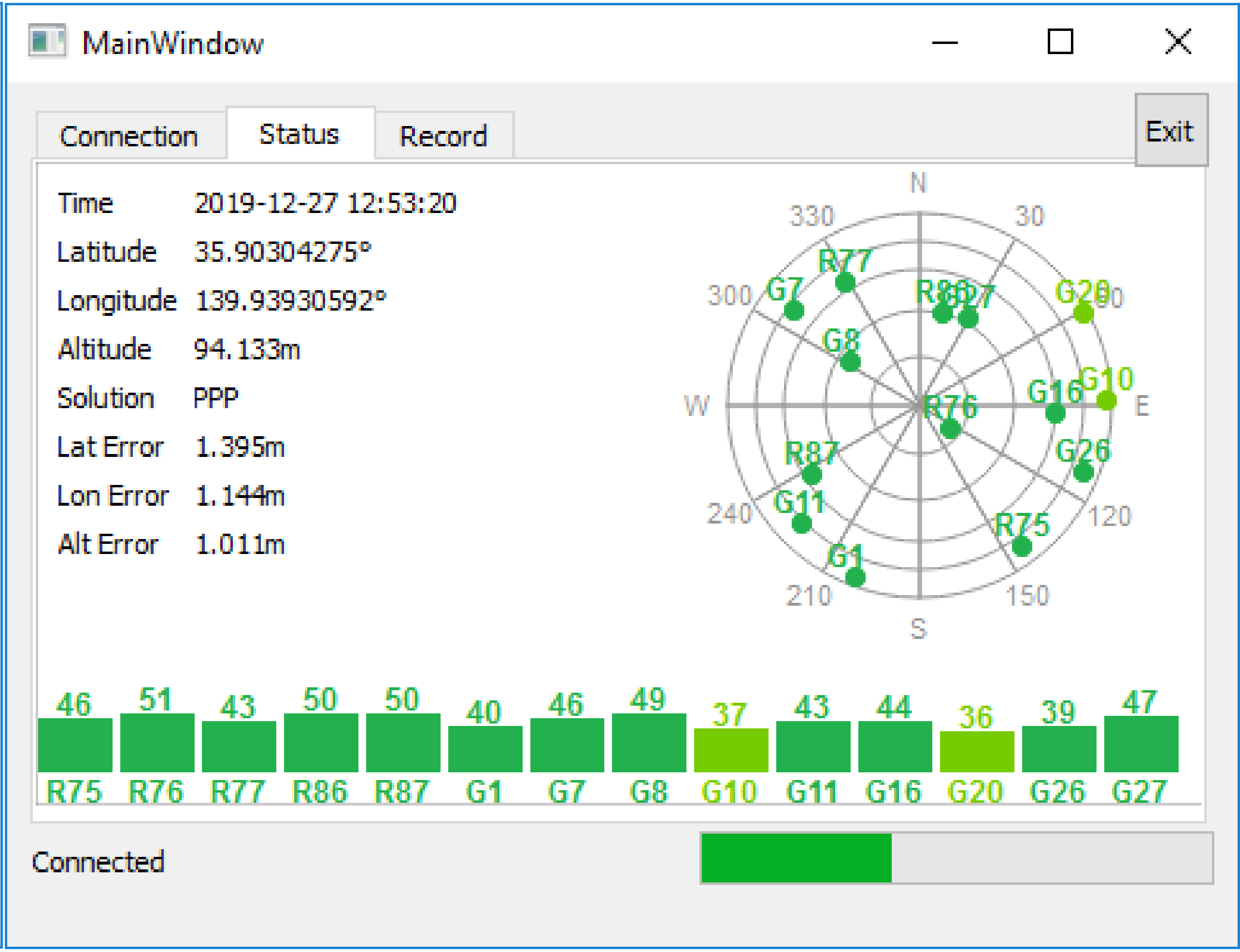
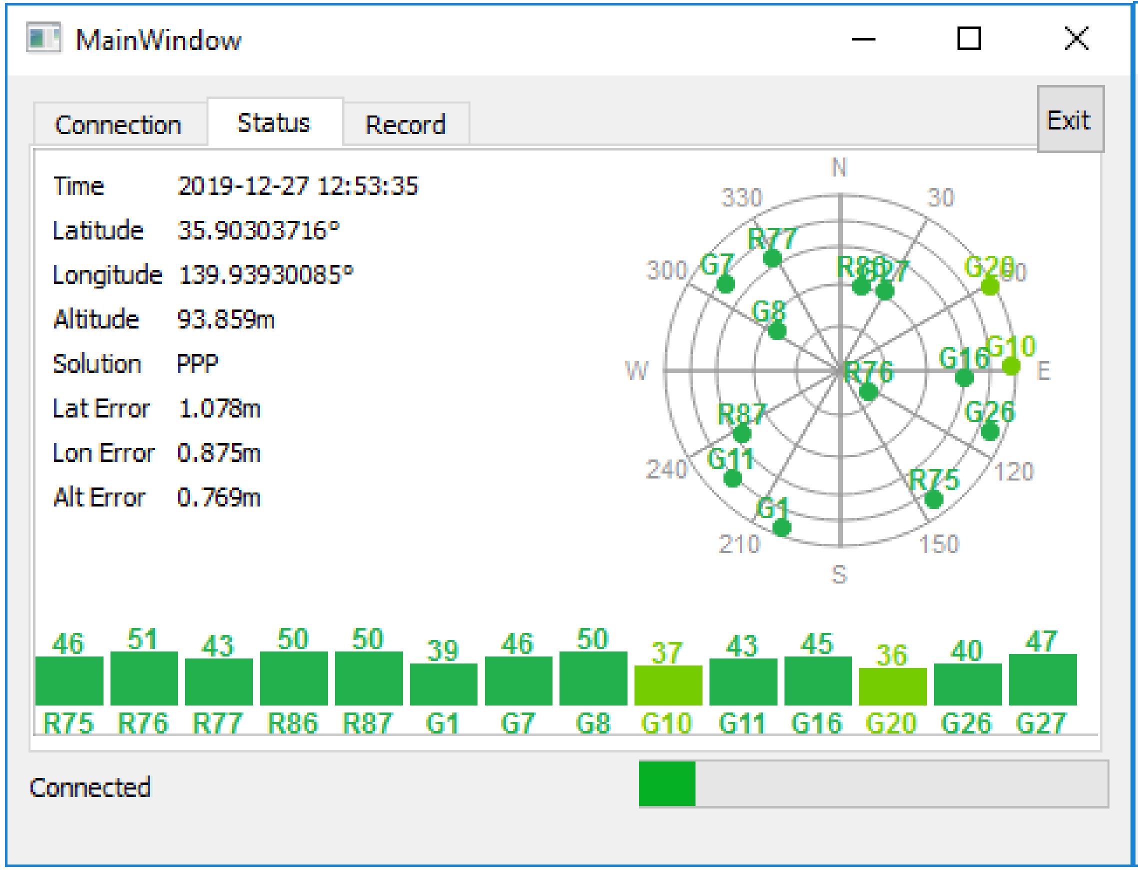
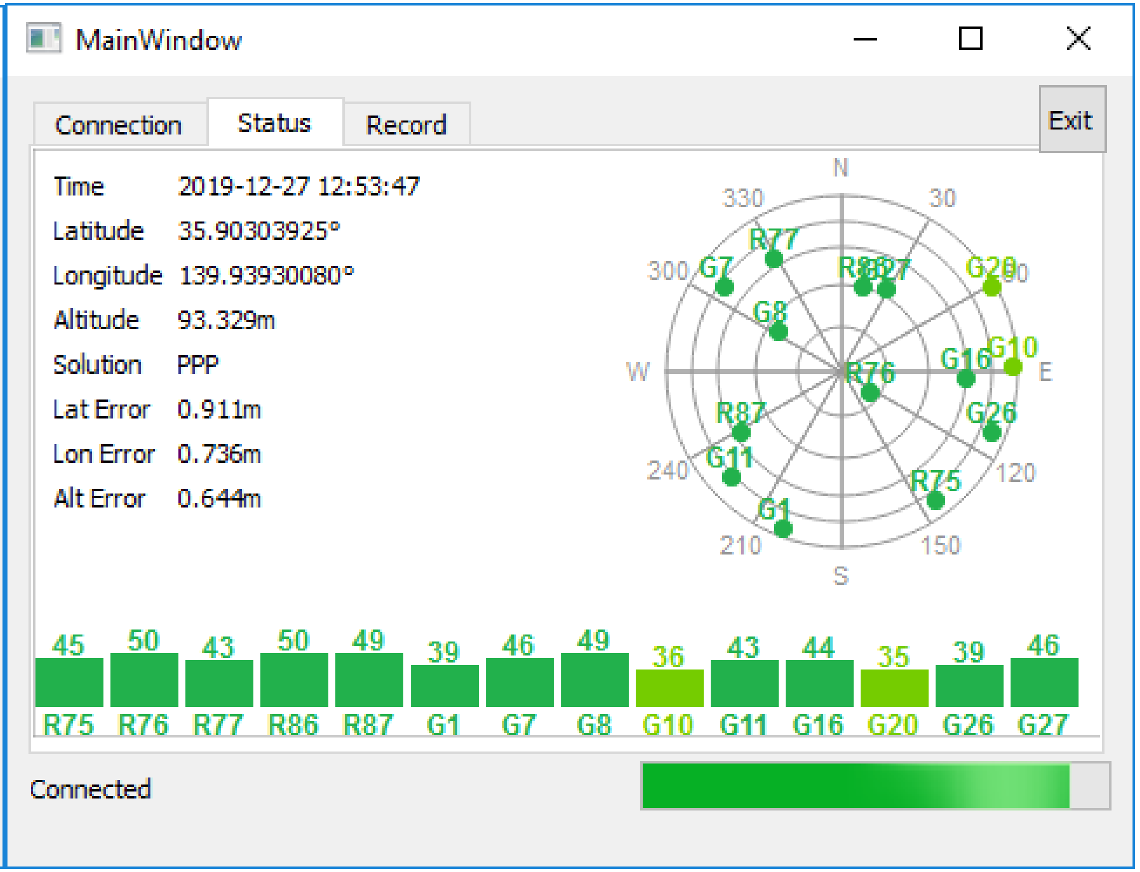
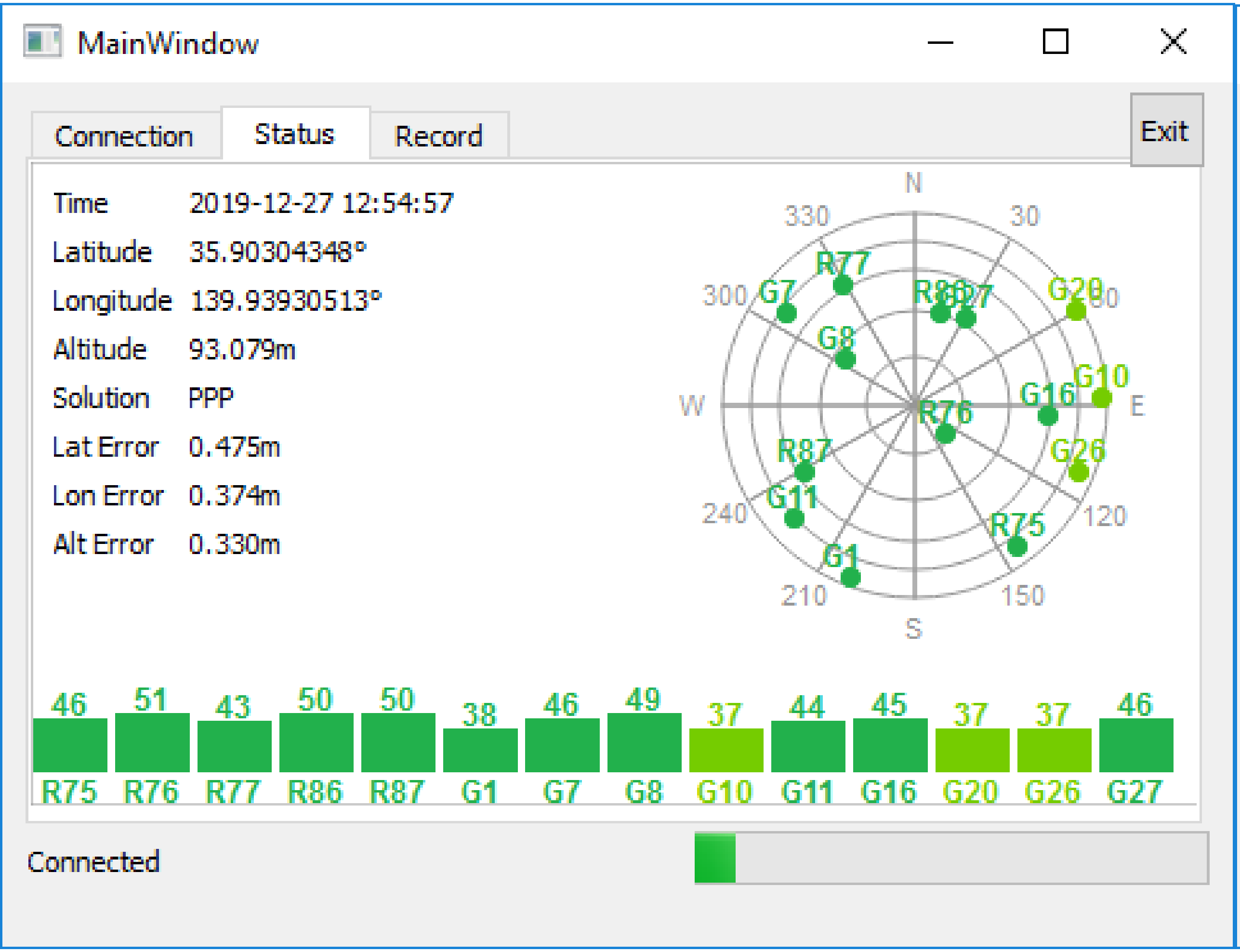
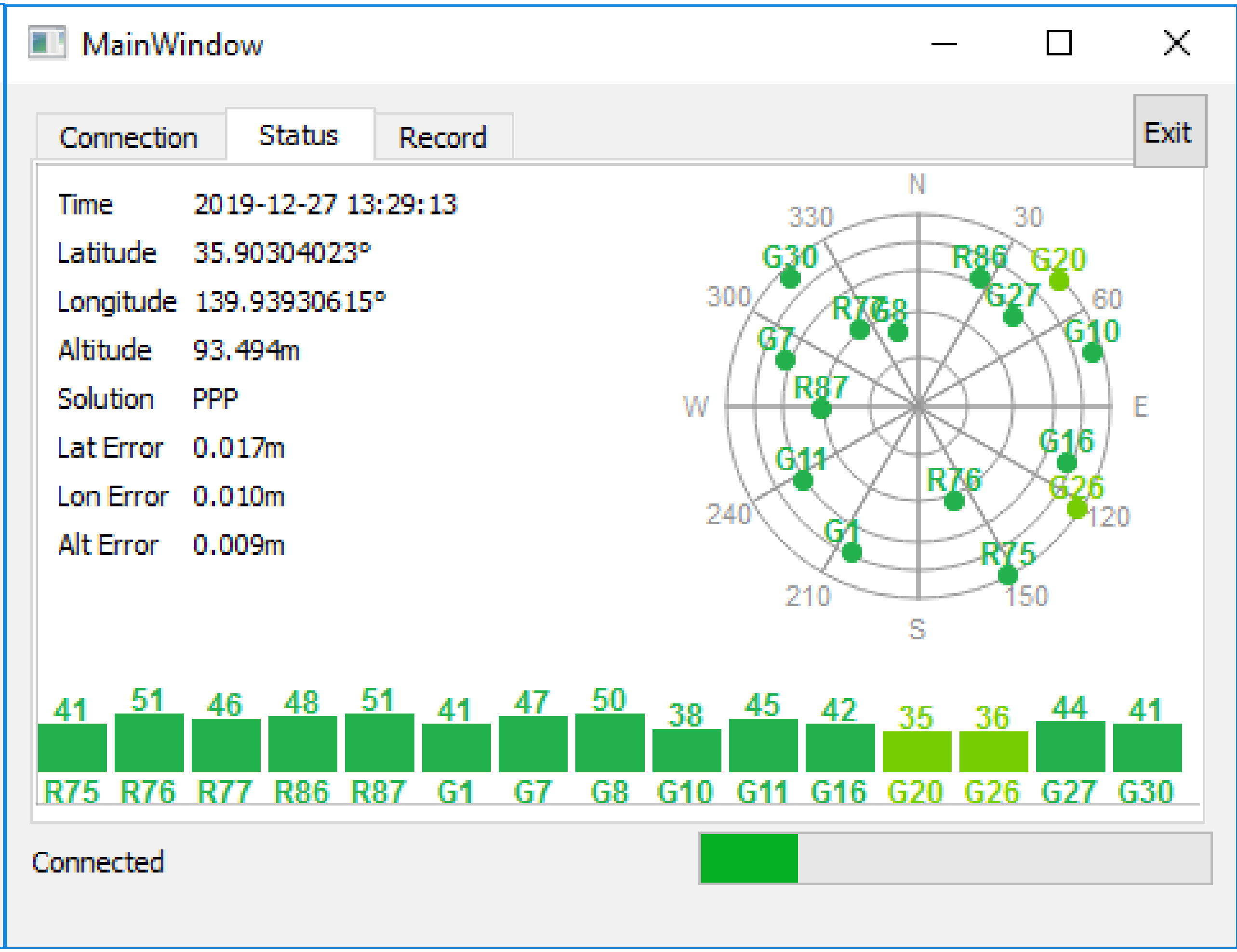




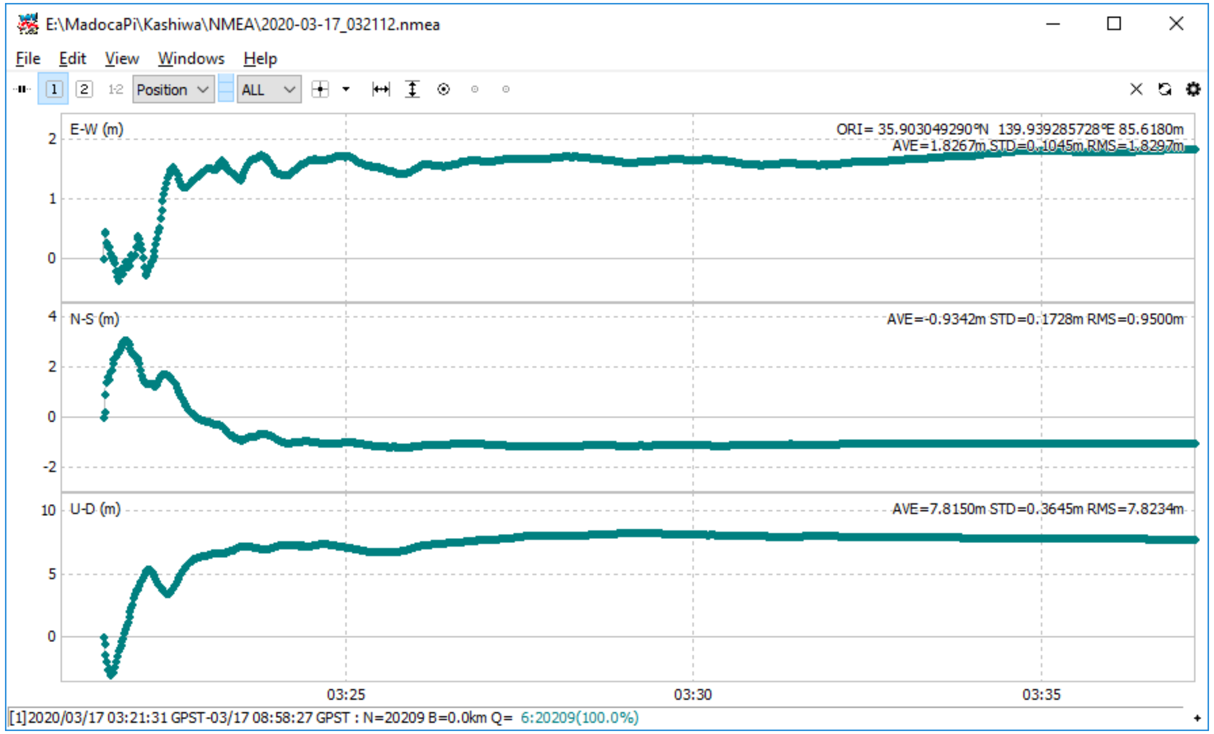

MainWindow
Connection
Status
Record
Exit
Time 2019-12-27 12:53:35
Latitude 35.90303716°
Longitude 139.93930085°
Altitude 93.859m
Solution PPP
Lat Error 1.078m
Lon Error 0.875m
Alt Error 0.769m
N
S
E
W
46 51 43 50 50 39 46 50 37 43 45 36 40 47
R75 R76 R77 R86 R87 G1 G7 G8 G10 G11 G16 G20 G26 G27
Connected


MainWindow
Connection
Status
Record
Exit
Time 2019-12-27 12:53:47
Latitude 35.90303925°
Longitude 139.93930080°
Altitude 93.329m
Solution PPP
Lat Error 0.911m
Lon Error 0.736m
Alt Error 0.644m
N
S
E
W
45 50 43 50 49 39 46 49 36 43 44 35 39 46
R75 R76 R77 R86 R87 G1 G7 G8 G10 G11 G16 G20 G26 G27
Connected


MainWindow
Connection
Status
Record
Exit
Time 2019-12-27 12:54:57
Latitude 35.90304348°
Longitude 139.93930513°
Altitude 93.079m
Solution PPP
Lat Error 0.475m
Lon Error 0.374m
Alt Error 0.330m
46 51 43 50 50 38 46 49 37 44 45 37 37 46
R75 R76 R77 R86 R87 G1 G7 G8 G10 G11 G16 G20 G26 G27
Connected

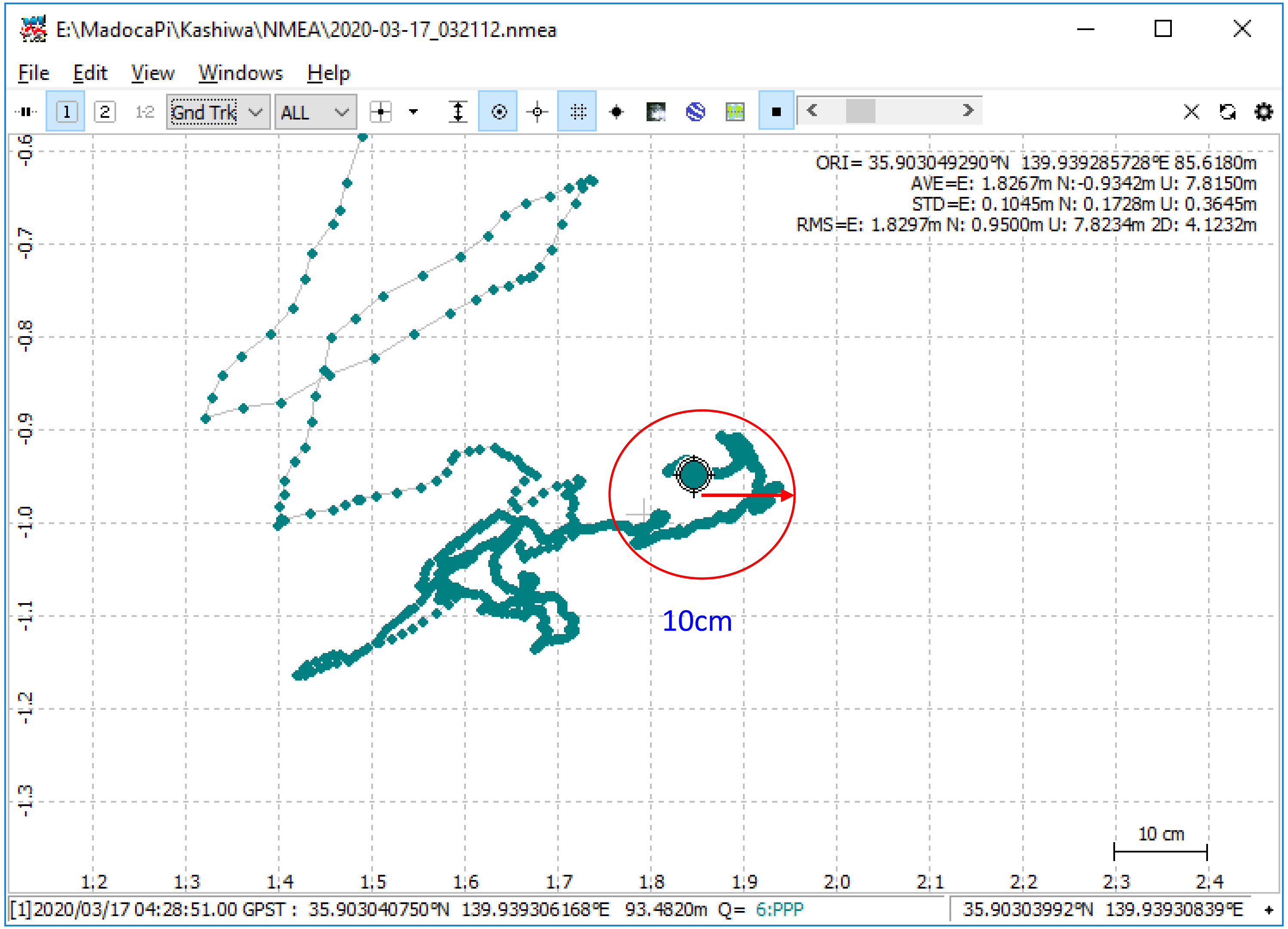

MainWindow
Connection
Status
Record
Exit
Time 2019-12-27 13:29:13
Latitude 35.90304023°
Longitude 139.93930615°
Altitude 93.494m
Solution PPP
Lat Error 0.017m
Lon Error 0.010m
Alt Error 0.009m
41 51 46 48 51 41 47 50 38 45 42 35 36 44 41
R75 R76 R77 R86 R87 G1 G7 G8 G10 G11 G16 G20 G26 G27 G30
Connected

MADOCA PPP at Kashiwa Campus



	Measured Values	True Values	Difference meter
LAT	35.90304079	35.90304065	-0.02
LON	139.93930587	139.93930614	0.03
Ht	93.446	93.463	0.02

MADOCA PPP at Kashiwa Campus



Part - B

Android GNSS Raw Data Measurement

New Tools for Android GNSS Measurements

GSA Raw Measurements Workshop, Prague, 26 June 2019

v1.01

Frank van Diggelen

Google

Many slides in this presentation are based on the presentation document from [Dr. Frank van Diggelen]

Raw Measurement : Lecture Notes by Dr. Frank van Diggelen, Google Inc.

1. Raw GNSS 2. Logging Tools 3. Pseudorange 4. Analysis Tools 5. Hands-on Exercises 6. Future: Apps and Research

Location APIs, Measurement APIs

aka *Google Play Services* aka *Google Mobile Service*
Most Android phones have this (not China)

Location APIs, android.gms.location
- Places
- Geofencing
- Fused Location Provider (FLP)
- Fit
- Activity Recognition
- Nearby

All Android phones have this

Measurement/Sensor APIs, in android.location
- Location
- GnssMeasurement
- GnssClock

GNSS Raw Measurements
All phones with:
GNSS chips build date ≥ 2016
OS ≥ Android N (Nougat)

 4

Download the Lecture Notes from https://home.csis.u-tokyo.ac.jp/~dinesh/GNSS_Raw.htm

Developers | Platform | Android Studio | Google Play | Jetpack | Kotlin | Docs | News | Search | LANGUAGE | SIGN IN

Documentation

OVERVIEW | GUIDES | REFERENCE | SAMPLES | DESIGN & QUALITY

- Audio & video
- Background tasks
- App data & files
- User data & identity
- User location
- Touch & input
- CameraX
- Camera
- Sensors
  - Overview
  - Sensors overview
  - Motion sensors
  - Position sensors
  - Environment sensors
  - Raw GNSS measurements
- Connectivity
- Renderscript
- Web-based content
- Android App Bundles

Android Developers > Docs > Guides

Raw GNSS Measurements

The Android Framework provides access to raw GNSS measurements on several Android devices.

Note: Google has released version 2.6.3.0 of the GNSS Analysis App. For more information, see the GNSS Analysis app v2.6.3.0 release notes.

This article lists Android devices that support raw GNSS measurements as well as tools to log and analyze GNSS data. You can find the tools in the GPS Measurement Tools repo on GitHub, which includes the GNSS Logger APK and the GNSS Analysis app for Linux, Windows, macOS, and the Installation and User Manual.

Original equipment manufacturers (OEMs), developers, and researchers can make use of the tools in this page to test new phone designs, validate functionality, develop new algorithms, evaluate improvements to the GNSS system

Contents

https://developer.android.com/guide/topics/sensors/gnss

GNSS Raw Data Compatible Smart-Phones

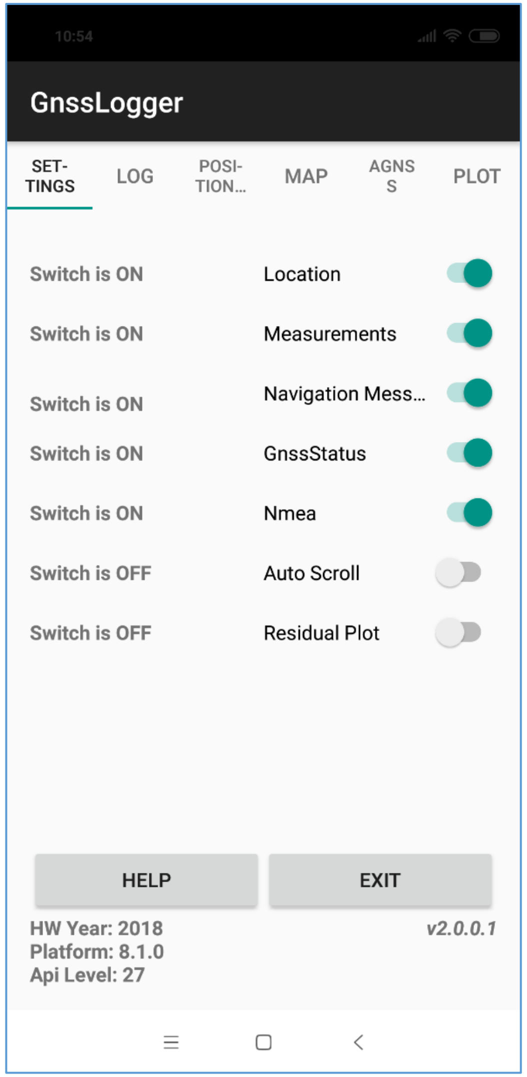
						Raw Data output used in System Score					Satellite Systems used in System Score					
S. No.	Model	Android version	System Score Max: 6 (D)	Function Score Max: 5 (E)	Total Score (D + E)	AGC	NAV MSG	Accumulated delta range	HW clock	L5 Support	GPS	GLO	GAL	BDS	QZSS	SBAS
4	Xiaomi Mi 8	8.1	5	4	9	no	yes	yes	yes	yes	yes	yes	yes	yes	yes	no
31	Samsung S8	7	5	3	8	no	yes	yes	yes	no	yes	yes	yes	yes	yes	no
33	Huawei P10	7	5	3	8	no	yes	yes	yes	no	yes	yes	yes	yes	yes	no
42	Huawei Mate 20 X	9	4	4	8	no	yes	yes	yes	yes	yes	yes	yes	no	yes	no
19	Google Pixel 2 XL	8	5	2	7	yes	no	no	yes	no	yes	yes	yes	yes	yes	no
20	Google Pixel 2	8	5	2	7	yes	no	no	yes	no	yes	yes	yes	yes	yes	no
22	Samsung Note 8	7.1	4	3	7	no	yes	yes	yes	no	yes	yes	yes	yes	no	no
1	Pixel 3 XL	9	4	3	7	yes	no	yes	yes	no	yes	yes	yes	yes	no	no
2	Pixel 3	9	4	3	7	yes	no	yes	yes	no	yes	yes	yes	yes	no	no
43	Huawei Mate 20 RS	9	4	3	7	no	no	yes	yes	yes	yes	yes	yes	yes	no	no
44	Huawei Mate 20 Pro	9	4	3	7	no	no	yes	yes	yes	yes	yes	yes	yes	no	no
45	Huawei Mate 20	9	4	3	7	no	no	yes	yes	yes	yes	yes	yes	yes	no	no
10	Huawei P20	8.1	3	3	6	no	yes	yes	yes	no	yes	yes	no	no	yes	no
11	Samsung Galaxy S9	8	3	3	6	no	yes	yes	yes	no	yes	yes	no	no	yes	no
18	Huawei Mate 10 Pro	8	3	3	6	no	yes	yes	yes	no	yes	yes	no	no	yes	no

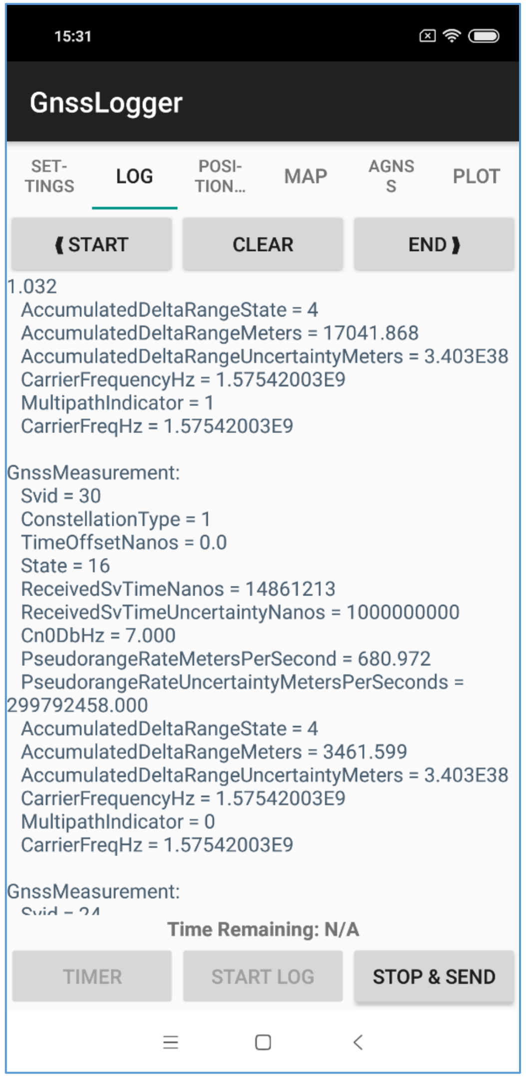
Check ➔ https://developer.android.com/guide/topics/sensors/gnss for Latest Updates

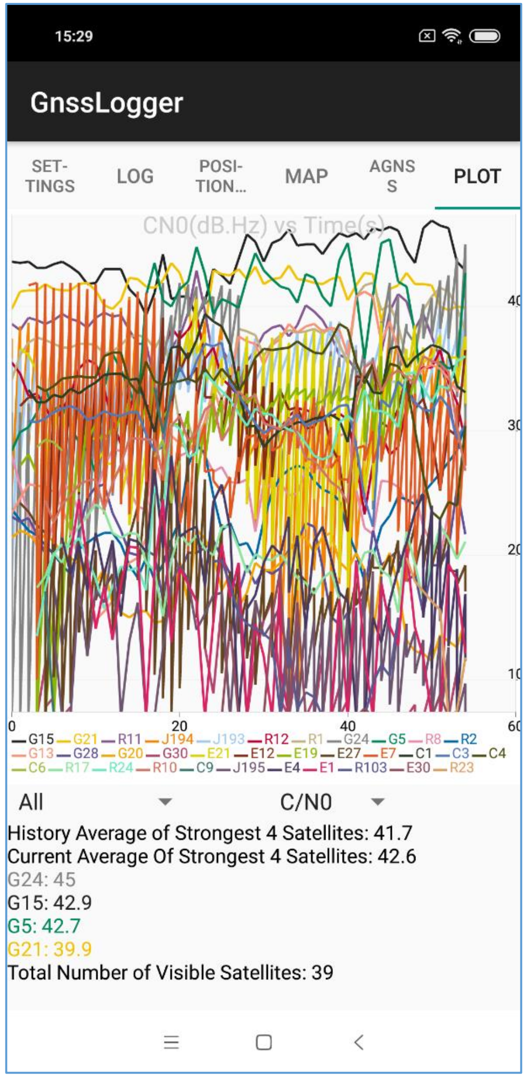
Android Raw Data Logging APPs

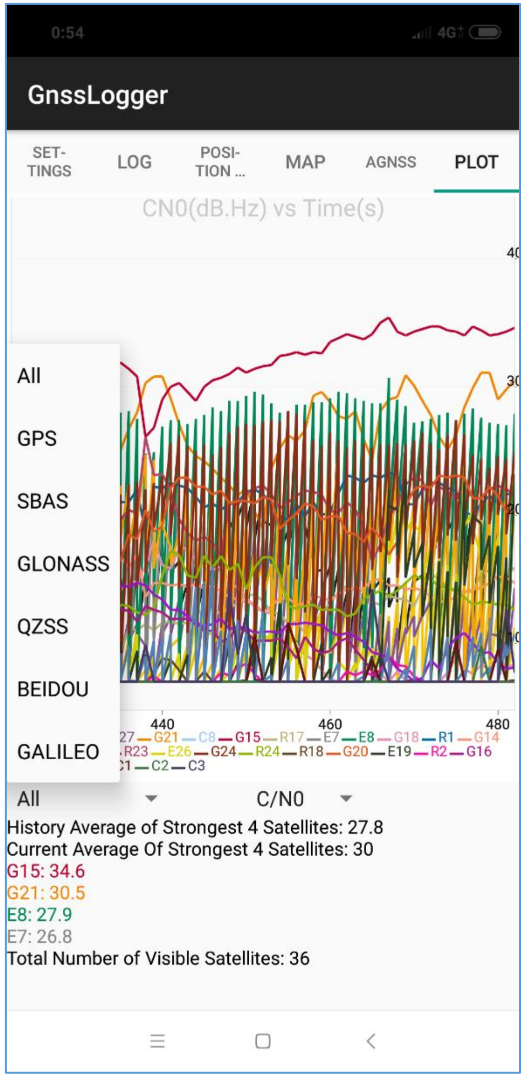
- GNSS Logger
  - Logs Raw Data
  - Some devices also output AGC and Navigation Bit Data
  - Multi Band Compatible
- Geo++ RINEX Logger
  - APP to generate RINEX Observation File
    - https://play.google.com/store/apps/details?id=de.geopp.rinexlogger&hl=en_US
    - Dual Frequency Compatible
- GNSS Compare
  - Compares position accuracy from each type of GPS and GALILEO Signal
    - https://play.google.com/store/apps/details?id=com.galfins.gnss_compare&hl=en_US

Android Raw Data Logging Tool – 1: GnssLogger









GNSS Raw Data Output Format from Smart Phone Device

- #
- # Header Description:
- # Version: v2.0.0.1 Platform: 9 Manufacturer: Xiaomi Model: MI 8
- **# Raw**,
  - ElapsedRealtimeMillis,TimeNanos,LeapSecond,TimeUncertaintyNanos,FullBiasNanos,
  - BiasNanos,BiasUncertaintyNanos,DriftNanosPerSecond,DriftUncertaintyNanosPerSecond,
  - HardwareClockDiscontinuityCount,Svid,TimeOffsetNanos,State,ReceivedSvTimeNanos,
  - ReceivedSvTimeUncertaintyNanos,Cn0DbHz,PseudorangeRateMetersPerSecond,
  - PseudorangeRateUncertaintyMetersPerSecond,AccumulatedDeltaRangeState,
  - AccumulatedDeltaRangeMeters,AccumulatedDeltaRangeUncertaintyMeters,CarrierFrequencyHz,
  - CarrierCycles,CarrierPhase,CarrierPhaseUncertainty,MultipathIndicator,
  - SnrInDb,ConstellationType,AgcDb,CarrierFrequencyHz
- # Fix,
  - Provider,Latitude,Longitude,Altitude,Speed,Accuracy,(UTC)TimeInMs
- # Nav,
  - Svid,Type,Status,MessageId,Sub-messageId,Data(Bytes)

GnssLogger: Sample GNSS Raw Data

Raw,148210058,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,24,0.0,51,16023402,13,38.61924362182617,-448.3204760268297,0.0021302644163370132,1,-2484.2876523853806,0.09621196860735094,1.57542003E9,,,,0,,1,,1.57542003E9
Raw,148210058,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,24,0.0,16,16023363,1000000000,22.01333236694336,-448.7947882361932,2.99792458E8,6,-54362.39162390184,3.4028234663852886E38,1.17645005E9,,,,0,,1,,1.17645005E9
Raw,148210059,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,2,0.0,99,448838468,42,33.2121467590332,-514.7820368047455,0.4567280495416781,4,-2821.165958154149,3.4028234663852886E38,1.59975002E9,,,,0,,3,,1.59975002E9
Raw,148210059,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,12,0.0,99,451783264,33,36.38795852661133,-789.8168953823033,0.31444507671593813,4,-3649.9399078027736,3.4028234663852886E38,1.60143744E9,,,,0,,3,,1.60143744E9
Raw,148210060,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,11,0.0,99,459913670,33,36.715248107910156,-352.6647914612738,0.0026083579286932945,1,-2248.5336107033927,0.0013041789643466473,1.602E9,,,,0,,3,,1.602E9
Raw,148210060,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,1,0.0,17,720287,71,26.745431900024414,-150.53345126992713,0.749486332694286,4,-982.5725209813795,3.4028234663852886E38,1.60256256E9,,,,1,,3,,1.60256256E9
Raw,148210060,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,24,0.0,99,451325376,47,31.866626739501953,540.7229232612153,0.004294544458389282,1,2792.0530589872405,0.002147272229194641,1.60312499E9,,,,0,,3,,1.60312499E9
Raw,148210061,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,23,0.0,17,163750,51,30.871082305908203,751.2325553423079,0.561522050942072,4,3454.136294113628,3.4028234663852886E38,1.60368755E9,,,,0,,3,,1.60368755E9
Raw,148210061,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,17,0.0,99,450599950,39,34.2637939453125,6.408111582737082,0.4097535710026252,4,42.03919027799001,3.4028234663852886E38,1.60424998E9,,,,0,,3,,1.60424998E9
Raw,148210061,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,8,0.0,17,490263,73,26.511377334594727,305.8143842387426,0.7594304219231991,6,1528.659101239677,3.4028234663852886E38,1.60537498E9,,,,0,,3,,1.60537498E9
Raw,148210062,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,194,0.0,17,631661,13,38.51543045043945,39.9065635909258,0.002155878348276019,1,221.32303678571114,0.09622477557332045,1.57542003E9,,,,0,,4,,1.57542003E9
Raw,148210062,6108000000,,,-1224572056418544947,0.0,1011000.0,,,0,195,0.0,17,934792,27,29.98949050903 32,63.56321905450875,0.6032179424598567,4,356.8051378882135,3.4028234663852886E38,1.57542003E9,,,,0,,4,,1.57542003E9

GnssLogger: Sample GNSS Raw Data, Header

Header Description:

Version: v2.0.0.1 Platform: 8.1.0 Manufacturer: Xiaomi Model: MI 8

##Raw,ElapsedRealtimeMillis,TimeNanos,LeapSecond,TimeUncertaintyNanos,FullBiasNanos,BiasNanos,BiasUncertaintyNanos,DriftNanosPerSecond,DriftUncertaintyNanosPerSecond,HardwareClockDiscontinuityCount,Svid,TimeOffsetNanos,State,ReceivedSvTimeNanos,ReceivedSvTimeUncertaintyNanos,Cn0DbHz,PseudorangeRateMetersPerSecond,PseudorangeRateUncertaintyMetersPerSecond,AccumulatedDeltaRangeState,AccumulatedDeltaRangeMeters,AccumulatedDeltaRangeUncertaintyMeters,CarrierFrequencyHz,CarrierCycles,CarrierPhase,CarrierPhaseUncertainty,MultipathIndicator,SnrInDb,ConstellationType,AgcDb,CarrierFrequencyHz

Fix,Provider,Latitude,Longitude,Altitude,Speed,Accuracy,(UTC)TimeInMs

Nav,Svid,Type,Status,MessageId,Sub-messageId,Data(Bytes)

#

GnssLogger: Sample GNSS Raw Data, Raw Data

Raw,678357857,828940000000,,,-1227744676059580169,0.0,5.135445098385752,,,0,2,0.0,16431,1504929579420,11,42.886016845703125,-253.99448677373584,0.0013739581918343902,1,-230928.61821755476,6.869790959171951E-4,1.57542003E9,,,,0,,1,,1.57542003E9

Raw,678357858,828940000000,,,-1227744676059580169,0.0,5.135445098385752,,,0,5,0.0,16431,1504926917641,12,42.14077587890625,-299.9095448909793,0.0014970472548156977,1,-262724.97200484236,7.485236274078488E-4,1.57542003E9,,,,0,,1,,1.57542003E9

Raw,678357858,828940000000,,,1227744676059580169,0.0,5.135445098385752,,,0,6,0.0,16,828010596684,1000000000,36.201961517333984,275.3221907272733,2.99792458E8,2,1144.5147370874038,3.4028234663852886E38,1.57542003E9,,,,0,,1,,1.57542003E9

Raw,678357858,828940000000,,,-1227744676059580169,0.0,5.135445098385752,,,0,7,0.0,16431,1504921150324,19,34.2019192626953,-228.16970128013054,0.003542420221492648,1,213920.67928652398,0.09691804650992876,1.57542003E9,,,,0,,1,,1.57542003E9

Raw,678357858,828940000000,,,1227744676059580169,0.0,5.135445098385752,,,0,9,0.0,16431,1504924621121,19,34.3650797241211,587.103966302386,0.003476497251540422 4,1,468139.7243548873,0.0017382486257702112,1.57542003E9,,,,0,,1,,1.57542003E9

Raw,678357858,828940000000,,,1227744676059580169,0.0,5.135445098385752,,,0,13,0.0,16431,1504920021810,19,34.32540512084961,666.6443721854594,0.0032926779240369797,1,561690.3480669406,0.0016463389620184898,1.57542003E9,,,,1,,1,,1.57542003E9

Raw,678357858,828940000000,,,1227744676059580169,0.0,5.135445098385752,,,0,17,0.0,16431,1504916630146,20,33.5648536682128 9,744.6819117466221,0.003812001552432776,1,619849.6424447118,0.0019060007762163877,1.57542003E9,,,,1,,1,,1.57542003E9

Raw,678357858,828940000000,,,1227744676059580169,0.0,5.135445098385752,,,0,19,0.0,16431,1504921921584,23,31.82895469665527 3,735.126564052538,0.004389062523841858,1,599416.7818672012,0.09734136766110336,1.57542003E9,,,,0,,1,,1.57542003E9

GnssLogger: Sample GNSS Raw Data, Position and NMEA

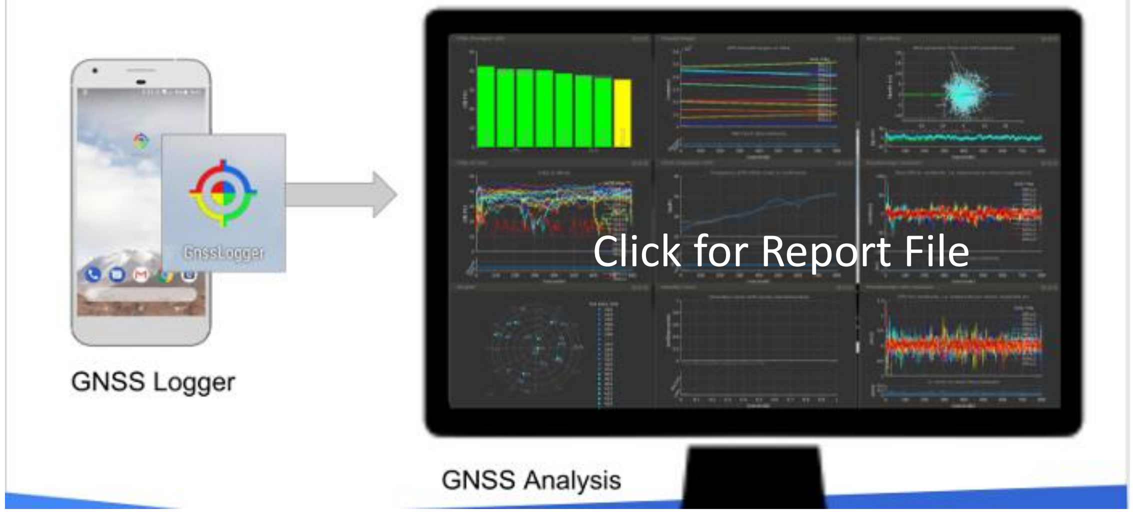
```
Fix,gps,35.850232,139.862279,37.854518,0.008482,4.000000,1543710718999
NMEA,$GPGSV,4,1,14,02,71,324,32,06,60,115,39,05,43,288,35,09,29,045,25*74
,1543710720204
NMEA,$GPGSV,4,2,14,07,26,093,34,19,24,182,23,30,22,130,27,13,22,207,23*72
,1543710720204
NMEA,$GPGSV,4,3,14,29,11,323,22,23,04,042,,17,03,169,*4A
,1543710720204
NMEA,$GPGSV,4,4,14,06,,,39,09,,,30,30,,,36,8*68
,1543710720204
NMEA,$GLGSV,2,1,07,83,80,264,26,68,65,326,32,82,37,165,23,69,32,254,33*6D
,1543710720204
NMEA,$GLGSV,2,2,07,67,28,037,24,84,26,329,19,77,08,073,11*5F
,1543710720204
NMEA,$QZGSV,2,1,05,01,83,285,31,03,41,201,33,02,07,171,22*53
,1543710720204
NMEA,$QZGSV,2,2,05,01,,,34,03,,,33,8*71
,1543710720205
NMEA,$BDGSV,1,1,02,203,38,224,23,202,20,250,*60
,1543710720205
NMEA,$GAGSV,2,1,08,104,75,259,30,112,61,159,30,119,42,045,29,109,22,236,25*6F
,1543710720205
NMEA,$GAGSV,2,2,08,104,,,34,112,,,32,119,,,21,109,,,26,1*7A
,1543710720205
NMEA,$GPGSA,A,3,02,05,06,07,09,13,19,29,30,,,,1.6,0.7,1.4*3A
,1543710720205
NMEA,$GNGSA,A,3,02,05,06,07,09,13,19,29,30,,,,1.6,0.7,1.4*24
,1543710720205
NMEA,$GNGSA,A,3,67,68,69,82,83,84,,,,,,,1.6,0.7,1.4*24
,1543710720205
NMEA,$QZGSA,A,3,01,02,03,,,,,,,,,,1.6,0.7,1.4*2B
,1543710720206
NMEA,$IMGSA,A,3,,,,,,,,,,,,,1.6,0.7,1.4*24
,1543710720206
NMEA,$BDGSA,A,3,203,,,,,,,,,,,,1.6,0.7,1.4*17
,1543710720206
NMEA,$GAGSA,A,3,104,109,112,119,,,,,,,,,1.6,0.7,1.4*20
,1543710720206
NMEA,$GPRMC,003159.00,A,3551.013922,N,13951.736758,E,000.0,337.0,02121
8,,,A*51
,1543710720206
```

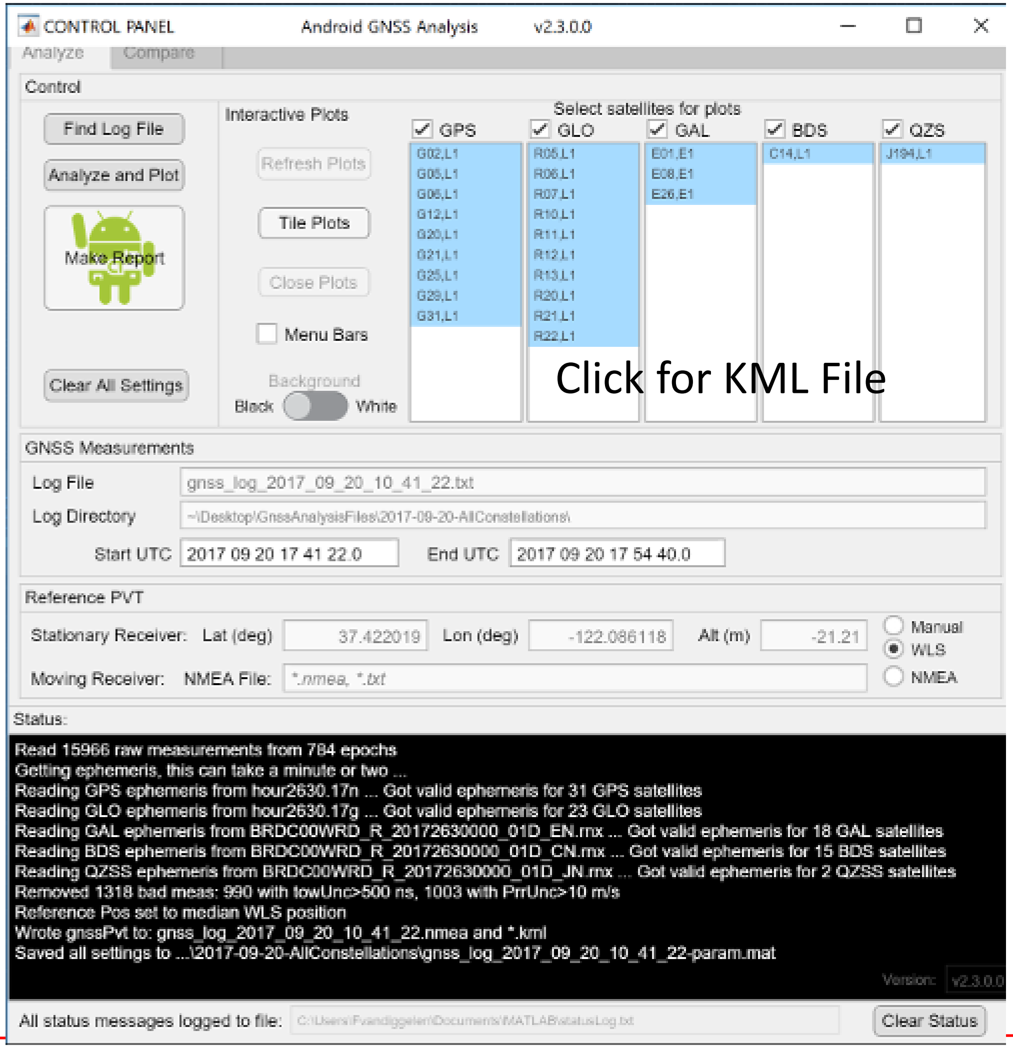
GnssLogger: Sample GNSS Raw Data, Navigation Bit Data

Nav,101,769,1,5,9,76,34,58,55,7,116,-65,67,-77,-42,88Nav,102,769,1,5,9,76,34,58,55,7,116,-65,67,-77,-42,88
Nav,103,769,1,5,9,76,34,58,55,7,116,-65,67,-77,-42,88Nav,105,769,1,5,9,76,34,58,55,7,116,-65,67,-77,-42,88
Nav,106,769,1,5,9,76,34,58,55,7,116,-65,67,-77,-42,88

GNSS Raw Data Analysis Tool for GnssLogger

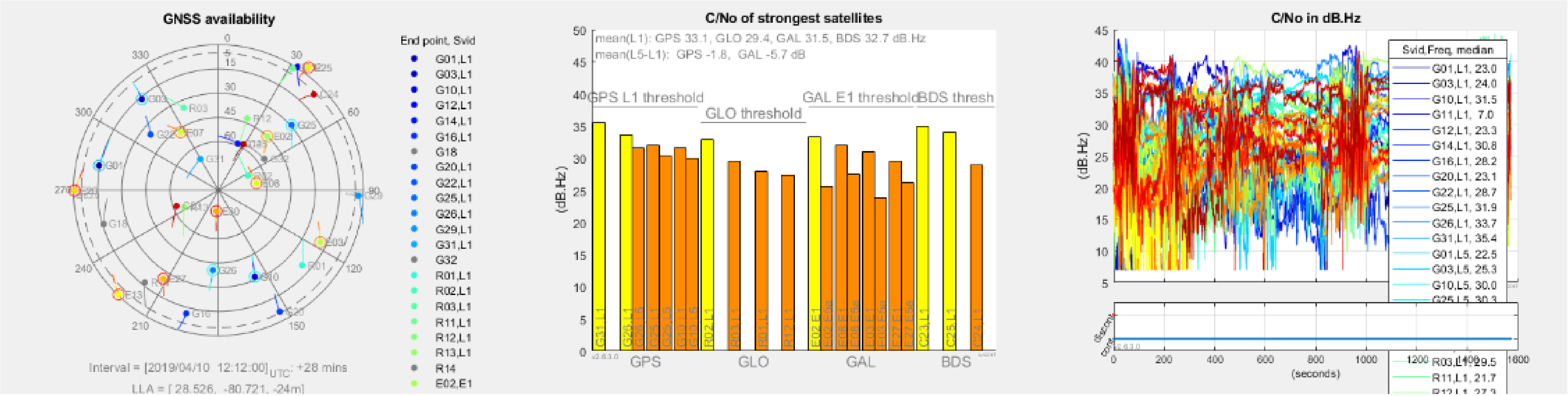
- GNSS Analysis APP
  - Matlab-based Tool
  - Linux, Windows, MacOS
  - Version 2.6.3.0
  - [Release Notes: https://developer.android.com/guide/topics/sensors/gnss#releaseGNSS Analysis app v2.6.3.0 release notes](https://developer.android.com/guide/topics/sensors/gnss#release).





The GNSS Analysis app is built on [MATLAB](), but you don't need to have MATLAB to run it. The app is compiled into an executable that installs a copy of the MATLAB Runtime.

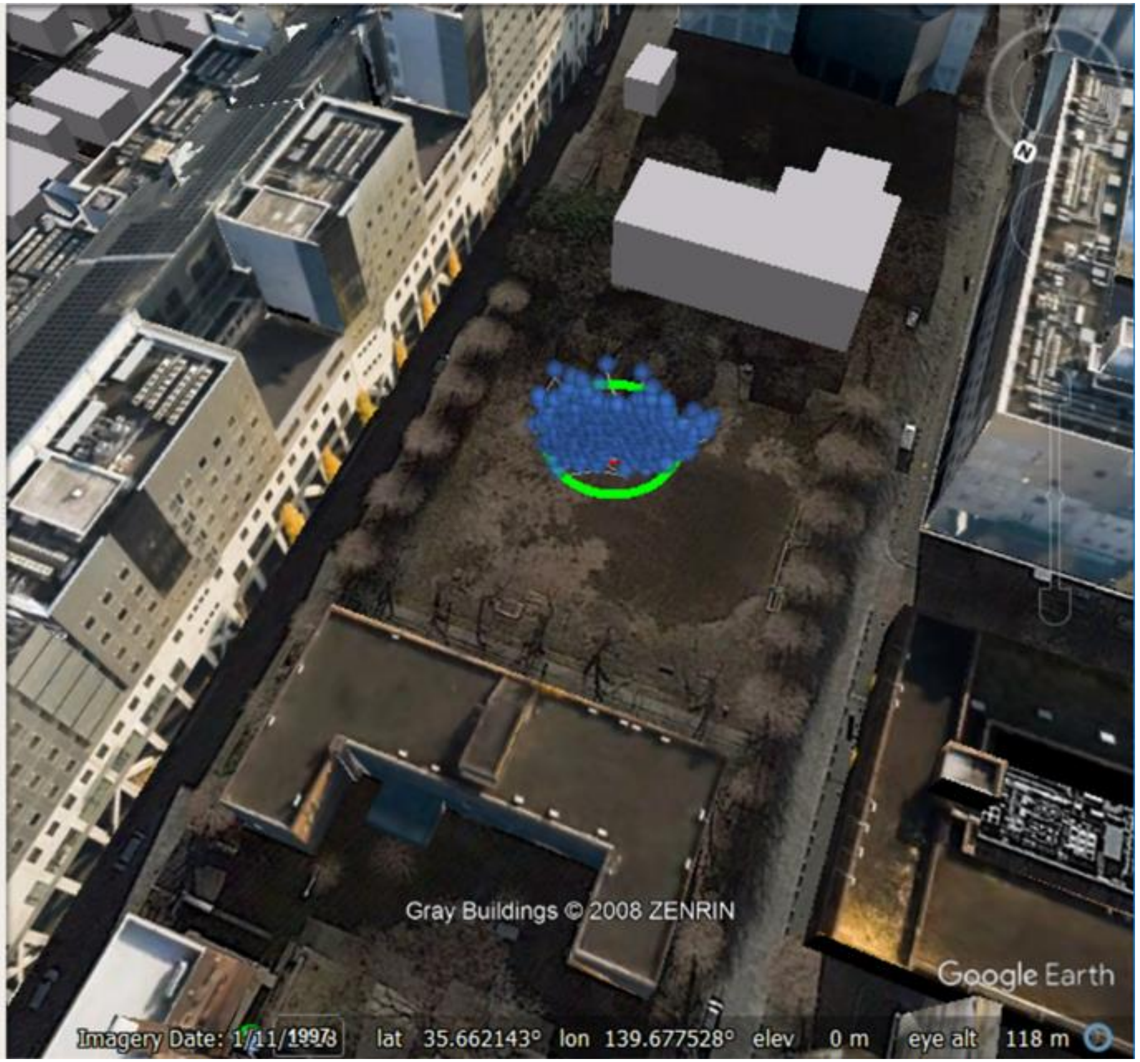
Output from GNSS Analysis Tool, Data Logged by GNSSLogger



Data logged by Mi8 Smart-phone inside the car

Position Output from Android GNSS Receiver, Komaba

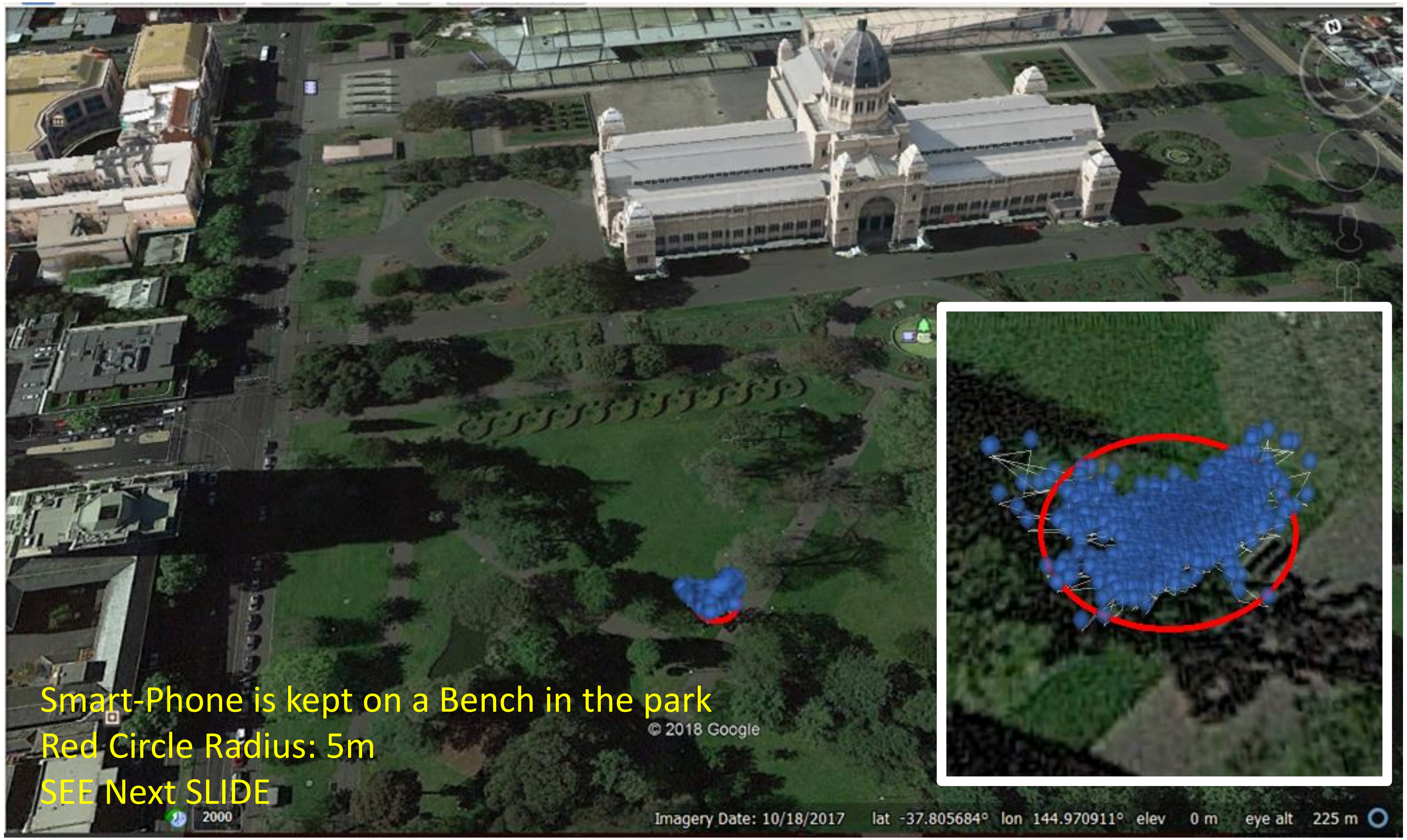
- Standard Position Computation
  - No DGPS or RTK Corrections
  - All visible GNSS Satellites are used
  - Frequency : L1/L5/E5
  - Surrounding : Tall Buildings around



Position Output from Android GNSS Receiver, Hongo

Position Output from Android GNSS Receiver

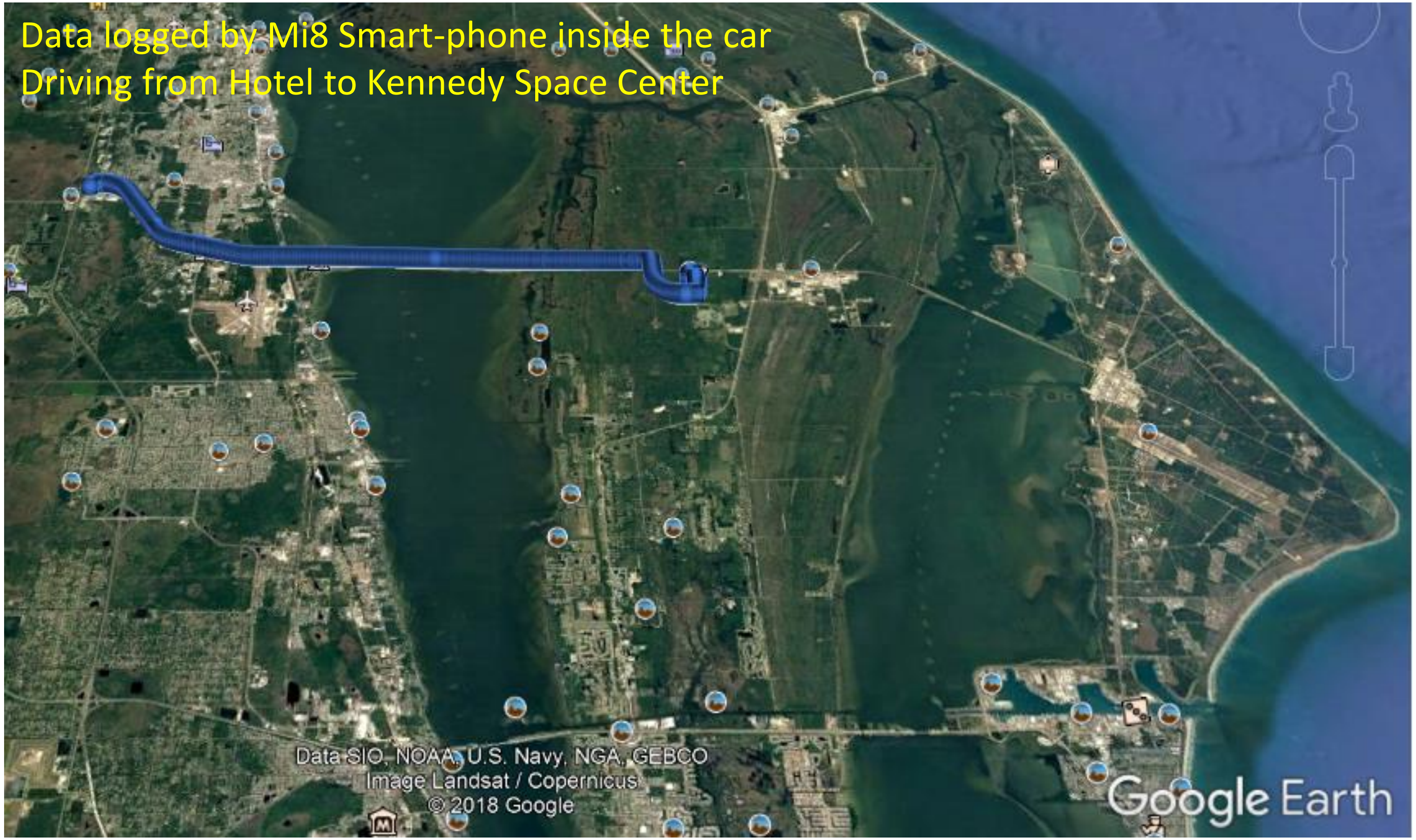
Position Output from Android GNSS Receiver, Melbourne




Exit Street View
Smart-Phone is kept on a Bench in the park
Red Circle Radius: 5m
© 2018 Google
© 2019 Google
Report a problem
Google Earth
Imagery Date: 8/2014 lat -37.806114° lon 144.970363° elev 0 m eye alt 3 m

Output from GNSS Analysis Tool, Data Logged by GNSSLogger

Location:
Kennedy Space Center
Florida



Output from GNSS Analysis Tool, Data Logged by GNSSLogger

GNSS Position Data from Mi8 Android Device

Yellow Circles : Mi8 Device
White Circle : 5m Radius

Location: SUVA, FIJI

GNSS Position Data from P20 Android Device

Red Circles : P20 Device
White Circle : 5m Radius

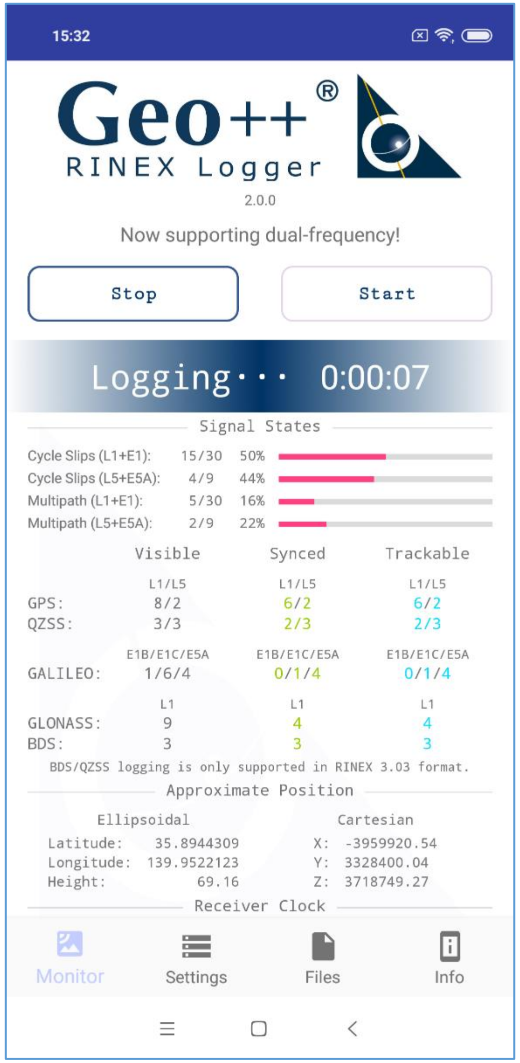
Location: SUVA, FIJI

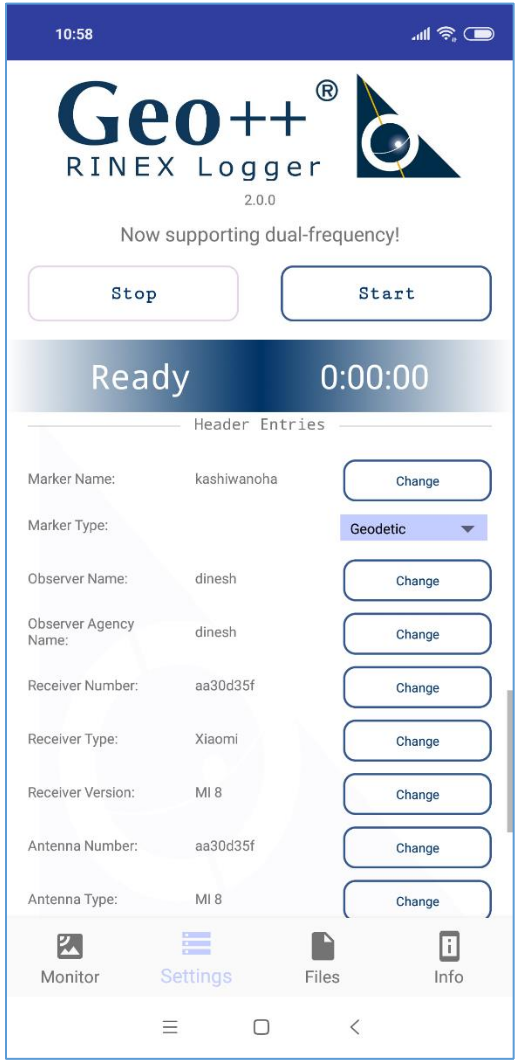
GNSS Position Data from Mi8 & P20 Android Devices

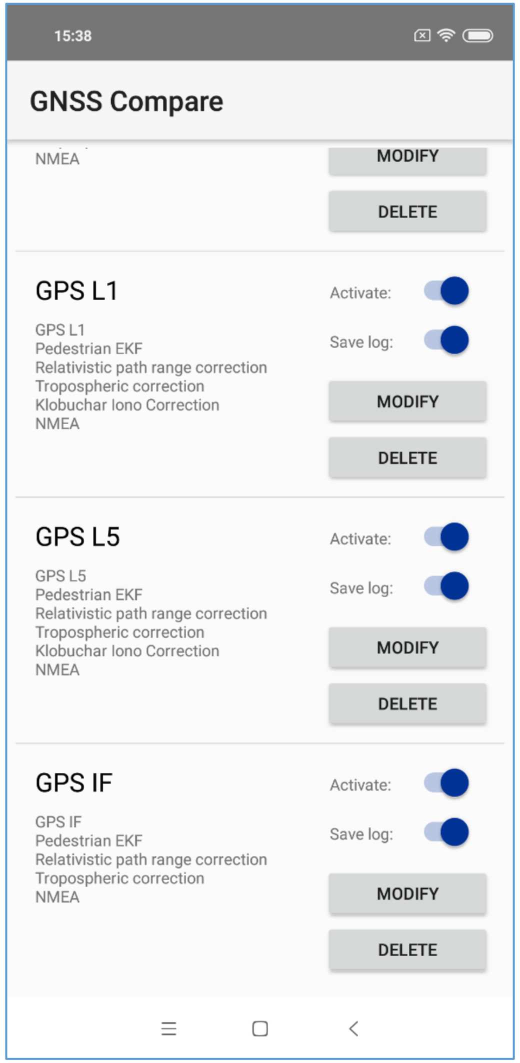
Red Circles : P20 Device
Yellow Circles : Mi8 Device
White Circle : 5m Radius

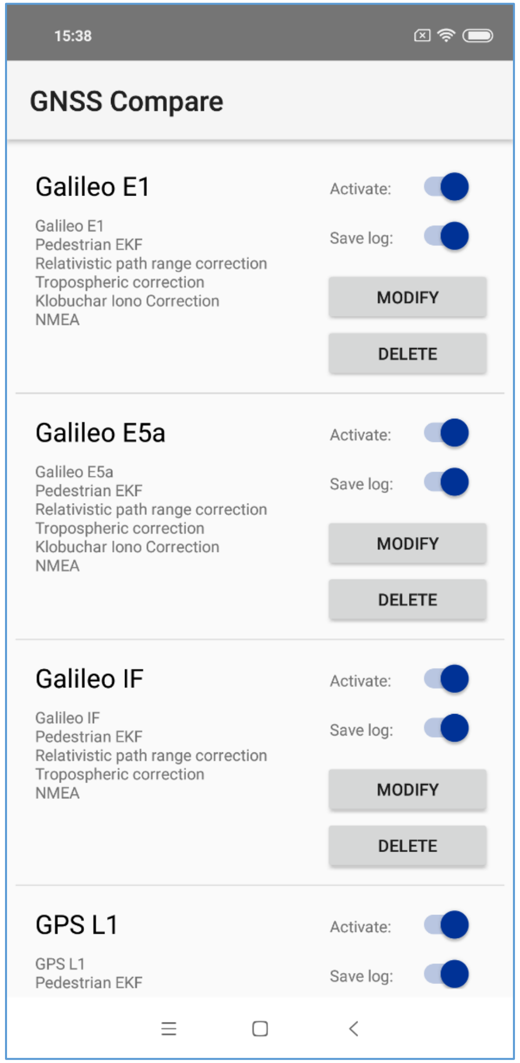
Location: SUVA, FIJI

Android Raw Data Logging APP Geo++ RINEX Logger





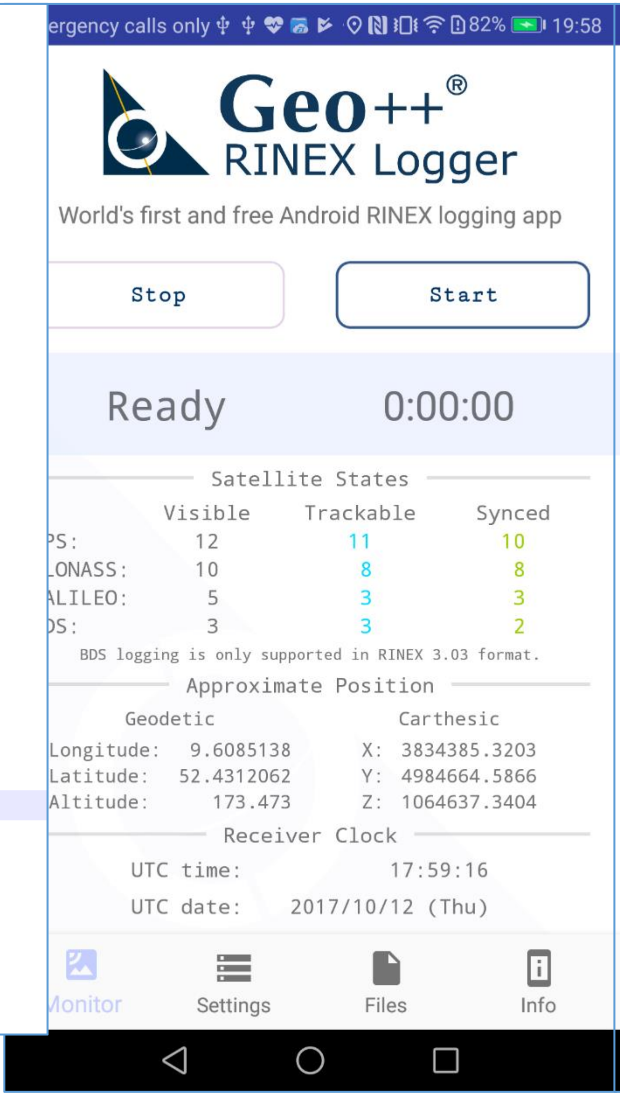


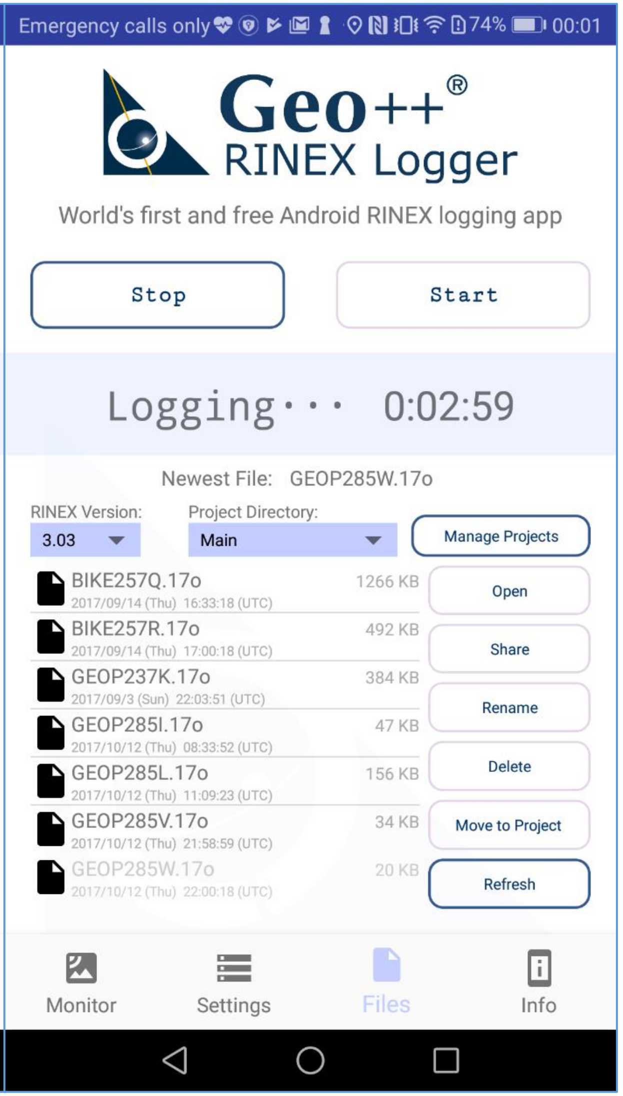


Geo++ RINEX Logger

```
     3.03           OBSERVATION DATA    M: Mixed            RINEX VERSION / TYPE
Geo++ RINEX Logger  Geo++               20181022 071442 UTC PGM / RUN BY / DATE
************************************************************COMMENT
This file was generated by the Geo++ RINEX Logger App       COMMENT
for Android devices (Version 2.0.0). If you encounter       COMMENT
any issues, please send an email to android@geopp.de        COMMENT
************************************************************COMMENT
park                                                        MARKER NAME
GEODETIC                                                    MARKER TYPE
dinesh              dinesh                                  OBSERVER / AGENCY
aa30d35f            Xiaomi              MI 8                REC # / TYPE / VERS
aa30d35f            MI 8                                    ANT # / TYPE
 -4131685.6432  2896217.5961 -3888491.9491                  APPROX POSITION XYZ
        0.0000        0.0000        0.0000                  ANTENNA: DELTA H/E/N
G    8 C1C L1C D1C S1C C5Q L5Q D5Q S5Q                      SYS / # / OBS TYPES
R    4 C1C L1C D1C S1C                                      SYS / # / OBS TYPES
E   12 C1B L1B D1B S1B C1C L1C D1C S1C C5Q L5Q D5Q S5Q      SYS / # / OBS TYPES
C    4 C2I L2I D2I S2I                                      SYS / # / OBS TYPES
J    8 C1C L1C D1C S1C C5Q L5Q D5Q S5Q                      SYS / # / OBS TYPES
  2018    10    22     7    15    0.0001146     GPS         TIME OF FIRST OBS
 24 R01  1 R02 -4 R03  5 R04  6 R05  1 R06 -4 R07  5 R08  6 GLONASS SLOT / FRQ #
    R09 -2 R10 -7 R11  0 R12 -1 R13 -2 R14 -7 R15  0 R16 -1 GLONASS SLOT / FRQ #
    R17  4 R18 -3 R19  3 R20  2 R21  4 R22 -3 R23  3 R24  2 GLONASS SLOT / FRQ #
G L1C                                                       SYS / PHASE SHIFTS
G L5Q -0.25000                                              SYS / PHASE SHIFTS
R L1C                                                       SYS / PHASE SHIFTS
E L1B                                                       SYS / PHASE SHIFTS
E L1C +0.50000                                              SYS / PHASE SHIFTS
E L5Q -0.25000                                              SYS / PHASE SHIFTS
C L2I                                                       SYS / PHASE SHIFTS
J L1C                                                       SYS / PHASE SHIFTS
J L5Q -0.25000                                              SYS / PHASE SHIFTS
 C1C    0.000 C1P    0.000 C2C    0.000 C2P    0.000        GLONASS COD/PHS/BIS
                                                            END OF HEADER
```

Supports both L1 & L5

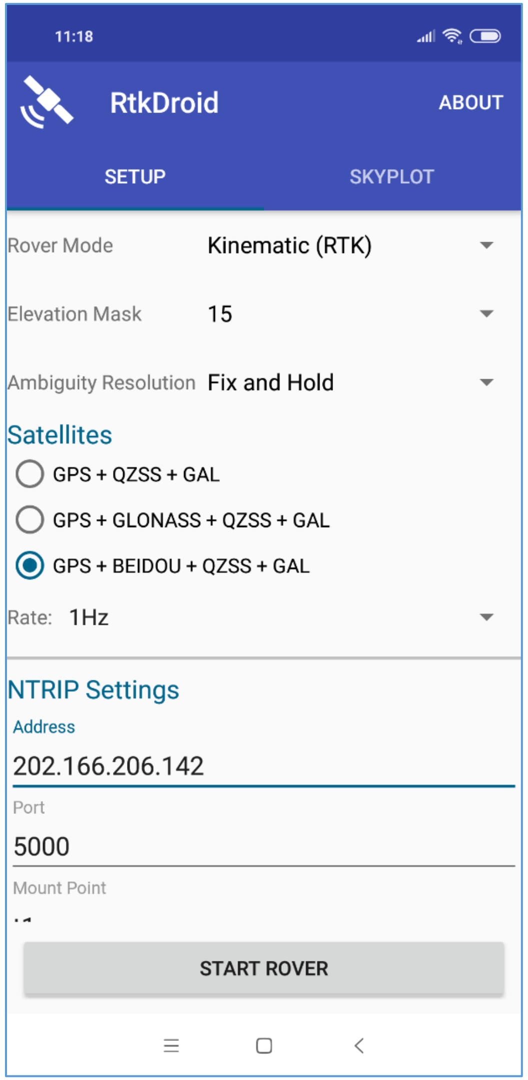


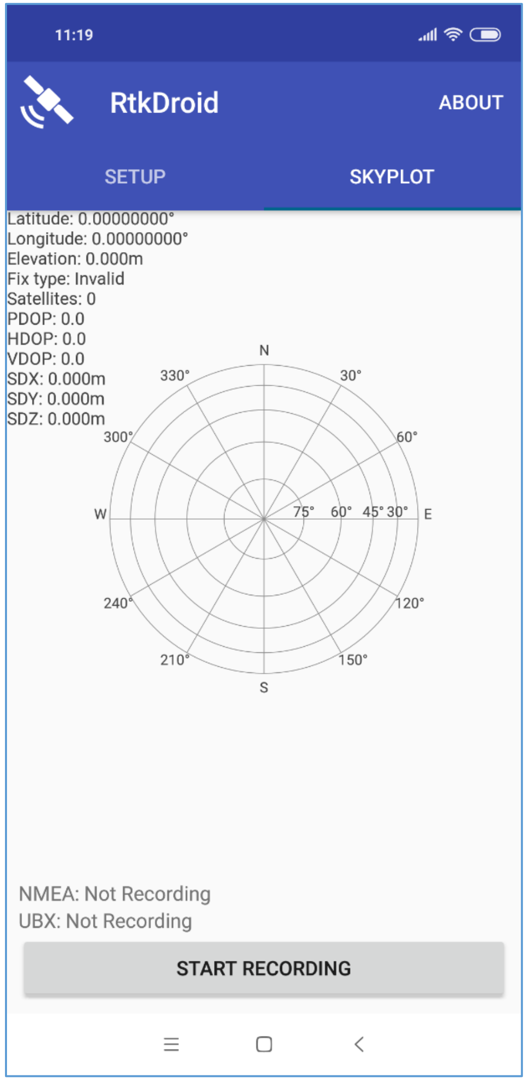


http://www.geopp.de/logging-of-gnss-raw-data-on-android/

Android Raw Data Logging APP: RTKDROID

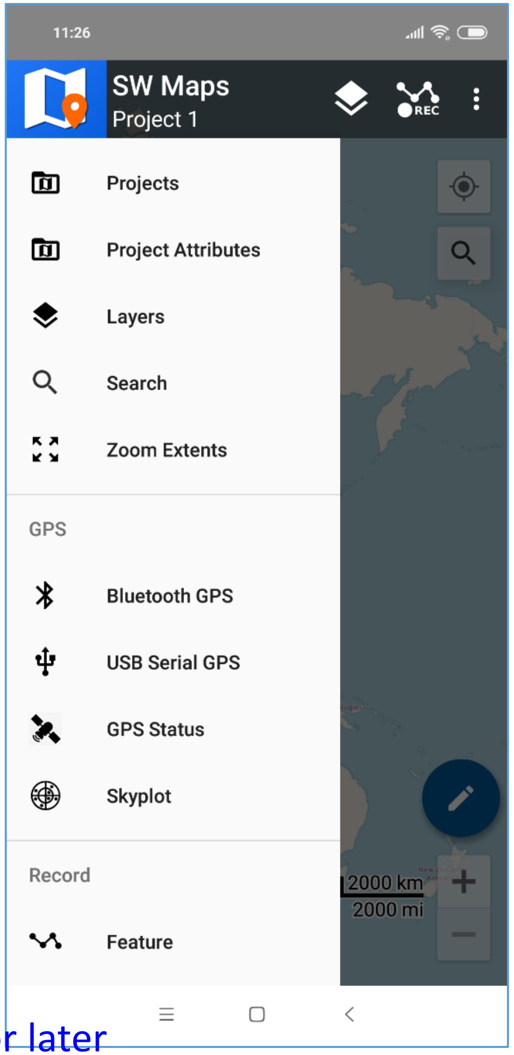
- External GNSS Receiver can be connected to Android Device
- Base-Station is connected via NTRIP Address
- VRS Correction also supported
- Supported File Format
  - ubx (u-blox)
  - Other formats will be included if requested
    - SBF (Septentrio) will be included in near future
- Real-Time RTK
- Raw Data can be logged for Post-Processing
- Output from RTKDROID can be send to other APKs in the device

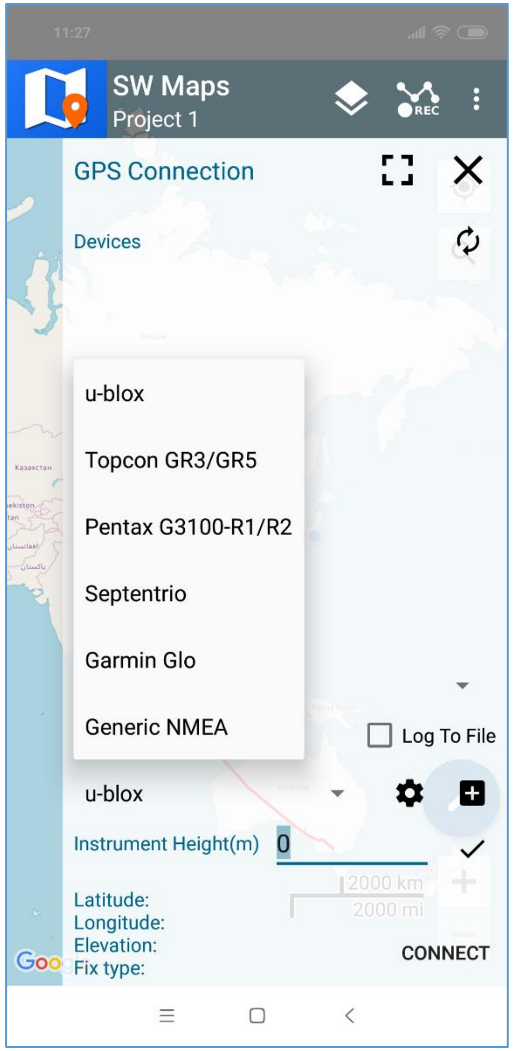




Android APP to Input GNSS Data for GIS: SW Maps

- Excellent APP to collect GIS Data in the field
- Internal or External GNSS Receiver can be used
  - External Receiver can be connected via BT or USB Cable
- Many Popular File Formats are Supported
  - u-blox
  - Topcon
  - Trimble
  - Septentrio
  - Garmin
  - Or Any Receiver with NMEA output
  - Output from RTKDROID can be send to SW Maps





RTKDROID and SW MAPS run in many Android Devices that has OS 5.0 or later

Contact and Additional Information

- Homepage
  - Main Page : https://home.csis.u-tokyo.ac.jp/~dinesh/
  - Webinar Page : https://home.csis.u-tokyo.ac.jp/~dinesh/WEBINAR.htm
    https://gnss.peatix.com/
  - Training Data etc. : https://home.csis.u-tokyo.ac.jp/~dinesh/GNSS_Train.htm
  - Low-Cost Receiver : https://home.csis.u-tokyo.ac.jp/~dinesh/LCHAR.htm
  - Facebook : https://www.facebook.com/gnss.lab/
- Contact
  - E-mail : dinesh@csis.u-tokyo.ac.jp
  - Skype : mobilemap