

## Techniques for resilient time provision and GNSS spoofer/jammer eraser

Advanced Algorithms and Techniques for Resilient Time Provision (ESA AO/1-10897/21/NL/AS)

Block-Box for an Optimized GNSS Spectrum Monitoring Network Using Artificial Intelligence (ESA AO/1-11383/22/NL/CW)

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# Advanced Algorithms and Techniques for Resilient Time Provision

Huld together with  
University of West Bohemia  
Czech Republic



## Objectives

### Timing source units

Various local oscillators/clocks  
(from cheap to expensive models)

Internet time protocols  
(NTP, PTP, White Rabbit)

Radio timing services  
(DCF77)

Navigation systems  
(GNSS, eLoran)

Signals of opportunity  
(DAB, DVB-T2, FM transmitters)

Various other sources  
(Pulsar-based timing)

### Signal processing unit

**Time fusion**

**&**

**Fault detection  
algorithms**

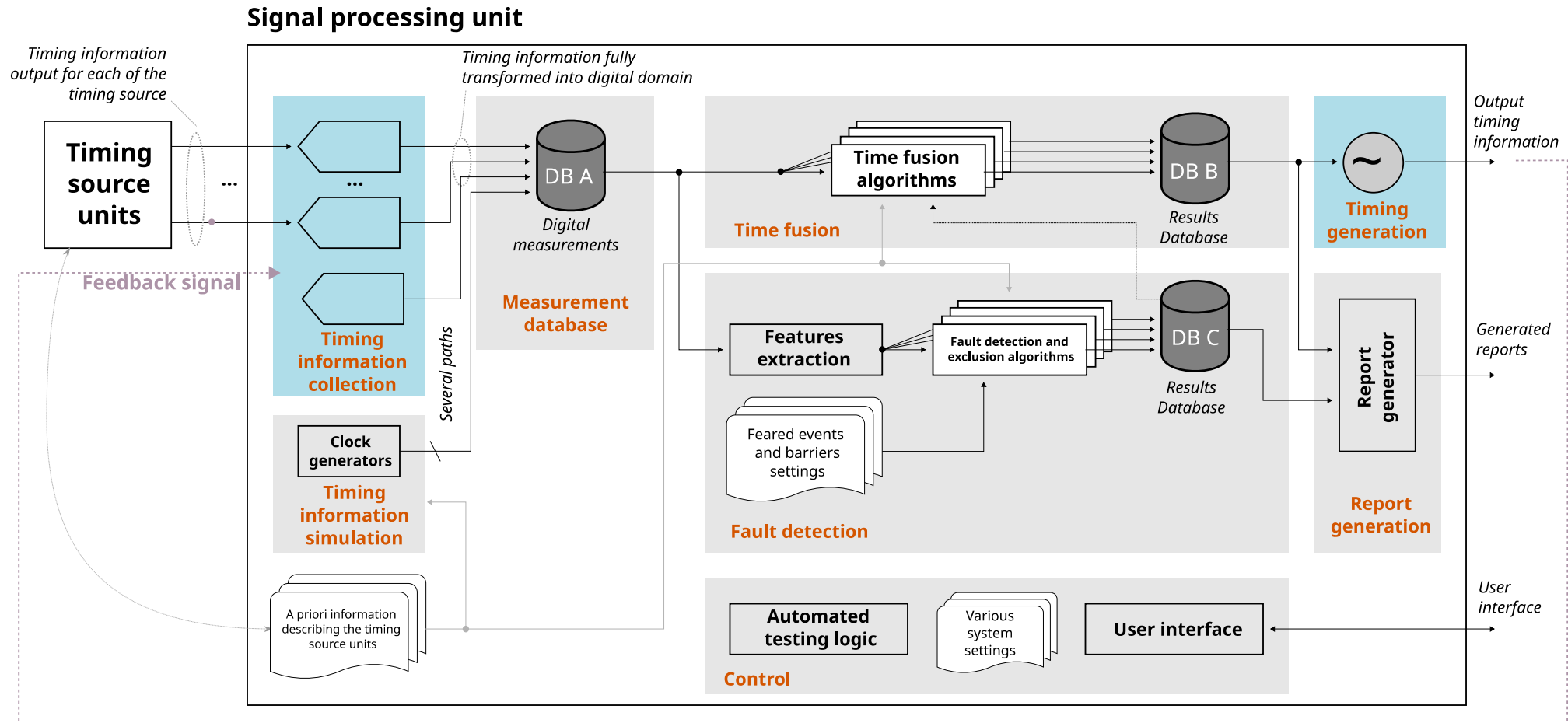
Kalman filter-based  
AI/ML-based

*Including evaluation  
of various metrics such as  
stability, accuracy,  
integrity, and availability.*

Timing information with  
assessed and evaluated  
performance criteria

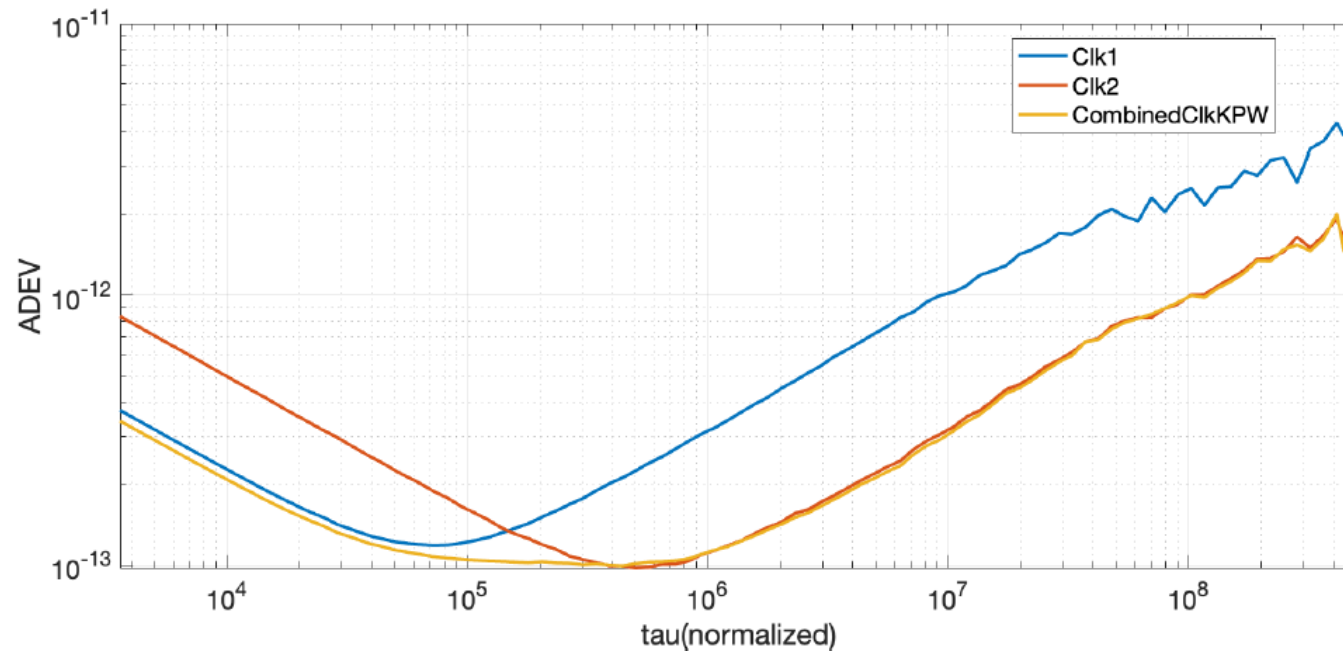


## System overview



# Clock combination

- Optimal ensemble of clocks leads to better frequency stability, and it is better than any of the individual clocks
- Modern clock combination algorithms are based on Kalman filter (and state-space models)

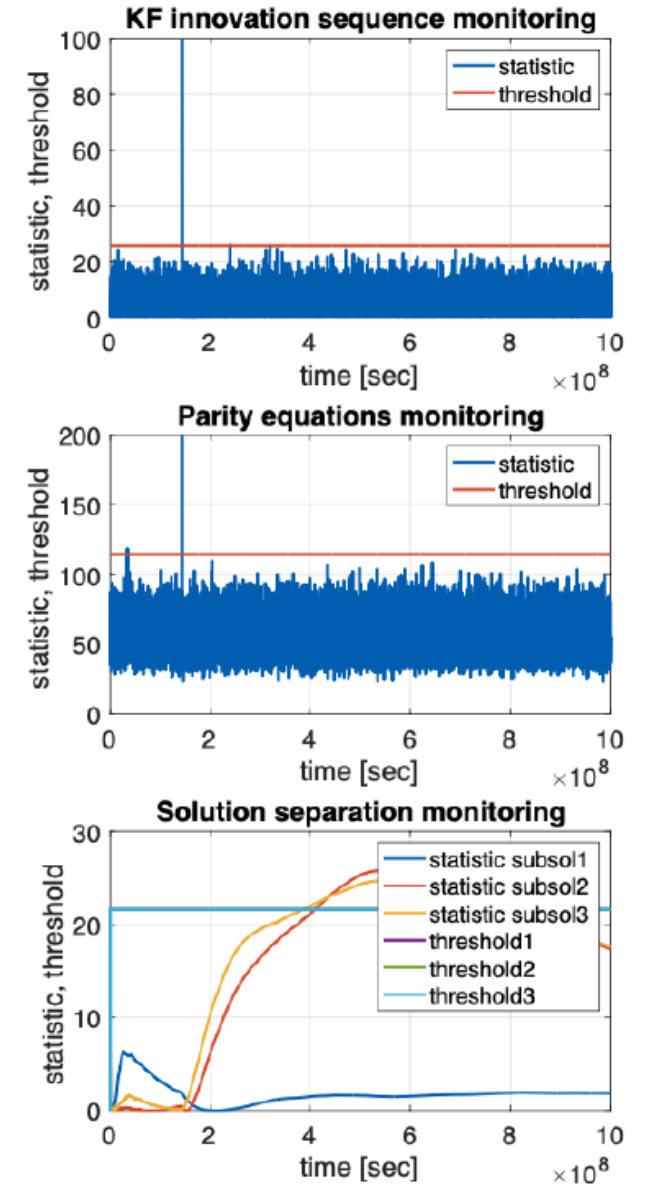


## Fault detection

- Reliable clock ensemble requires not only algorithms for clock combination but also algorithms for fault detection of the input clocks
- State-of-the-art literature mentions several signal-based (SB) fault detection techniques, often designed ad-hoc (based on user defined thresholds).
- We have considered additional two groups of fault detection techniques
  - Statistical (model-based)
  - AI/ML (data-based)

## Fault detection | Statistical tests

- Parity equations
- Kalman filter innovation sequence monitoring
- Solution separation



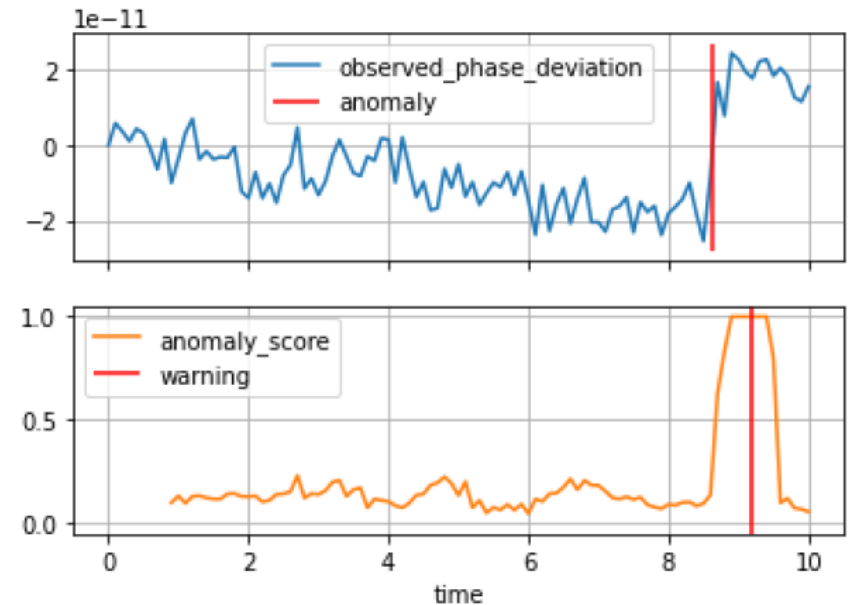
# Fault detection | ML-based

## Detection ML Algorithms

- *Assumption:* Anomalous (faulty) data are not at disposal for all possible faults
- *Idea:* Train AI/ML model for nominal conditions
- Suitable for abrupt faults
- 10 methods from Python Outlier Detection (PyOD) library

## Classification ML Algorithms

- *Assumption:* Anomalous (faulty) data are available for all possible faults
- *Idea:* Train AI/ML model for all faulty conditions
- Sensitive for certain slowly growing errors
- 10 methods from Python Scikit-learn library

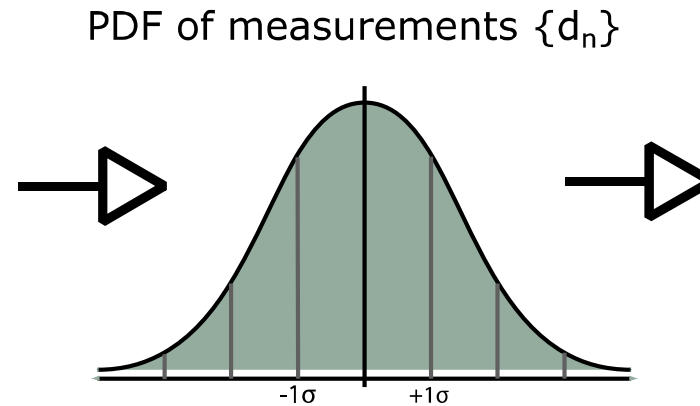
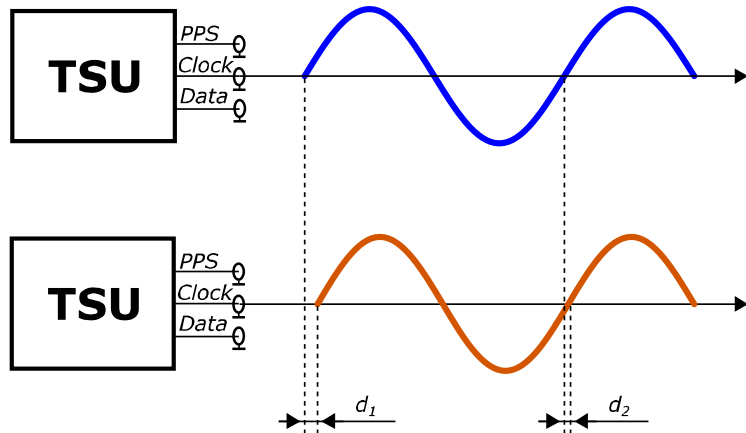




# Accuracy requirements

- The developed system shall be useful for generating clock ensemble based on atomic clocks

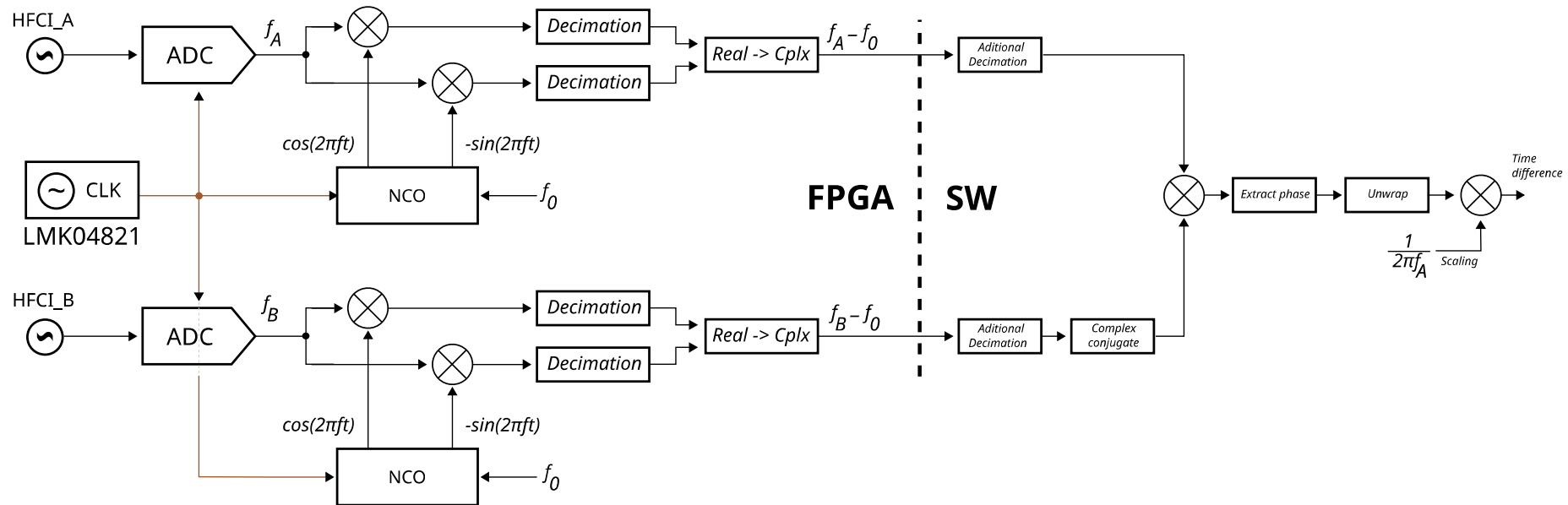
Accurate and stable  
Timing Source Units



$+1\sigma$  shall be  
smaller than 1 ps

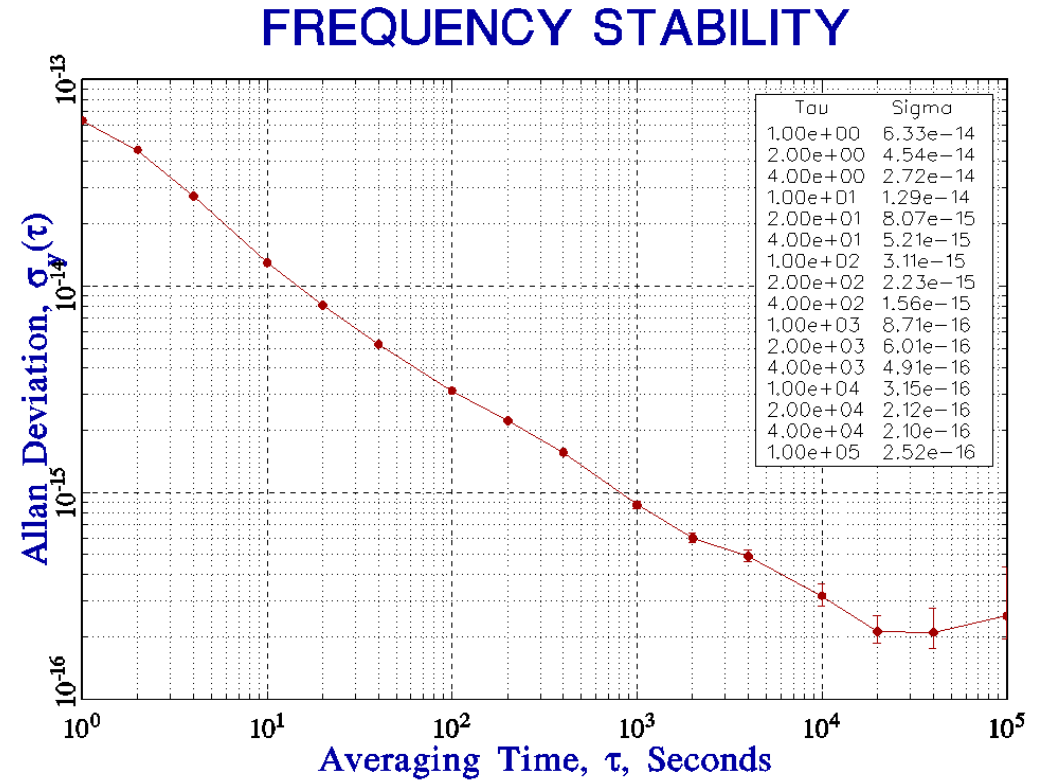
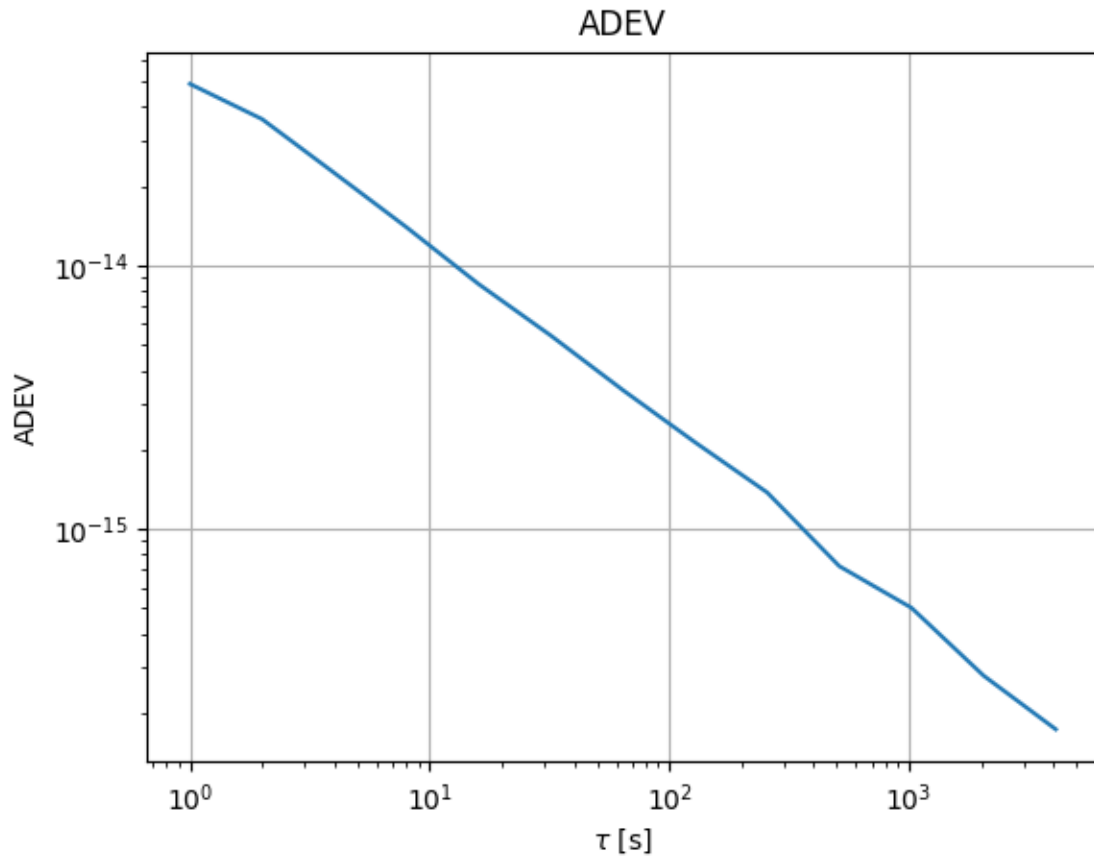
## Measurements technique

- Dual Mixer Time Difference (DMTD) method
- **Direct analog to digital conversion**



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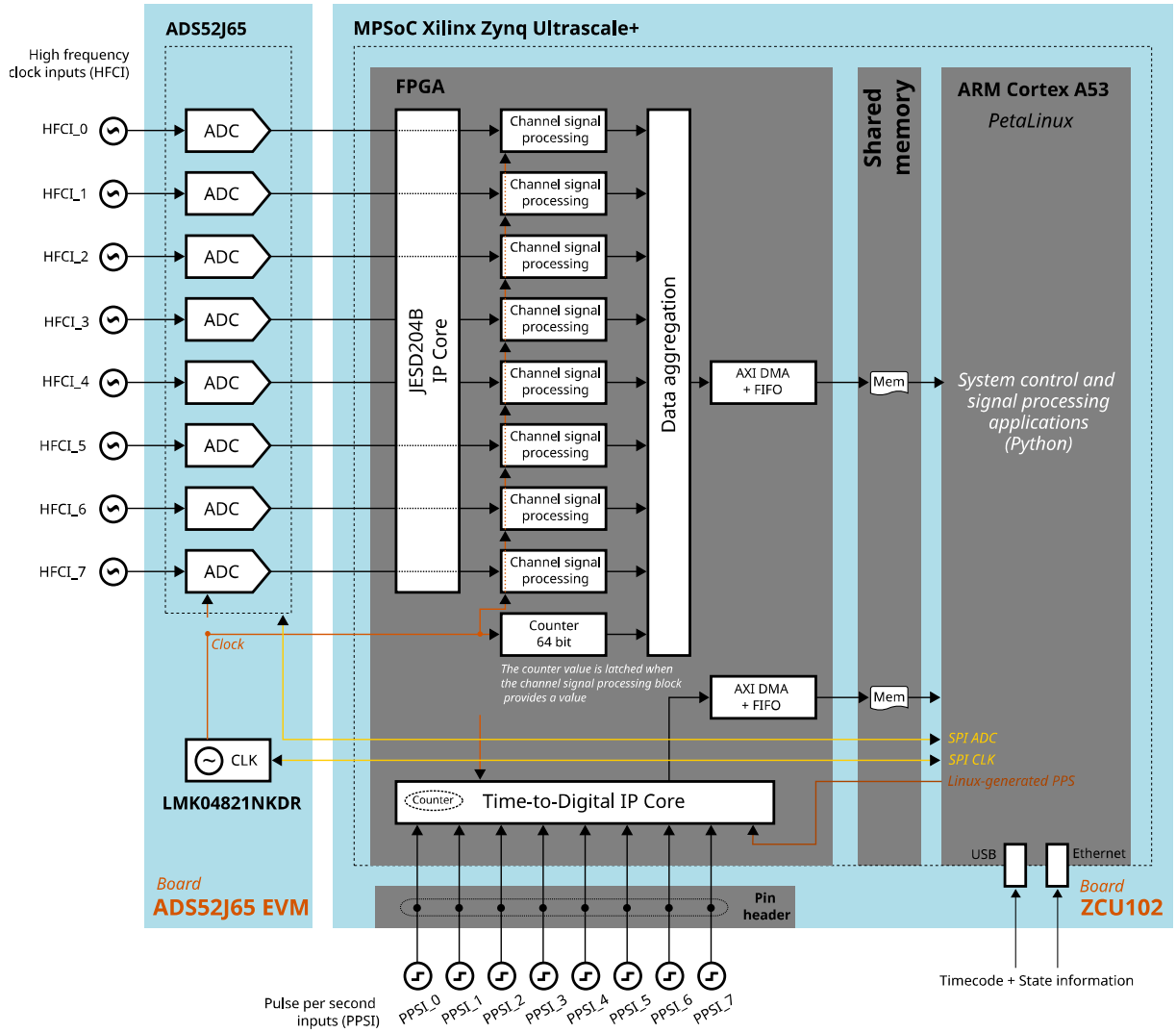
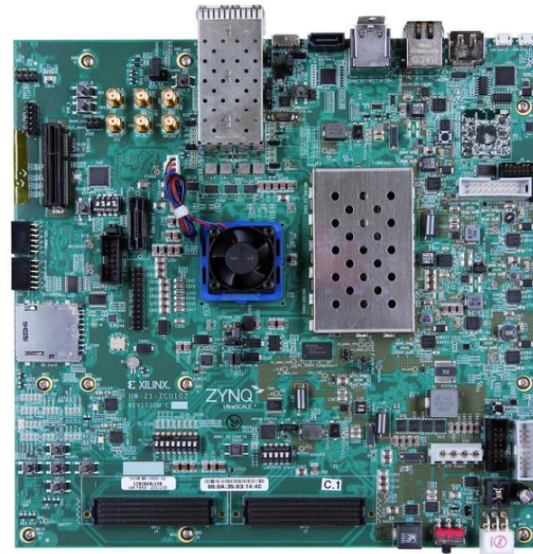
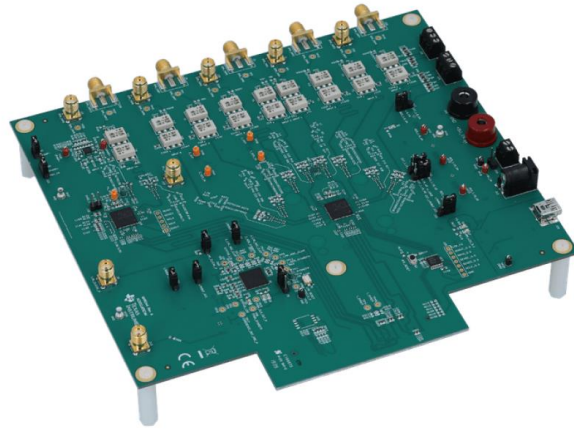
## Preliminary characterization



iMaser 3000<sup>TM</sup>  
SMART ACTIVE HYDROGEN MASER CLOCK

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## System

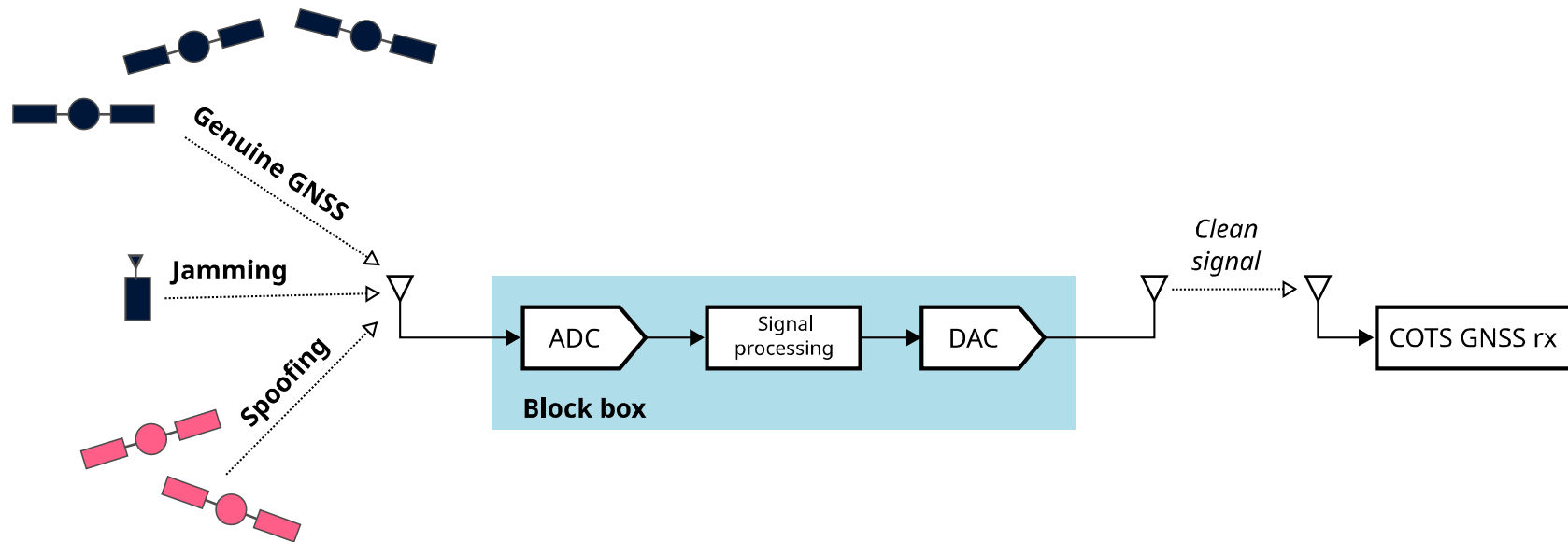


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# Block-Box for an Optimized GNSS Spectrum Monitoring Network Using Artificial Intelligence

## Objectives

- System capable of detecting and mitigating GNSS jamming and spoofing using state-of-the-art AI/ML techniques
- SW and HW demonstration (Python, FPGA)

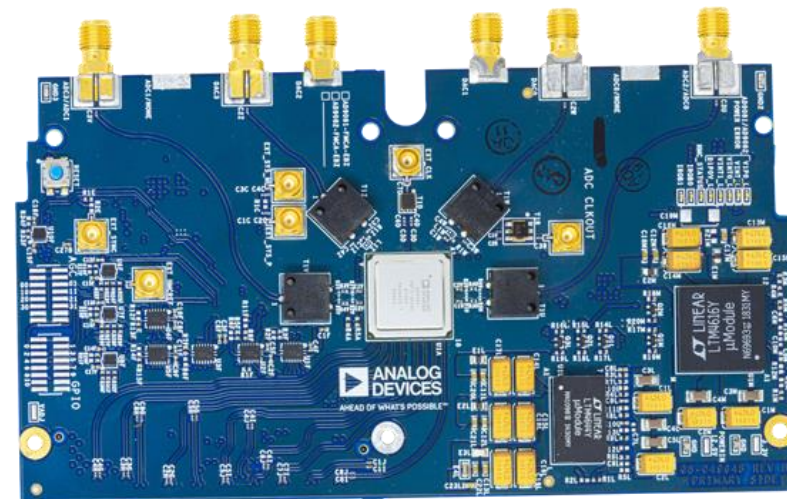


## Scope

- Definition of threats, detection metrics and mitigation techniques for GNSS signals
- FPGA as development and validation HW platform (Xilinx Zynq, AD MxFE 9082)
- Execution of AI algorithms, DSP, mitigation, signal retransmission, ... in real-time in HW
- Supported frequency bands: E1, E5, E6
- Cloud SW as backend application allowing customized training and control

**AD9082**

MxFE Quad, 16-Bit, 12 GSPS RF DAC and Dual, 12-Bit, 6 GSPS RF ADC



## Development approach

- Preliminary design of **anti-jamming** algorithms based on simulated data
- Preliminary design of **anti-spoofing** techniques based on available spoofing data sets:
  - **OAKBAT** (Oak Ridge Spoofing and Interference Test Battery)
  - **TEXBAT** (Texas Spoofing Test Battery)
- After this preliminary stage, the real signals are used



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## Machine learning

- Classification
- Segmentation
- Reinforcement learning
- Training with various inputs
  - Spectrogram, AGC, Correlation function, PVT
- Finding dependence between clean signal and jammed/spoofed signal



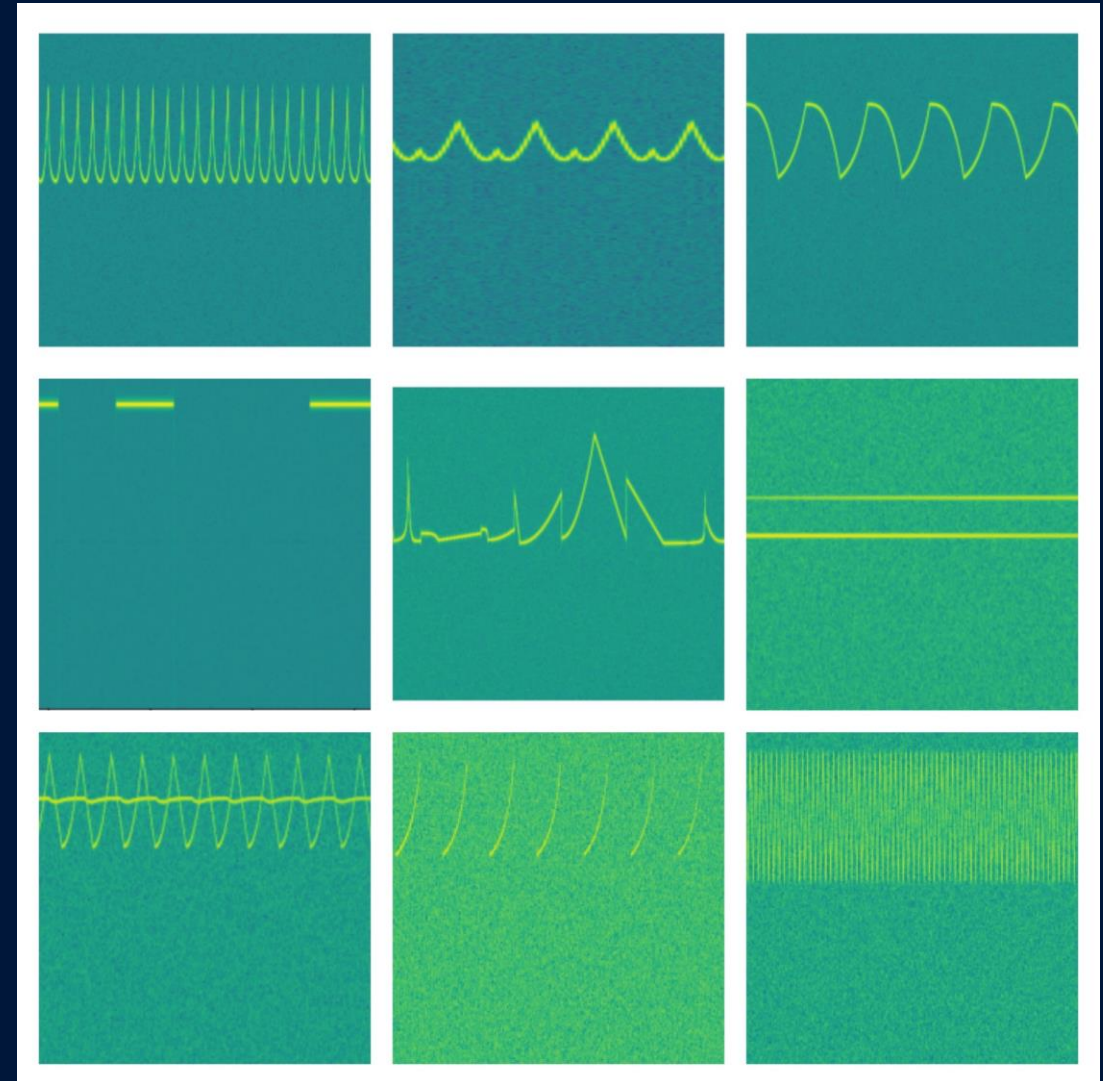
# Jamming

## Types of jamming

- Chirp
- Pulse
- Single tone
- Constant or variable amplitude
- Combination of above
- Multiple jammers

## AI input

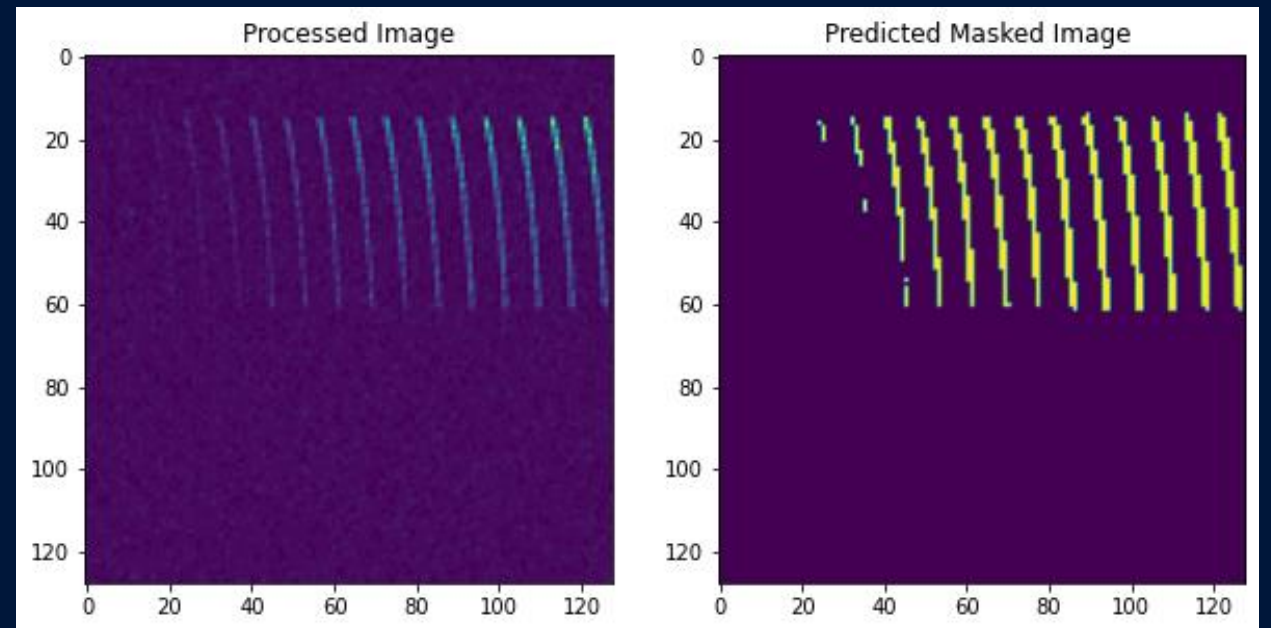
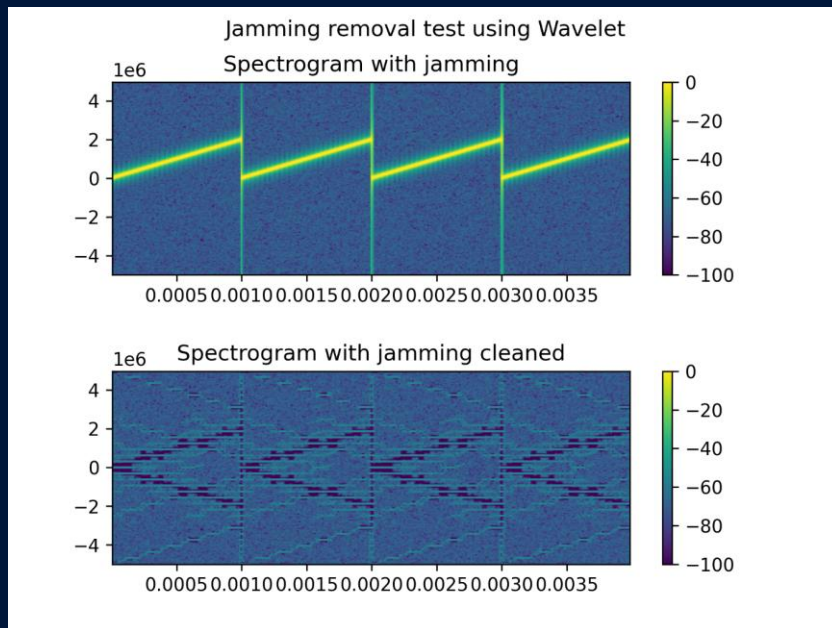
- Spectrogram
- ADC histogram





# Jamming mitigation

- DSP with AI-derived parameters
- FDAF (Frequency Domain Adaptive Filtering)
- STFT or Wavelet transformation





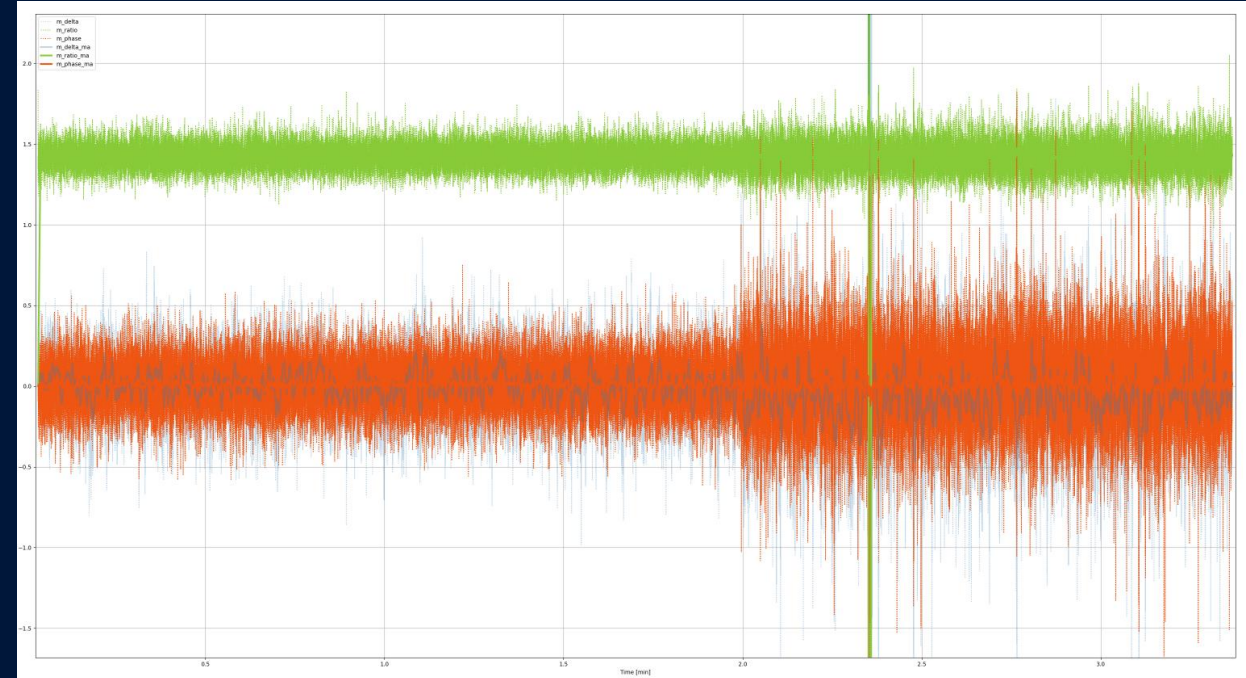
## Spoofer

### AI spoofing detection based on

- event (change of parameters)
- state (don't need to catch start of spoofing)

### AI input

- Correlation function
- $C/N_0$
- SQM (Signal quality metric)
  - Delta, Ratio, early/late phase metrics



- Delta Metric

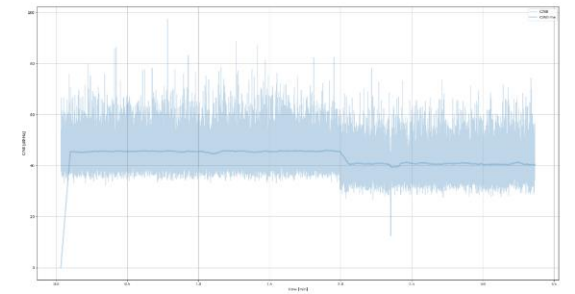
$$m_{\text{delta}} = \frac{I_{-d} - I_{+d}}{I_p} \quad (6)$$

- Ratio Metric

$$m_{\text{ratio}} = \frac{I_{-d} + I_{+d}}{I_p} \quad (7)$$

- Early Late Phase Metric

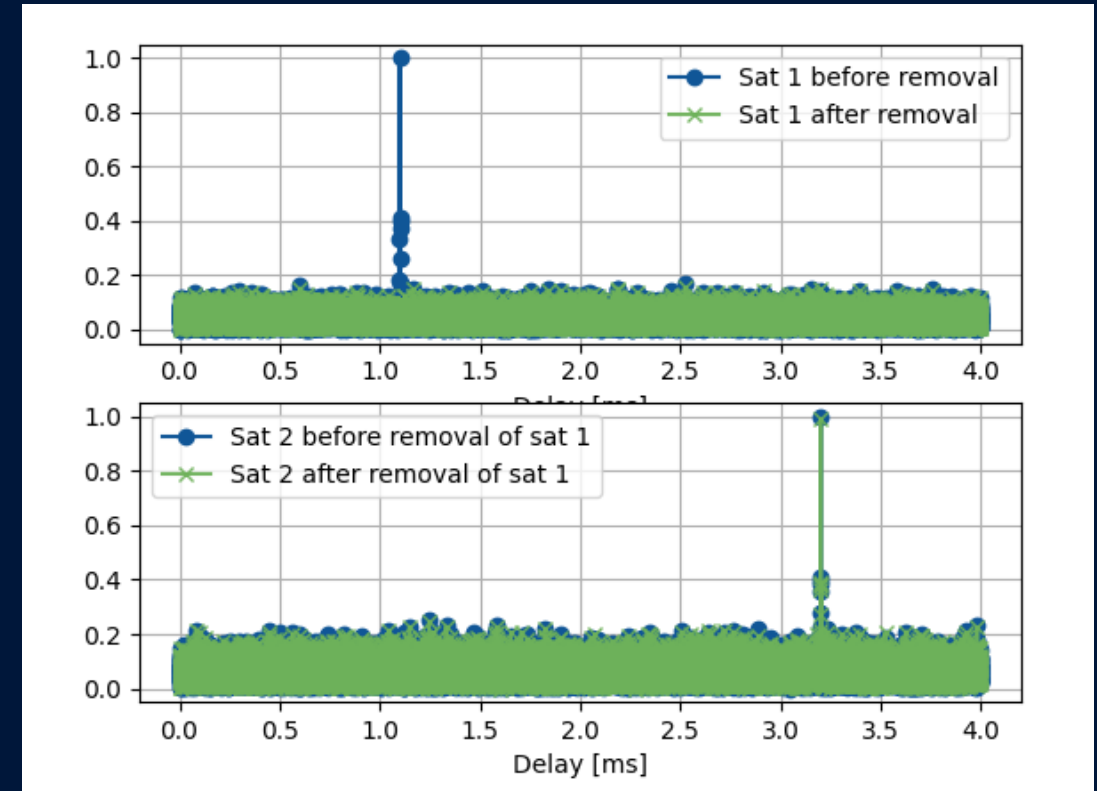
$$m_{\text{elp}} = \tan^{-1} \left( \frac{Q_{-d}}{I_{-d}} \right) - \tan^{-1} \left( \frac{Q_{+d}}{I_{+d}} \right) \quad (8)$$





# Spoofing mitigation

- Classical tracking of the signal to be mitigated
- Subtracting of the tracked component from the stream of baseband samples



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Beyond tomorrow