

# Overview of Japanese Lunar CubeSats OMOTENASHI & EQUULEUS

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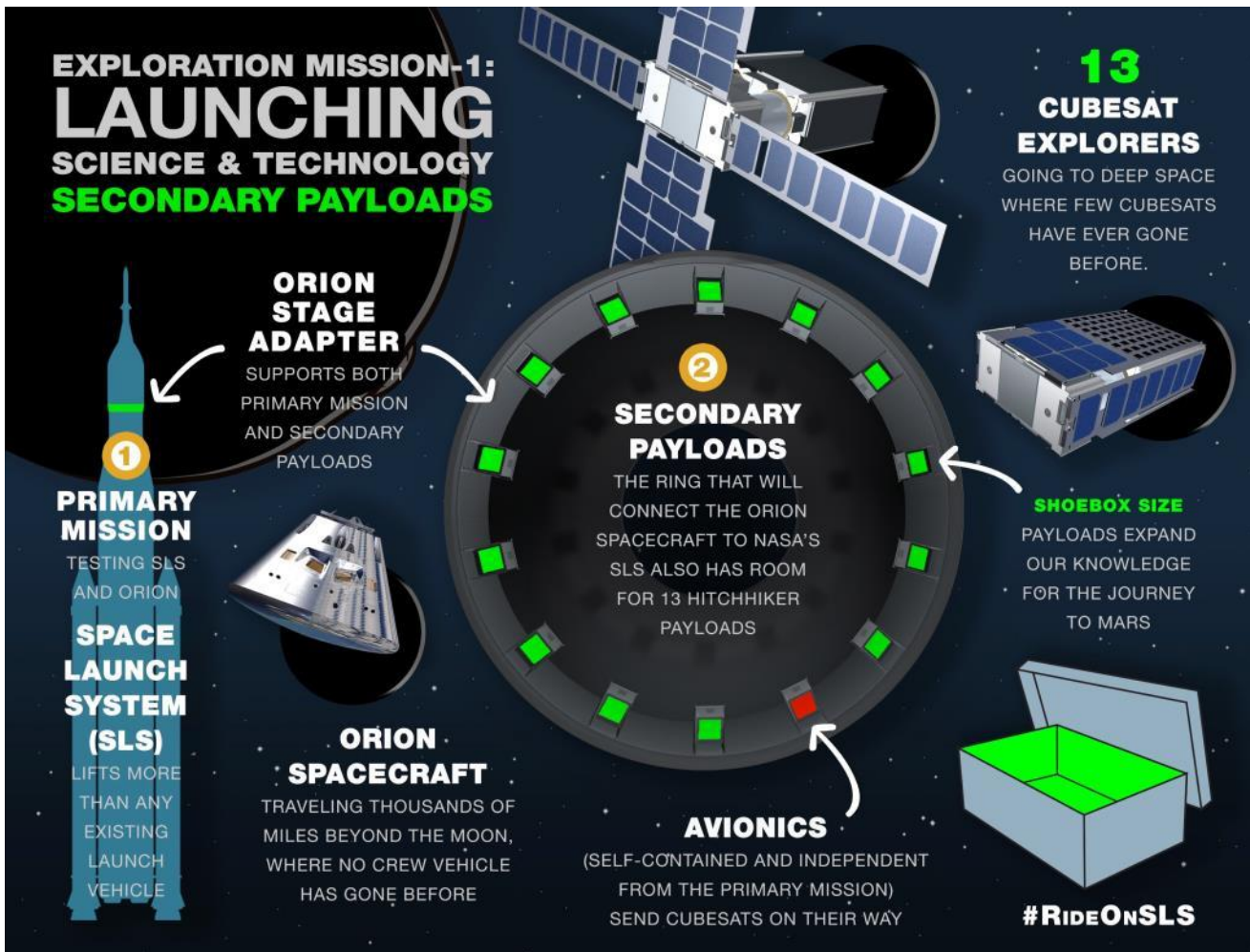
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# Introduction: NASA SLS EM-I



13 CubeSats were selected in Early 2016.

2 of those are EQUULEUS and OMOTENASHI from JAXA/UTokyo

“No harm” to main payload (Orion) policy.

Current launch date: Late 2019



# OMOTENASHI

- Outstanding **MO**on exploration **TE**chnologies demonstrated by **N**ano **S**emi-**H**ard **I**mpactor
  - おもてなし (OMOTENASHI): spirit of selfless hospitality (dictionary definition)
  - Also main slogan of 2020 Tokyo Olympics
  
- World's smallest moon lander
  - A novel approach to landing: No initial orbit, straight to the surface after deployment.
  - 6U, Total mass = ~14 kg
  
- Fulfilling complimentary roles for large-scale manned and unmanned exploration missions by
  - Demonstrating necessary technologies for semi-hard landing
  - Measuring the radiation environment beyond LEO in accordance with Global Space Exploration Roadmap by International Space Exploration Coordination Group (ISECG).

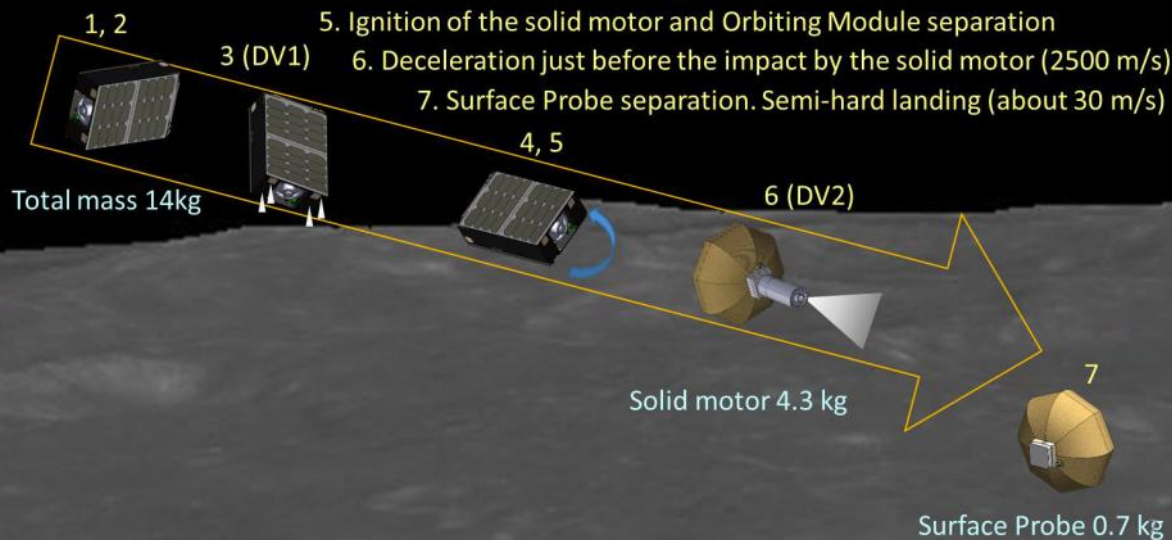


# OMOTENASHI: Mission Sequence

Credits: JAXA

1. Deployment from SLS rocket
2. Spacecraft activation and sun pointing attitude acquisition
3. Orbit control to lunar impact orbit by Gas jet thrusters (10 m/s)
4. Attitude maneuver and spin-up for the deceleration
5. Ignition of the solid motor and Orbiting Module separation
6. Deceleration just before the impact by the solid motor (2500 m/s)
7. Surface Probe separation. Semi-hard landing (about 30 m/s)

Measuring radiation environment



Total of 2 orbital maneuvers,  $dV1$ ,  $dV2$

Attitude spin maneuver before deceleration

Deceleration until "some" (~100-200 m) altitude above the surface

Free fall to the surface with low vertical speed.

Total mission duration: ~5 days

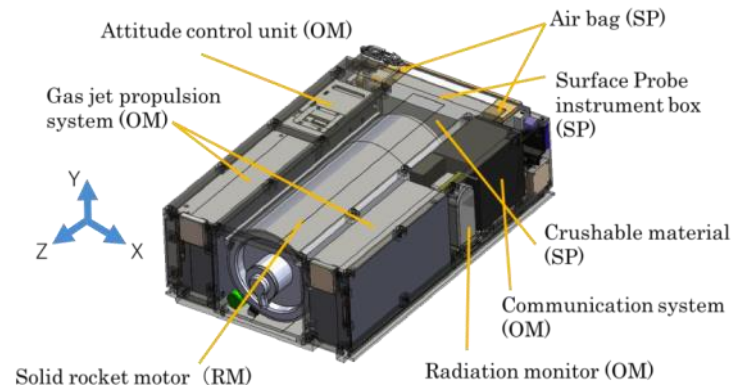
# OMOTENASHI: Spacecraft configuration



Total mass = 14 kg

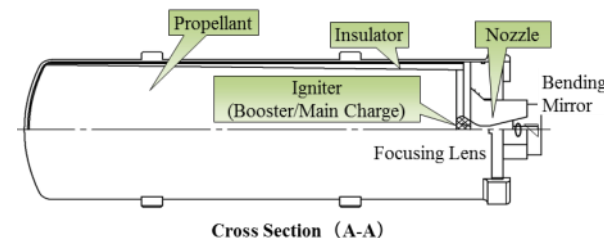
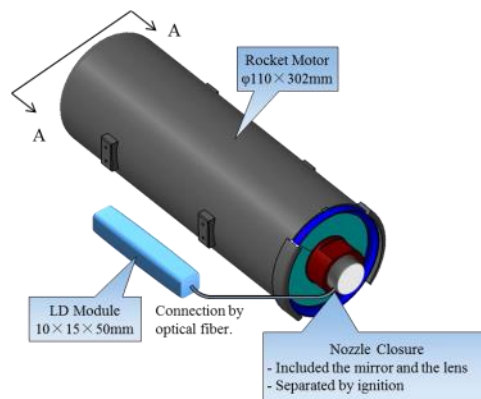
Orbit Module: 8.5 kg  
(excl. RM and SP)

OM carries all spacecraft  
bus and payloads

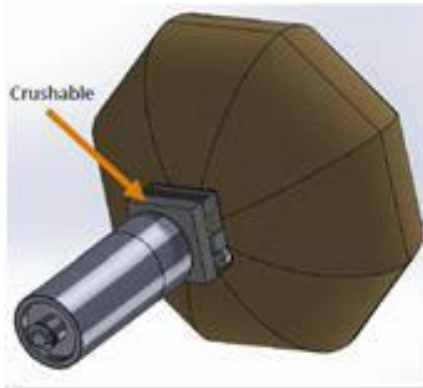


Retro Motor: 4.3 kg (excl.  
OM and SP)

RM is the solid motor that  
decelerates the CubeSat  
to the Lunar surface.



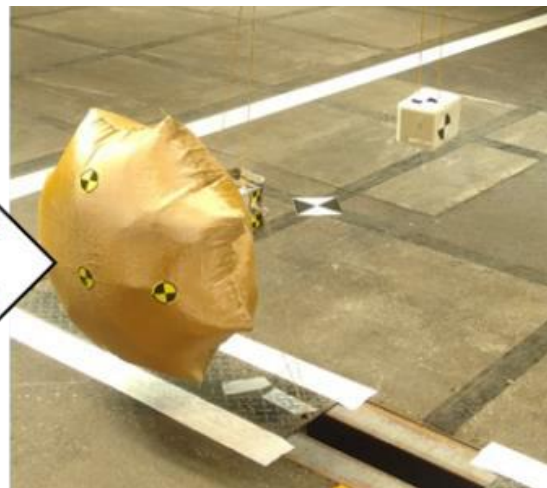
# OMOTENASHI: Spacecraft configuration



Surface Probe: 0.7 kg

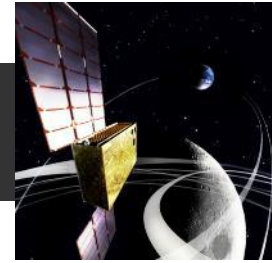
SP carries the landing structure and the transponder for communication (P-band), along with OBC and Power system (Li – 18Wh)

All Credits: JAXA



Crash tests in Japan  
Automobile Research  
Institute.

# EQUULEUS



- **EQU**libri**U**m **L**unar-**E**arth point **6U** **S**pacecraft
  - Also, means small horse (in Latin), one of the star constellations listed by Ptolemy
- World's smallest spacecraft to reach Earth-Moon L2 point
  - 6U, Total mass = ~14 kg
- Primary mission: Demonstration of the trajectory control techniques within the Sun-Earth-Moon region by a nano-spacecraft through the flight to the Earth-Moon Lagrange point L2 (EML2)
- Science missions:
  - Imaging observation of the Earth's plasmasphere
  - Measurement of dust environment in cis-lunar region
  - Lunar impact flash observation (optional)



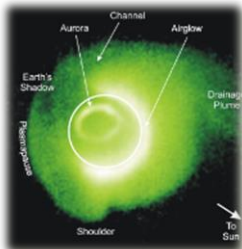
# EQUULEUS: Mission overview

The spacecraft will **fly to a libration orbit around the Earth-Moon L2 point and demonstrate trajectory guidance, navigation and control techniques within the Sun-Earth-Moon region** for the first time by a nano-spacecraft. The mission will also **contribute to the future human exploration scenario** by **understanding the radiation environment in the geospace and characterizing the flux of impacting meteors at the far side of the moon**, and **demonstrating the future deep space exploration scenario using the “deep space port” at Lagrange points.**

## Mission objective #1

### Imaging the Earth's plasmasphere

(Comprehensive understanding of the geospace in cooperation with “ERG” and “Van Allen Probes”)  
(Understanding the Earth's radiation environment)



1. Lunar flyby#1

4. Lunar capture

3. Lunar flyby#3

## Mission objective #2

### Trajectory control within Sun-Earth-Moon region

(Orbit insertion into a libration orbit around the Earth-Moon L2 point using Sun-Earth weak stability regions, for the demonstration of the future exploration mission scenario using the “deep space port”)

0. Post-injection Maneuver  
(within 24hrs from separation)

2. Lunar flyby#2

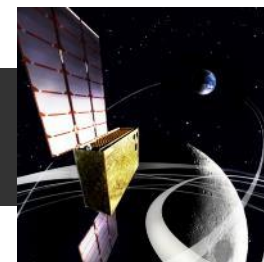
## Mission objective #3 (optional)

- Lunar impact flash observation
- Dust detection at EML2
- Flyby exploration of an asteroid or comet starting from EML2

\* The spacecraft will be disposed to heliocentric orbit after mission completion.



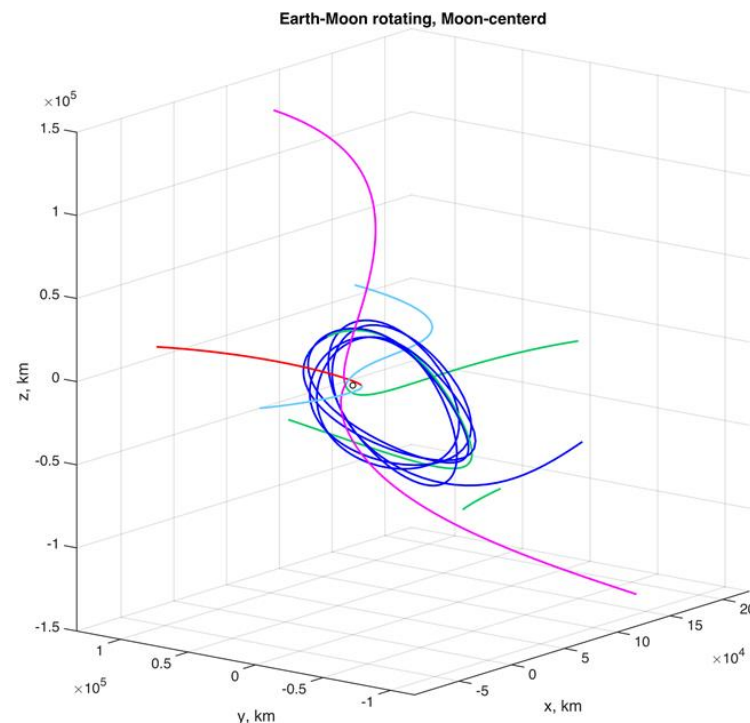
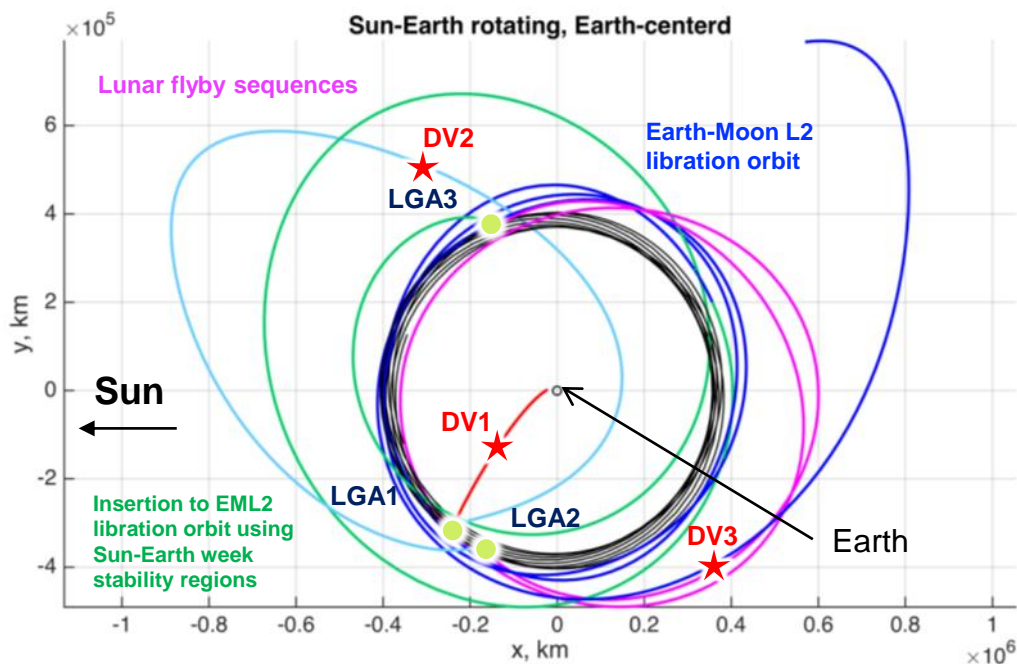
# EQUULEUS: Trajectory



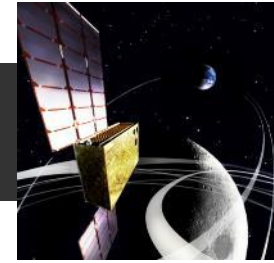
1. Launch and Early Orbit Phase (LEOP) : ~1 week
2. Lunar flyby sequence phase : 1~3 months (full success)
3. Insertion to EML2 libration orbit phase : 5 months
4. Observation (from EML2) phase : > 1 month
5. Departure from EML2 (End of mission)

Simulations are performed for  
Launch Date: July 2018

EQUULEUS will perform **~6-8 months flight to EML2** with DV of **as low as ~10m/s**.



# EQUULEUS: Science Goal #1



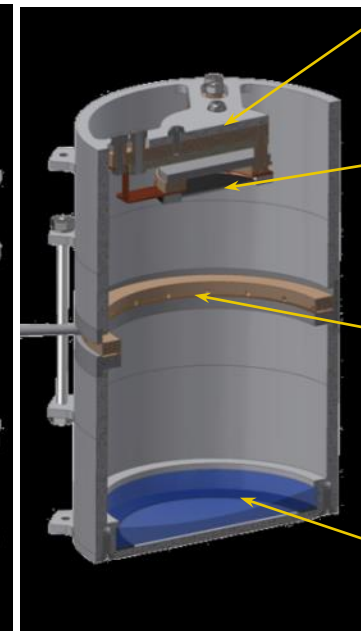
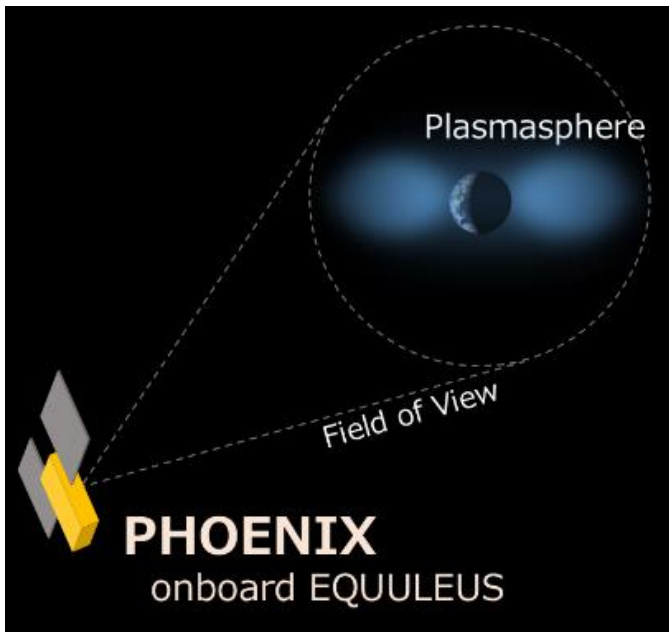
Imaging observation of the Earth's plasmasphere in UV band, enhancing results of ERG and other magnetospheric probes.

Detector (MCP)

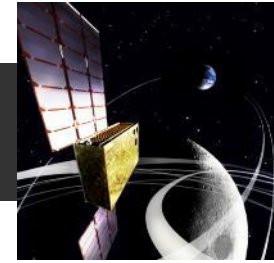
Metal thin film filter

Mechanical shutter

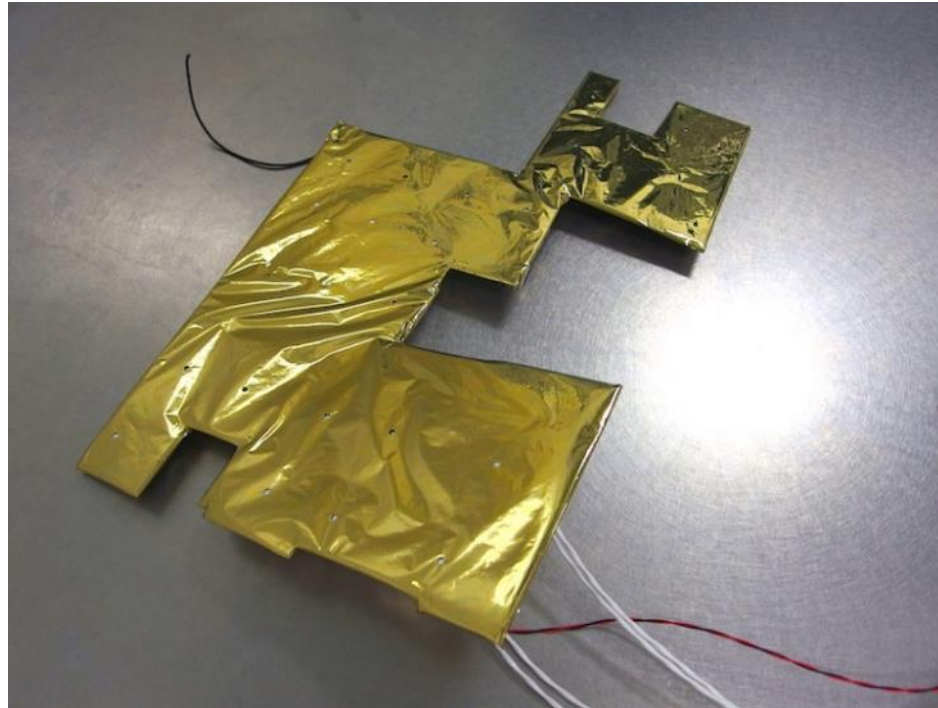
Primary mirror  
(multilayer film optimized for  
He<sup>+</sup> (30.4nm)



## EQUULEUS: Science Goal #2

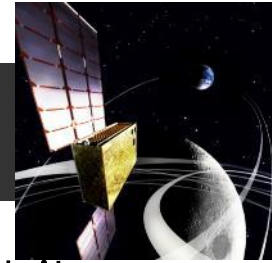


Measurement of dust environment in cis-lunar region along the trajectory

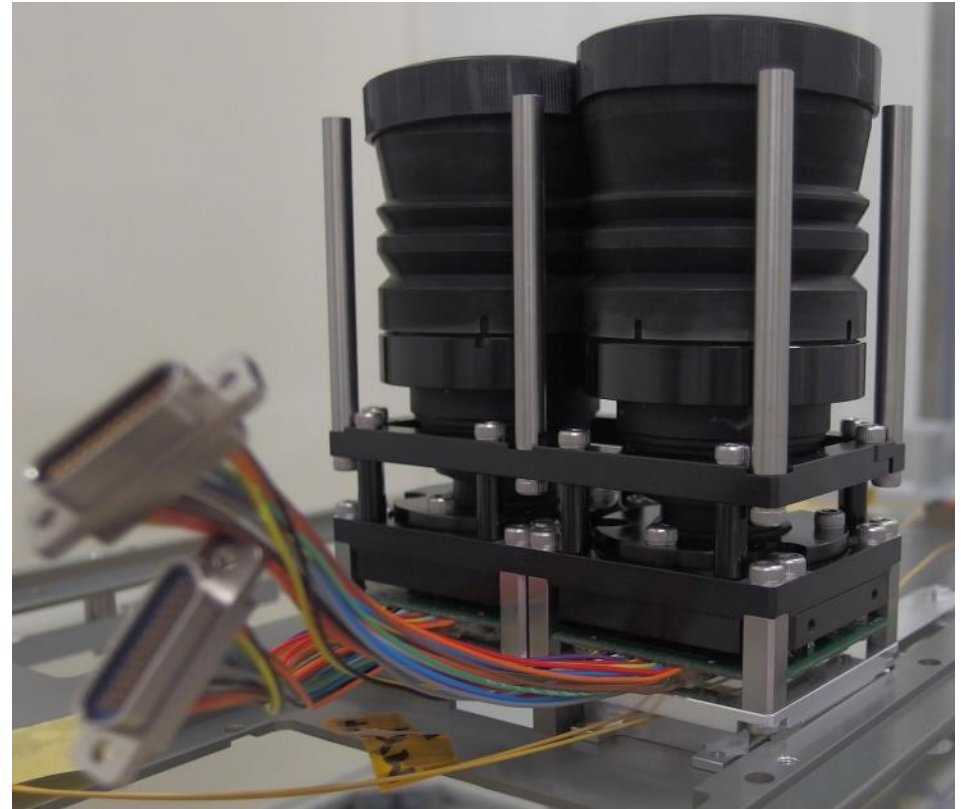


Dust impact sensors installed within spacecraft thermal blanket (MLI)

## EQUULEUS: Science Goal #3



Lunar impact flashes observation from EML2 Halo orbit  
For the first time !



Credits: UTokyo/JAXA

# EQUULEUS: S/C configuration

Solar Array

Paddles  
with gimbal

Ultra-stable Oscillator  
Propellant (water)  
Tank

Transponder

X-Band MGA

X-Band LGA

20cm

Battery

CDH &  
EPS

30cm

X-Band LGA

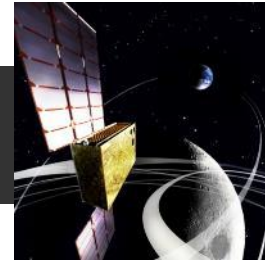
Water resistojet  
thrusters

Attitude control  
unit

PHOENIX (plasmasphere  
observation)

DELPHINUS (lunar impact flashes  
observation)

## Highlights



- OMOTENASHI and EQUULEUS are selected two of 13 CubeSats as to be secondary payload to NASA's EM-1 (Orion) mission.
- They will be world's firsts in several aspects
  - World's smallest moon lander (OMOTENASHI)
  - World's first small spacecraft to reach EML2 (EQUULEUS)
- These CubeSats pave the way for future deep space CubeSats, as well as cargo vehicles to cis-lunar region, by demonstrating novel trajectory control techniques with limited delta-V.
- These CubeSats also do necessary science for future manned/unmanned lunar exploration
- Both currently in testing phase
  - Trajectory design still continues.
- Current launch date is Late 2019
  - Initially was mid-2018, may delay further.

# Thank you !

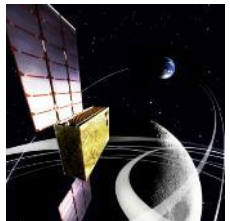
Special thanks to Daniel, Yukiko and local organisers for the support !

Follow the projects on:



Website: <http://www.isas.jaxa.jp/home/omotenashi/index.html>

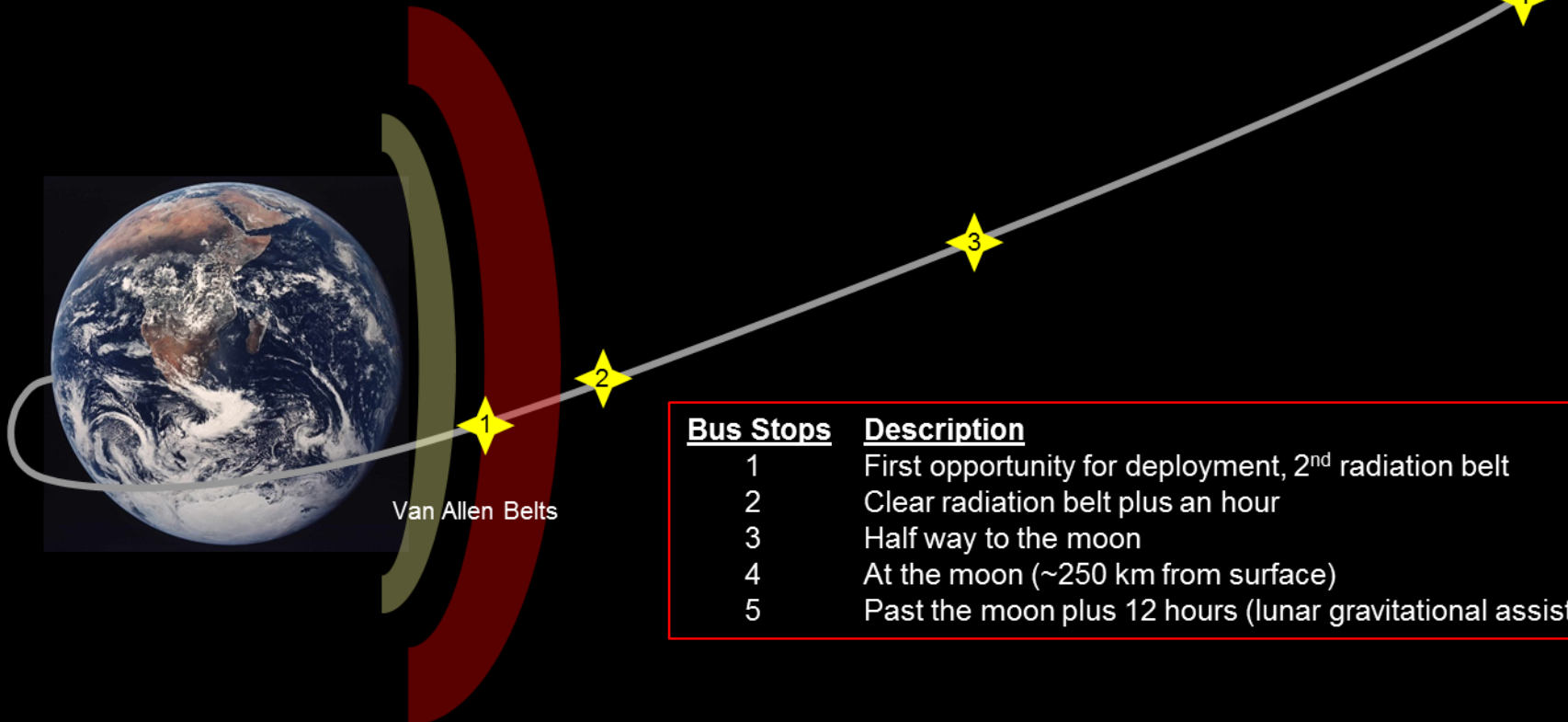
Twitter: @OMOTENASHI\_JAXA



Website: <http://issl.space.t.u-tokyo.ac.jp/equuleus/en/>

Twitter: @EQUULEUS\_en

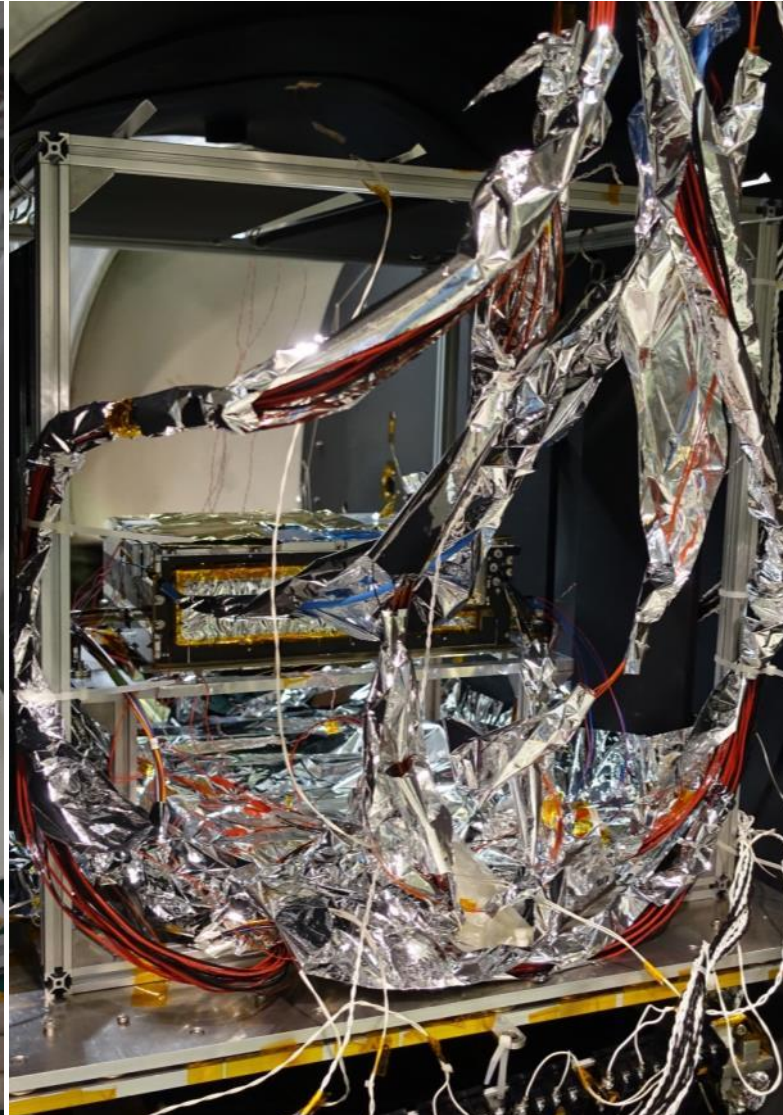
<u>Bus Stops</u>	<u>Distance</u>	<u>Flight Time</u>
1	26,700 km	4 Hrs. & 32 Min.
2	64,000 km	13 Hrs. & 17 Min.
3	192,500 km	3 Days, 10 Hrs. & 18 Min.
4	238,900 km	6 Days, 20 Hrs. & 51 Min.
5	313,400 km	7 Days, 9 Hrs. & 38 Min.

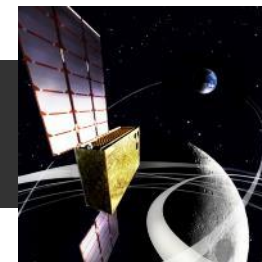


<u>Bus Stops</u>	<u>Description</u>
1	First opportunity for deployment, 2 <sup>nd</sup> radiation belt
2	Clear radiation belt plus an hour
3	Half way to the moon
4	At the moon (~250 km from surface)
5	Past the moon plus 12 hours (lunar gravitational assist)



# EQUULEUS: Current status





# EQUULEUS: Advancements

- Miniaturization of the deep space bus (e.g. deep space communication transponder) into the CubeSat form factor

XTRP demonstrated in PROCYON  
(2014)



\*XTRP: X-band Transponder

- \* Miniaturization
- \* Modularization
- \* Reduction of RF output
- \* Reduction of power consumption

XTRP being developed for  
CubeSat  
(EQUULEUS)



Digital Processing Module & Rx  
Module



Power Amplifier & XTx Module

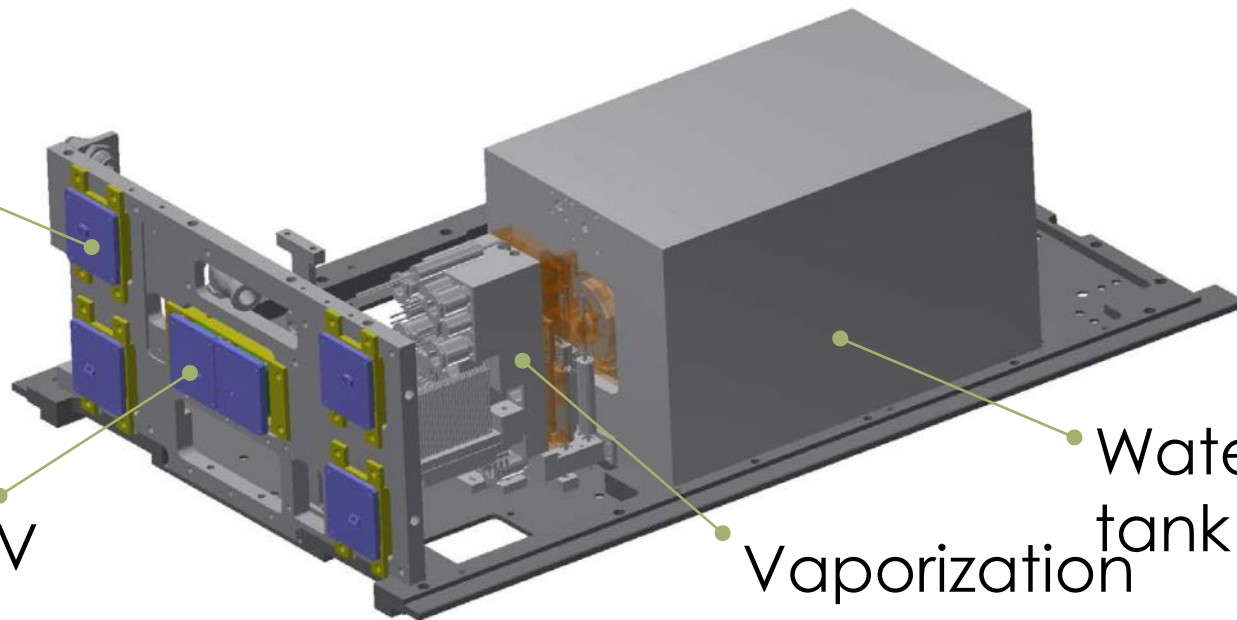


## EQUULEUS: Advancements

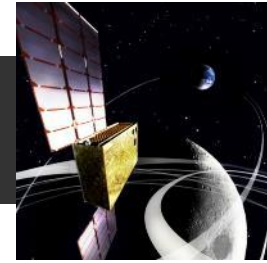
- Development of the new resistojet (warm gas) **propulsion system using water** as the propellant.
  - Water is **perfectly safe, non-toxic propellant**, which is advantageous when we consider piggyback launch.
    - Isp = 70 sec, 2+4 uN, total delta-V ~80 m/s.
  - Future in-situ space resource utilization age

4 x RCS  
thrusters

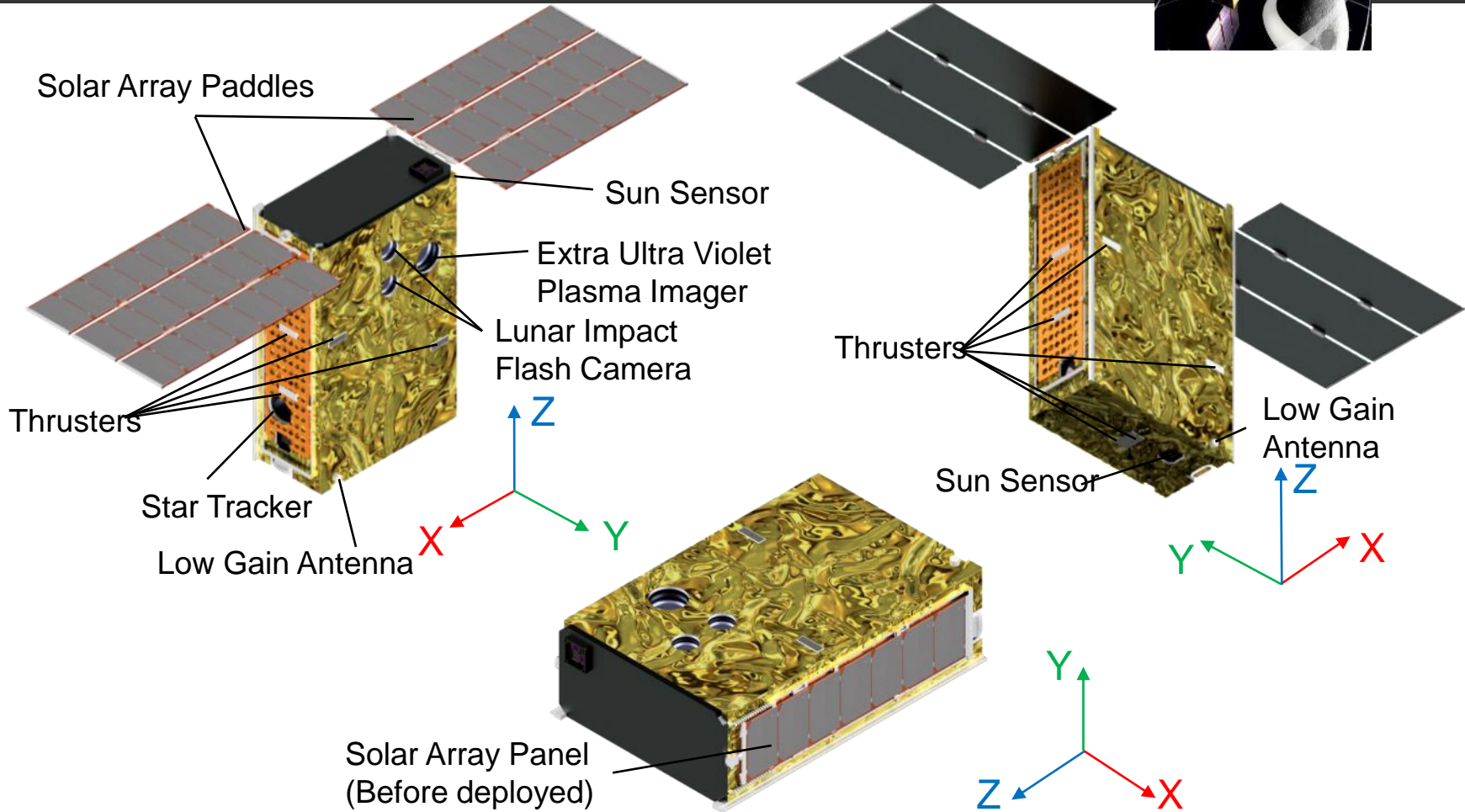
2 x Delta-V  
thrusters



Water  
tank  
Vaporization  
chamber



# EQUULEUS: S/C Overview



**EQUULEUS has fundamental bus systems for deep space missions within 6U CubeSat (deep space communication, power, thermal control, attitude control, propulsion).**