## IMES (Indoor Messaging System) A Proposal for New Indoor Positioning System

Presenter: Dr. Dinesh Manandhar GNSS Technologies Inc., Japan

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## What is IMES ?

# IMES stands for Indoor MEssaging System

## It transmits the position data itself in the Navigation Message

## **Fundamental Problem**

## How to know my location precisely ?

- Specially in deep indoors
  - At any condition
  - At any time
  - At any place

Where am I ? Conventional Position Information 139<sup>0</sup> 39' 40'' 35<sup>0</sup> 40' 41''

2

### **Background - 1**

#### Japanese E911 legislations were enforced in April 2007

More than 100 Million cell-phones with GPS receiver in Japan in a couple of years

#### > Number of mobile phones in the world : 3.3bil. by NOV 2007

- Penetration Factor 49%  $\rightarrow$  Near to Half the world's population,
- Expected Penetration Factor 61%  $\rightarrow$  By the end of 2008
- An average growth rate of 24% for the past eight years
  - Source: http://en.wikipedia.org/wiki/Mobile\_phone#cite\_note-9
  - http://www.guardian.co.uk/technology/2008/sep/26/mobilephones.unitednations
  - http://www.chinapost.com.tw/business/global%20markets/2008/05/26/158188/Mobile-phone.htm

## LBS market is expected to grow drastically Seamless positioning is one of the most important requirements for commercial applications.

- Several approaches
  - RF ID, WiFi, UWB, Pseudolite, Repeater and so on..... And of Course ultimately IMES

## **Background – 2 (USA Scenario)**

262mil. of wireless users in USA as per June 2008

- 60mil. addition compared to June 2005
  - CTIA Report
- 296K E911 calls per Day in Jun 2008
  - 36K addition compared to June 2005
    - CTIA Report 16% of US Houses are Wireless-only as per June 2008
  - This forces operators to develop methods to provide E911 callers' position using mobile networks only
    - CTIA Report

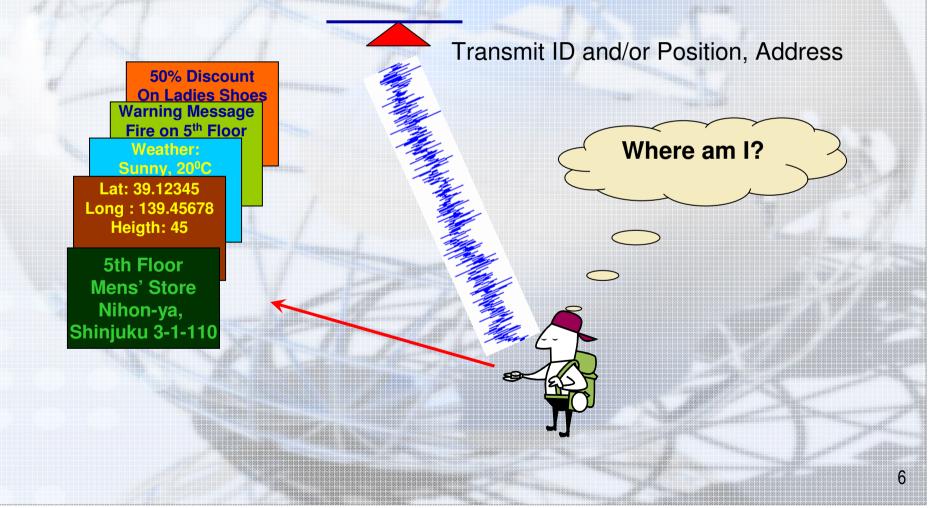
## **Background - 3**

### There are other indoor navigation systems like A-GPS, E-GPS and Pseudolites etc

- But they have unstable accuracy
  - The accuracy varies case by case from few meters to few hundreds of meters
- Complex architecture
- Difficulty in deep indoors
- During emergency, a search in 3-D space in 100m accuracy is not a good figure
- How to know that the victim is on the 15<sup>th</sup> Floor, Room No 1510 precisely?

## **IMES Concept - 1**

#### **Principle of Proposed IMES System**



## **IMES Concept - 2**

- IMES can transmit its position in three dimensions directly
  - No pseudorange measurement and time synchronization
- Compatible and interoperable signal with GPS/QZSS for seamless positioning
  - The same Receiver can acquire signals from satellites as well as indoor transmitters without serious modifications on existing receiver.
  - It can be upgraded to future GNSS signals
- Target users are cell-phone and handheld receiver with big mass volume and low dynamics.

## **Signal Design Concept**

- Compatible and interoperable with GPS/QZSS signals for seamless positioning
  - The same Receiver can acquire signals from satellites as well as from IMES
    - This means similar signal structure
- Different Message Types based on Application Types
- Low power consumption
  - Longer run of cell phones
- **& Stable Accuracy** 
  - Sub-meter accuracy is not required. 10m seems to be enough for users to know where they are
    - moderate room size, each shop or portion in shopping complex
  - Stable position data at any time is more important than higher precision

## **RF Properties of IMES**

#### **b** Same as GPS L1 C/A for minimizing receivers' modifications

RF Centre Frequency	1575.42Mhz (+/- ⊿ f)
PRN Code Rate	1.023Mhz
PRN Code Length	1ms
PRN ID	173 – 182
Navigation Message Rate	50bps
Modulation	BPSK
Polarization	RHCP

#### **The power of transmitter is**

- less than the value defined by radio regulation
- is varied with environment of the locations and space between transmitters

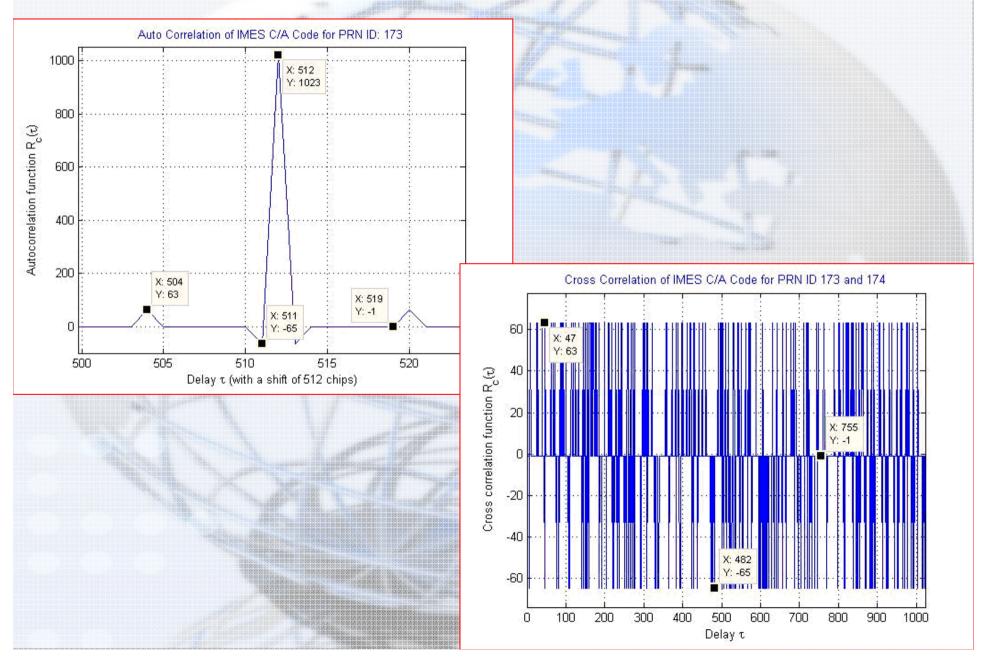
## **PRN Code Table for IMES**

The US Government has allocated 10 PRN Codes for IMES – C/A PRN CODE ASSIGNMENTS as of Nov. 5, 2007

 <u>http://www.losangeles.af.mil/shared/media/document/AFD-</u> 070530-036.pdf

PRN Signal	G2 Delay	Initial G2	First 10 Chips	PRN	Orbital Slot
Number	(Chips)	Setting (Octal)	(Octal)	Allocations	Orbital Slot
173	150	1362	415	QZSS – IMES3	Ground
174	395	1654		QZSS – IMES3	
175	345	510	1267	QZSS – IMES3	Ground
176	846	242	1535	QZSS – IMES3	Ground
177	798	1142		QZSS – IMES3	
178	992	1017	760	QZSS – IMES3	Ground
179	357	1070	707	QZSS – IMES3	Ground
180	995	501	1276	QZSS – IMES3	Ground
181	877	455	1322	QZSS – IMES3	Ground
182	112	1566	211	QZSS – IMES3	Ground
183	144	215	1562	QZS1	A1
184	476	1003	774	Reserved (QZS	TBD

## Auto and Cross Correlation between IMES PRN Codes



## **IMES Message Structure**

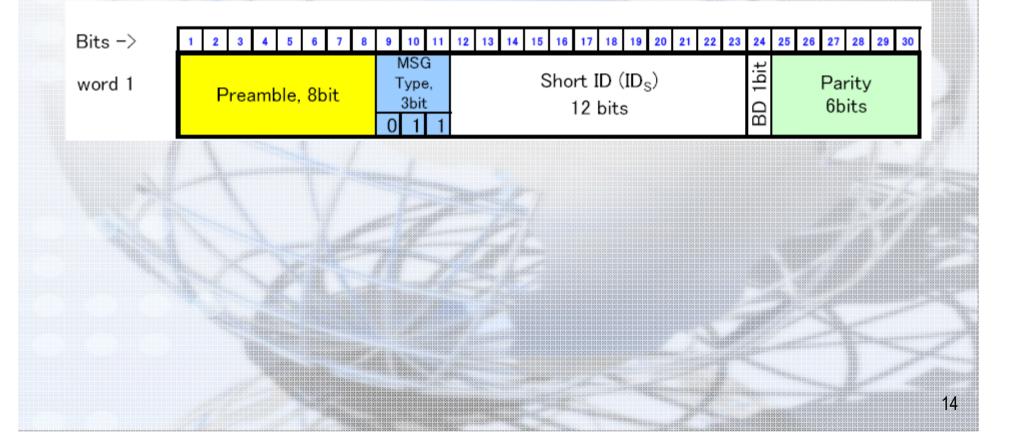
- The message structure of IMES is defined in the annex of IS-QZSS.
  - Similar to QZSS and GPS L1C/A message structure
  - Four types of IMES messages are defined currently
    - Type #0: Longitude, Latitude, Floor ID, [90bit,1.8 sec]
    - Type #1: Longitude, Latitude, Height, Floor [120bit, 2.4 sec]
    - Type #3: Short ID [30bit, 0.6sec]
    - Type #4: Medium ID [60bit, 1.2sec]

## **IMES Message**

## Type # 1, 3-D Position Format with Floor ID

Bits -> word 1	1 2 3 Prea	4 5 6 7 8 9 amble, 8bit	MSG Type	5 16 17		20 21 22 23 24	25	26 27 28 29 30 Parity 6bits	
word 2	CNT 3bit		Latitude 21bits (MSB)				Parity 6bits		
word 3	CNT 3bit	Longitude 21bits (MSB)					Parity		
word 4	CNT 3bit	Altitud	Altitude 12 bits		Lat (LSB)	(HSD)		Parity	
	# Cont	ent Bit Length	LSE	}			ang I~		1
		_	_		minimum -50 th		~	maximum 205 th	
	1 Floo 2 Latit			(1.19 r	m)	-90 deg		90 deg	-
	3 Longit		1.1E-05 deg	(1.19 r		))		180 deg	
	4 Altitu	ude 12			-95 m		~	4000 m	1

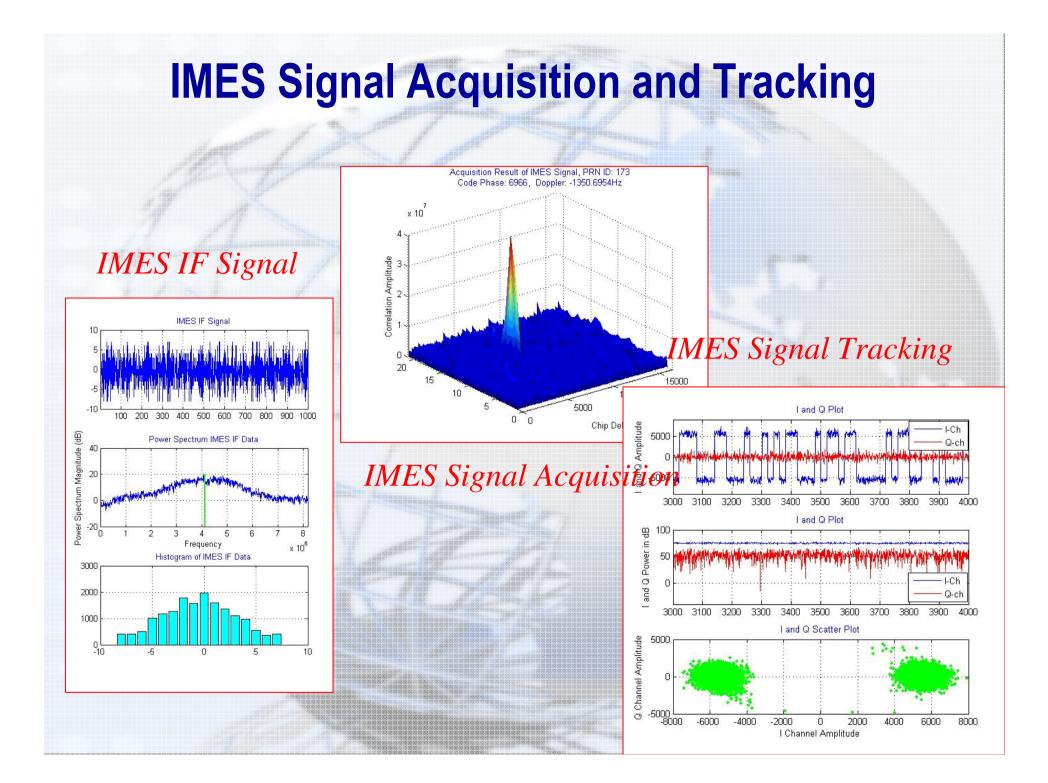
## IMES Message Type #3, Short ID Format



## IMES Control Software

PRN ID	×	Message Type	~	RF Attenuation 31 set
Preamble	H8B	Short ID	2045	RF Carrier ON/OFF NAV DATA ON/OFF Run On/Off
Latitude	35.667683	Medium ID	12345678	PRN CODE ON/OFF NAV Rate 50
Longitude	139.792495	Floor ID	3	User Command
Altitude	40	BD Bit	0	
Reserve Bit	B01			CommandMemo
Word 1			Send Frame	
Word 2				
Word 3				
Word 4				
Word 5				COM PORT 4 🚭 OPEN Initialize SAVE
Word 6				
_ MsgType #0	MsgType #3	MsgType #0 and #	3 MsgType #1 and #3	
MsgType #1			1         MsgType #1 and #4	Bizzer un
		nd Seq		
				COREDO RUN MORE

15

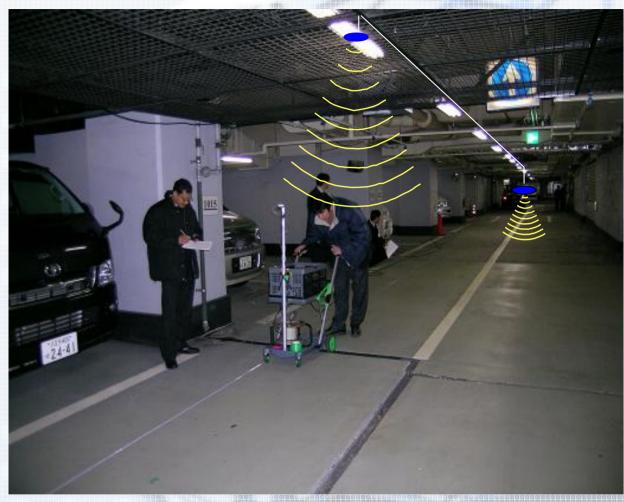


## **IMES Output Position Data**





## **Experiments & Demonstration**



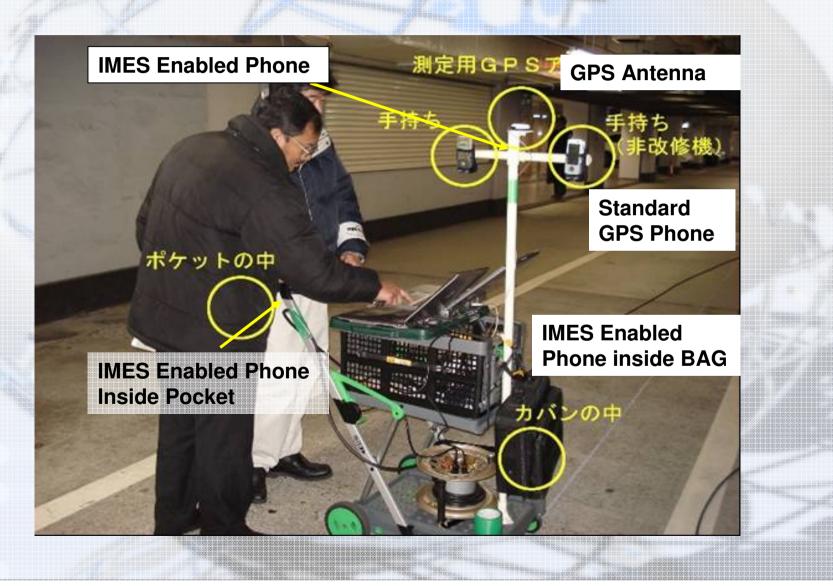
Indoor Demonstration at Underground Parking



#### **IMES Enabled Cell Phone**

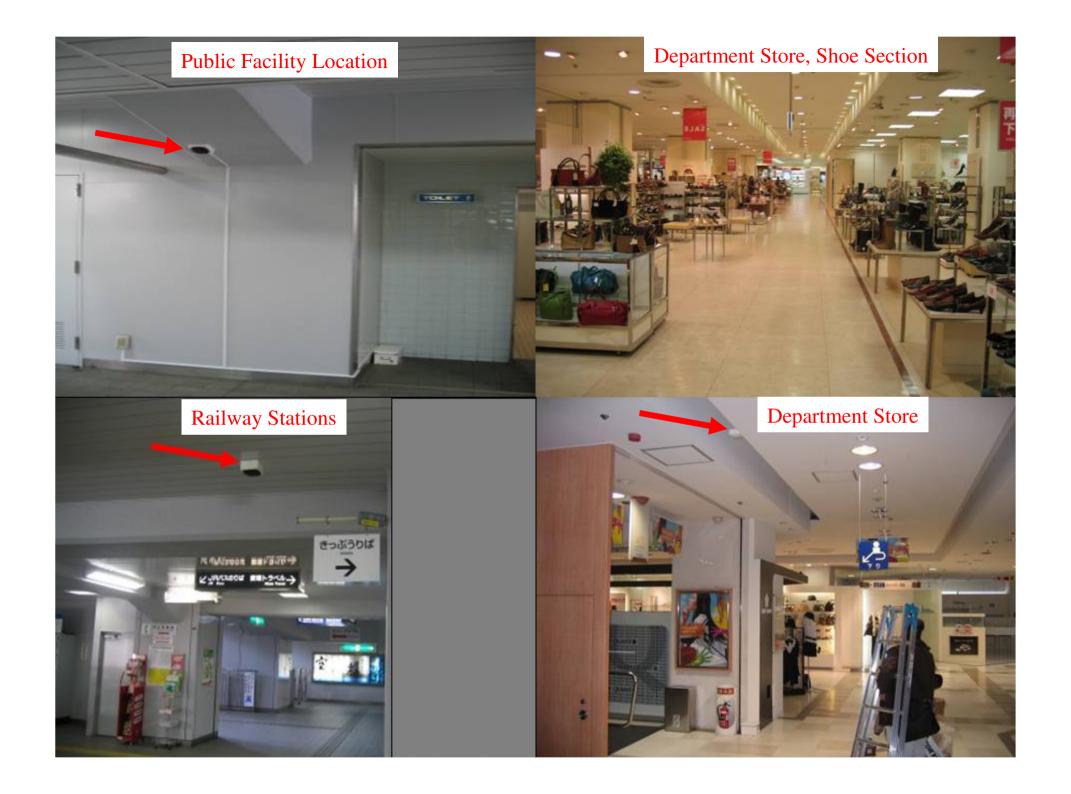


## **Observation using Mobile Phone**



## **Experiments Conducted at Various Locations**





## Summary - 1

## The concept of IMES for seamless navigation is introduced.

- Requires No ranging
- Requires No synchronization
- Requires Only single unit for 3D position & messages
- Requires No H/W change for existing GPS
- Applicable to any cellphone globally with GPS chip
- Applicable to any GNSS signal type
- Provides seamless position, anytime, anywhere

## Summary - 2

The concepts and its feasibilities were demonstrated by experiments.

- Demonstration at underground parkings, office buildings, building lobby etc
- Interference experiments

Patents related to IMES signal design, transmitter, receiver, data management and other related are filed internationally

More interference related analysis are planned to fix detail specifications

## Thanks a lot !