

# Status of EGNOS and Galileo Projects



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Ecomponents

EGNOS



**GALILEO:** Satellite constellation and ground mission and control segments





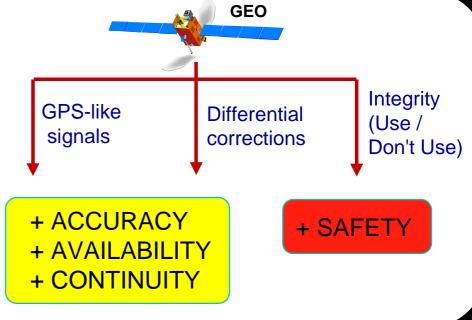


SERVICE CENTERS

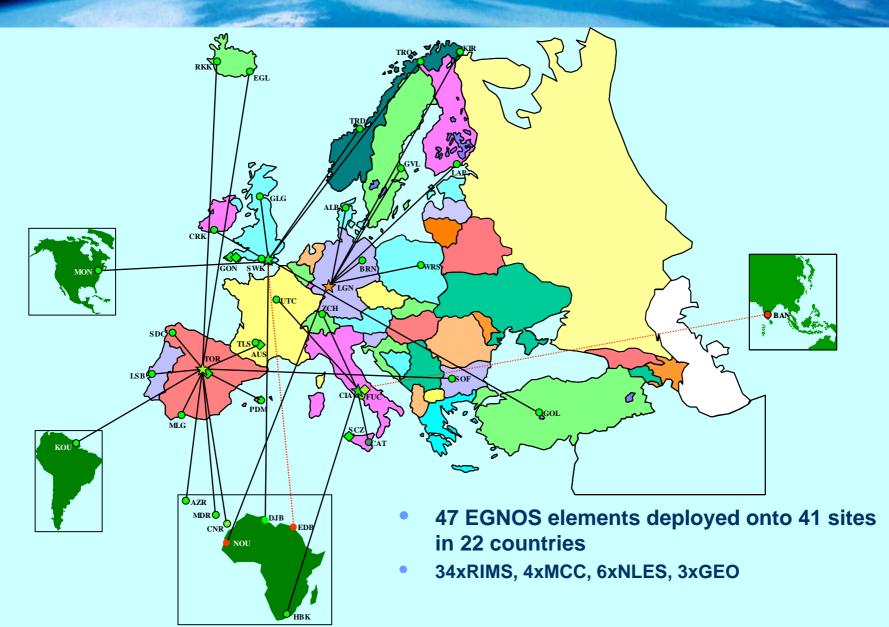




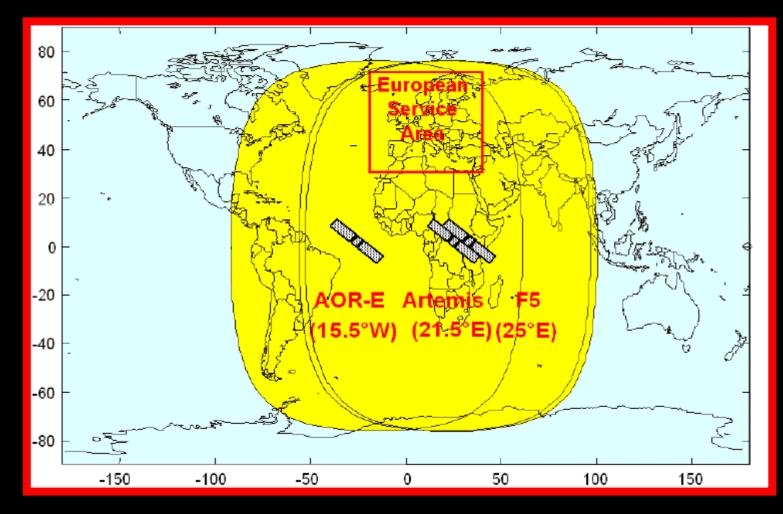
- The first step of the European GNSS Strategy leading to Galileo.
- EGNOS is the first component of the European SatNav infrastructure.
- EGNOS provides early benefits to users and it is a precursor of Galileo services (e.g. integrity).
   GPS-like Signals Differential corrections











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#### Triple coverage over Mediterranean and Africa



# **EGNOS Status**

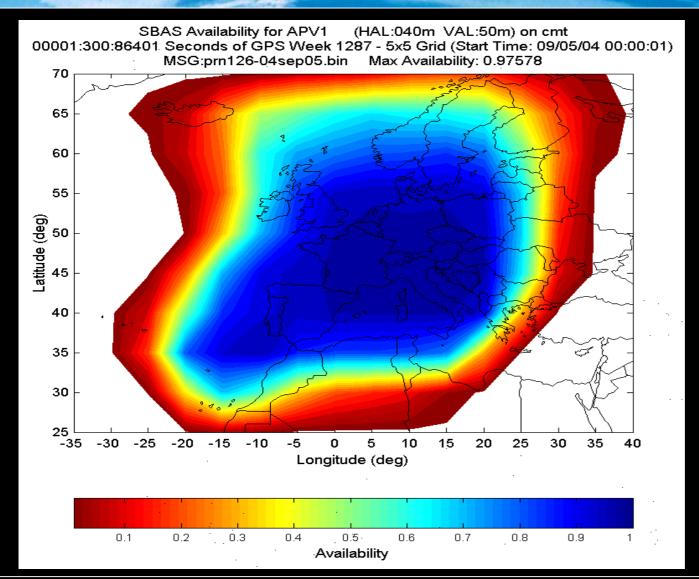
- Deployment practically completed
  - 4 MCCs, 6 NLES, 30 out of 34 RIMS;
  - All 3 EGNOS Geostationary satellites are transmitting successfully: AOR-E, IOR-W and ARTEMIS
- EGNOS test transmissions since July 2004.
- Signals available for non-safety of life users in early 2005.
- Signals available for safety-of-life users in 2006.
- Gradual introduction of EGNOS evolutions (e.g. extension of coverage area) to be initiated in 2005.



Less than 1 m horizontal accuracies recorded in EGNOS quite often;
Excellent vertical accuracies 1-2m (well below the 7.6 m specification)

	Lisbon	Toulouse	Rome	Brussels	Paris
HNSE 95%	1.2 m	0.9 m	1.1 m	0.8 m	1.0 m
VNSE 95%	1.7 m	1.4 m	1.2 m	1.7 m	1.3m

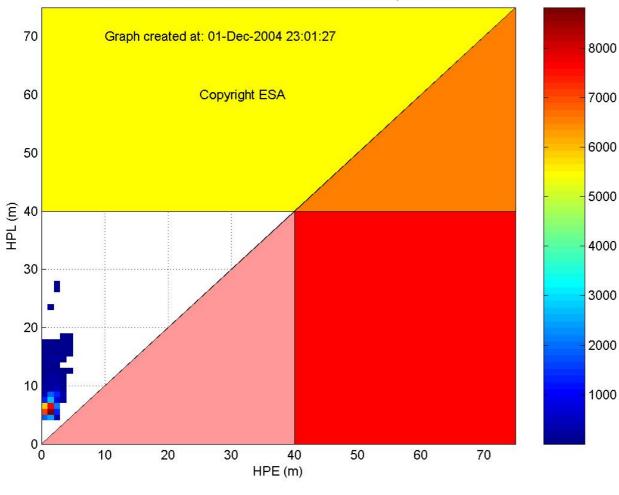
# Cesa Service Coverage



Sep 5, 2004 (24 h) 26 RIMS out of 34



Avail. APV-I: 0.99994 Avail. APV-II: 0.99994 # Samples: 49794

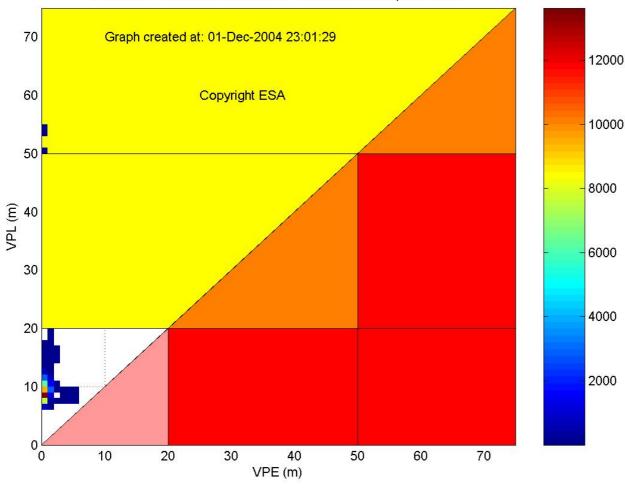


ESA/ESTEC (NL) Dec 1, 2004 30 out of 34 RIMS

Number of Points per Pixel



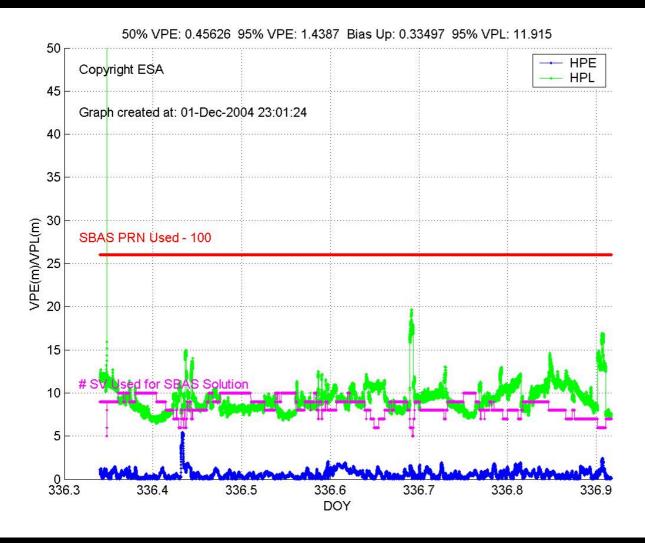
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ESA/ESTEC (NL) Dec 1, 2004 30 out of 34 RIMS

Number of Points per Pixel

# Control<t



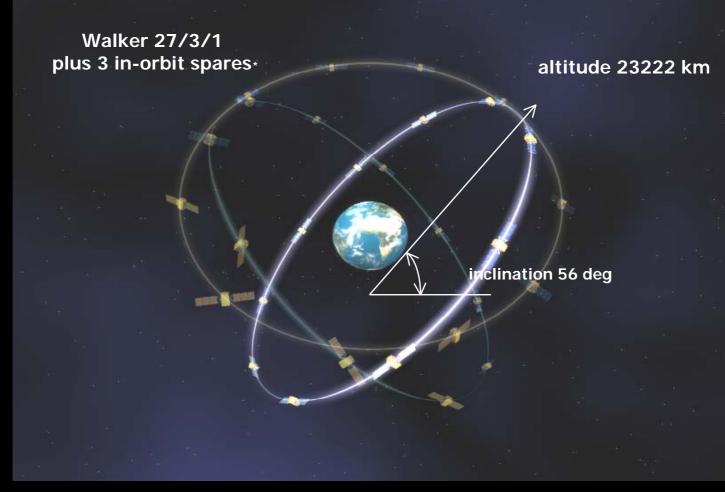
ESA/ESTEC (NL) Dec 1, 2004 30 out of 34 RIMS



# **EGNOS Evolution**

- No disruption of operational service
- Step-wise Implementation.
- Step 1 (2006):
  - EGNOS GEO data for dissemination over non-GEO links.
  - Extension of coverage area: South of Mediterranean area and East Europe.
- Step 2 (2007-2008)\*:
  - Extension in Africa
  - L5 capabilities
  - Search and Rescue Return Link



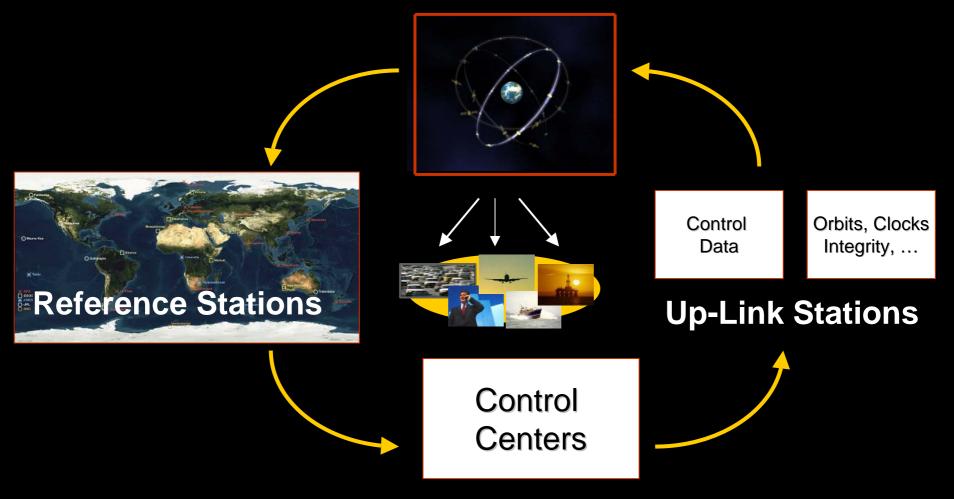


\*) passive spares

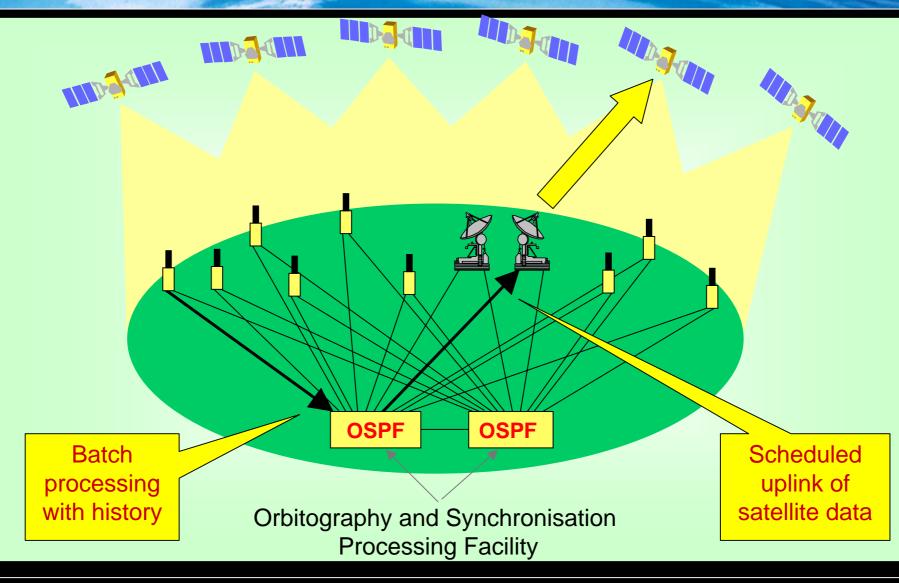
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# esa *Galileo* Architecture

#### Constellation

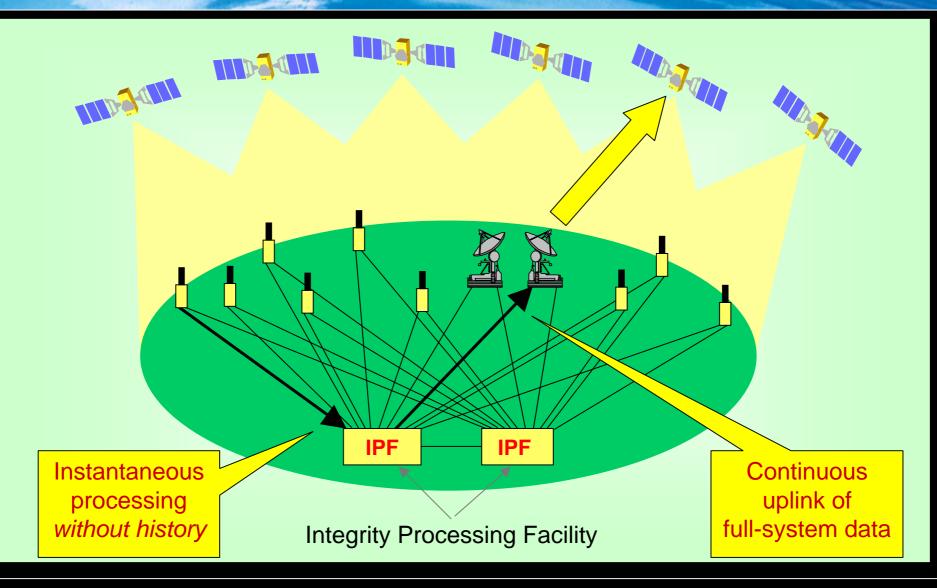






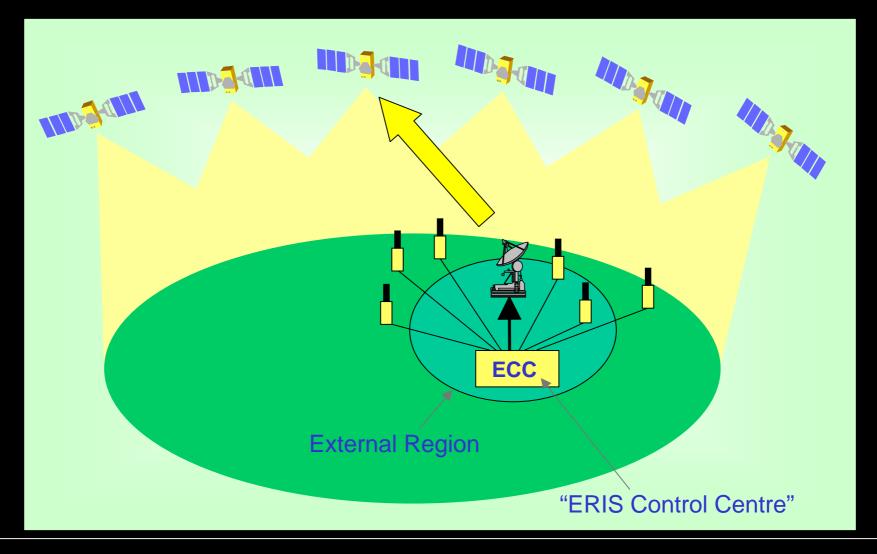
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### Integrity Determination

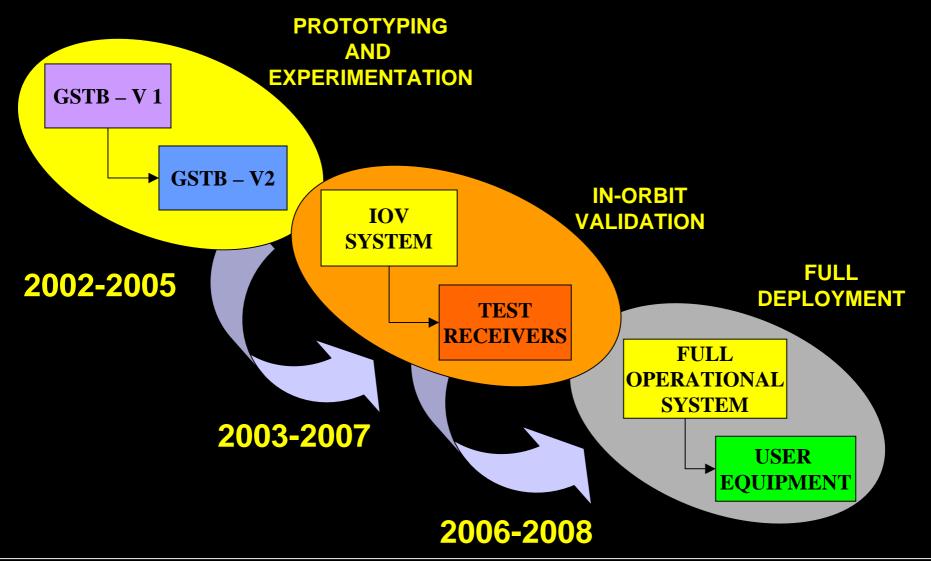


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## **External Region Integrity** Service









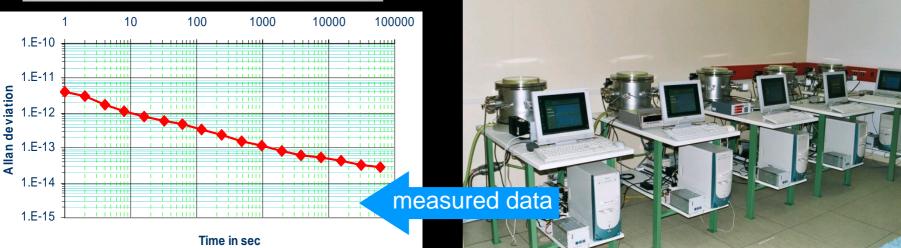
- Critical technology developments completed: (i.e clocks Rubidium, H-Maser (1ns in 100min), Satellite Navigation Antenna, GSS Antennas, GSS Receiver PreDev, ...)
- Galileo System Test-Bed (GSTB-V1) developed to experiment with Galileo-like processing algorithms based on GPS Observables. Six months of results.
- The GSTB-V2 development was Kicked-off in July 03
  - Two experimental satellites under development.
  - First experimental satellite to be launched by end 2005.
  - The GSTB-V2 is planned to be operated for a period of two years after launch (2006 & 2007)
- In-Orbit Validation Phase on-going.



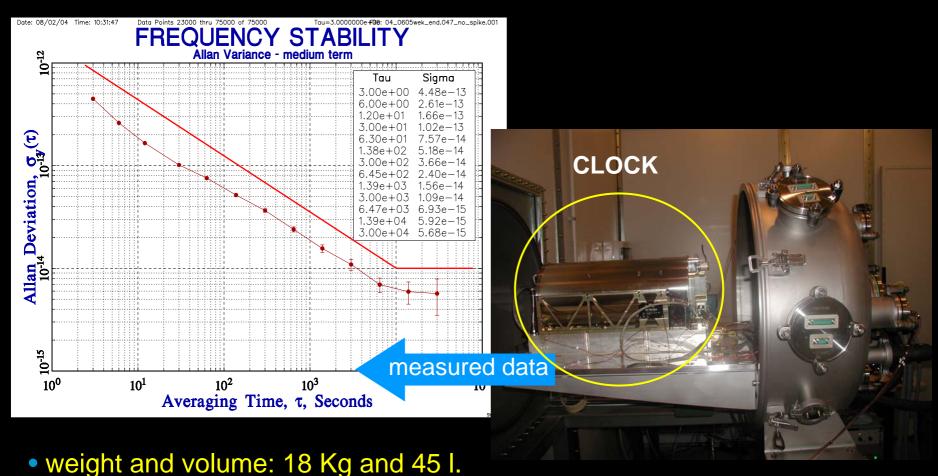
### **Rubidium Atomic Clock**



weight and volume: 3.3 Kgs and 2.4 I.
time stability: better than 10 nsec per day



H-maser Atomic Clock



time stability: better than 1 nsec per day.

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# Satellite Navigation Antenna



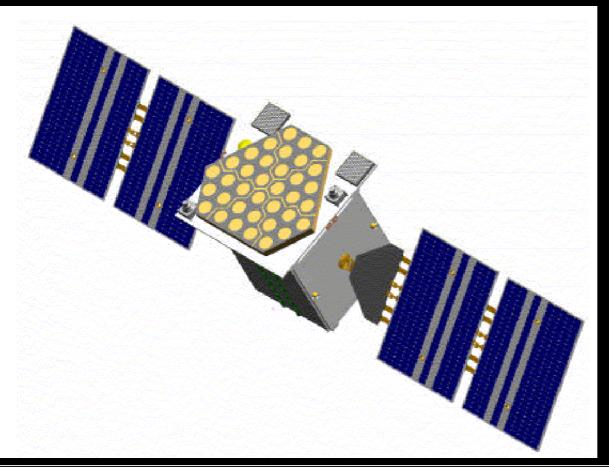
• Phase array.

 Isoflux pattern to equalize received power level on ground.

 Broadband frequency response to cover all the Galileo frequency bands with high performance



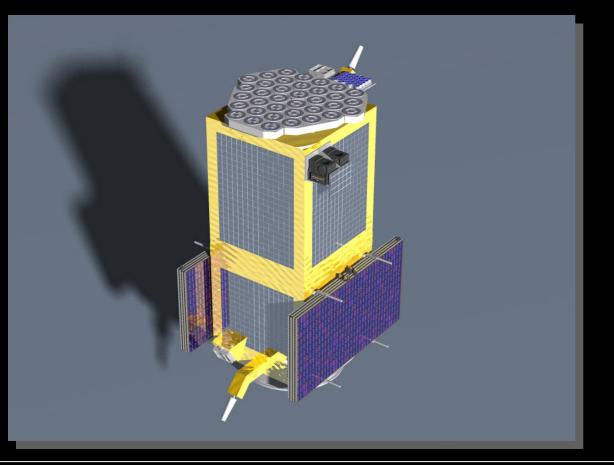
### GSTB-v2 A Satellite (Surrey Satellite Technology Ltd)



- Lift-off mass 450 kg
- Power demand 660 W
- Stowed Dimensions 1.3 m x 1.74 m x 1.4 m



### GSTB-v2 B Satellite (Galileo Industries)



- Lift-off mass 523 kg
- Power demand 943 W
- Stowed Dimensions: 0.955 m x 0.955 m x 2.4 m



### **Experimental GroundSegment** (GSTB-v1)

- Galileo demanding performance require:
  - Very precise satellite orbit prediction capability (65 cm).
  - Very precise satellite clock synchronization (1.5 nsec over 100 minutes)
  - Low integrity risk in detecting system failures (satellite or ground).
  - Overall high availability of service (99.5%)
- Requires advanced ground segment processing algorithms.
- Algorithms being experimented today with GSTB-v1 using GPS signals and a dedicated network of GPS ground stations.



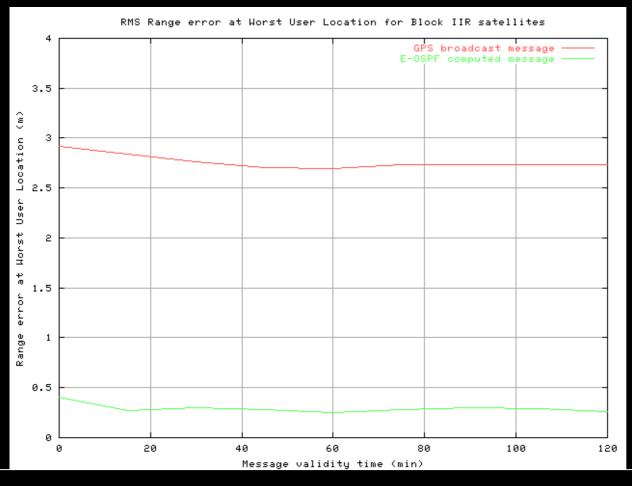
### **GSTB-V1 Sensor Stations Network**



#### The GALILEO network of reference stations will also be global.



#### GSTB-v1 Results: GPS Orbit and Clock Synchronization



- Contribution to range error due to orbit and clock erros.
- Comparison of the broadcasted GPS navigation msg with the E-OSPF computed one.
- Validity Time (2 hrs).
- Feasibility of meeting the GALILEO requirement (65 cm) proven.





- GOAL:
  - qualification of space, ground and user segment through extensive test
  - Analysis of system performance with the view to refine the system prior to full system deployment

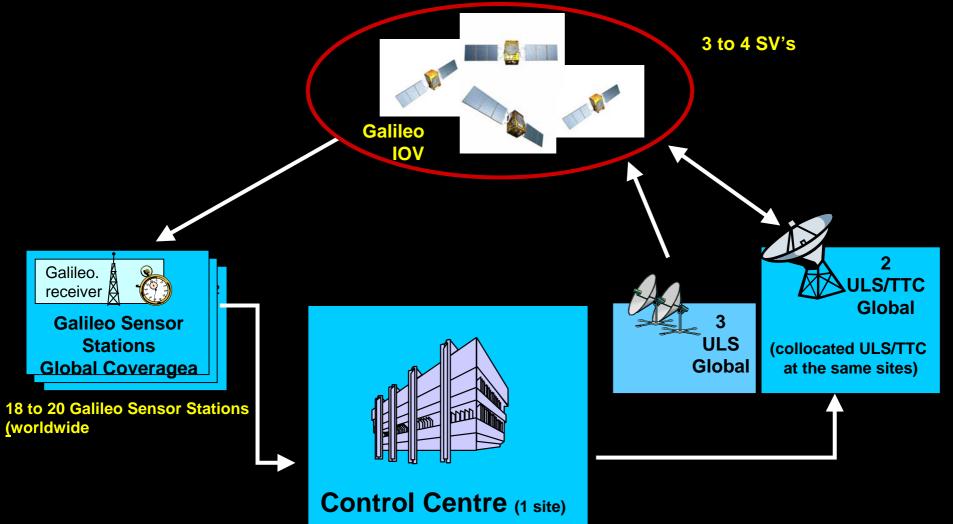
IOV Scope

- Verification of operational procedures
- Deployment risk reduction
- Based on manufacturing and deployment of a limited In-Orbit-Validation (IOV) System Configuration:
  - 1 experimental satellite (GSTB-V2) (early version of operational IOV Sat.)
  - 3-4 operation satellites (considered minimum number required)
  - Associated ground (20 GSS, 5 ULS, 2 TTC, 1 GCC) and test user segment

#### IOV Transition to FOC

• by recurring manufacturing / deployment / integration of IOV system components

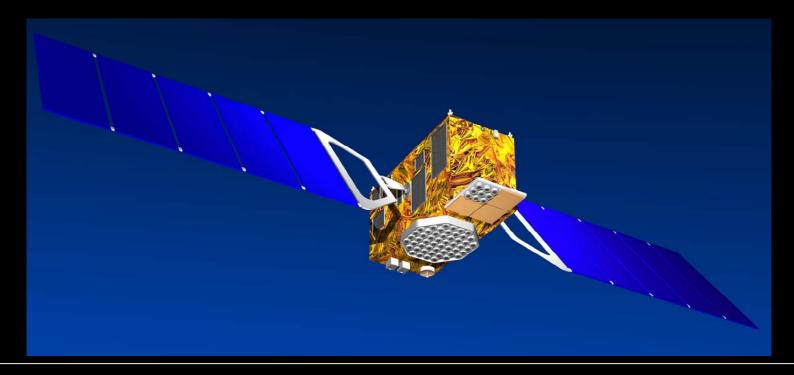
# esa *IOV System Configuration*



# **Galileo IOV Spacecraft**

- Overall Spacecraft: 680 Kg / 1.6 kW class
- Launcher Options: Ariane, Proton, Soyuz, Zenit

- Navigation payload: 115 Kg / 780 W
- SAR transponder: appr. 20 kg / 100 W
- Dimensions: 2.7 x 1.2 x 1.1 m3





# Further information

 Further information is available on the following websites: <u>http://europa.eu.int/comm/dgs/energy\_transport/galileo</u>
 <u>http://www.esa.int/export/esaSA/navigation.html</u>

 Further information on the Joint Undertaking: <u>http://www.galileoju.com</u>