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Statistical approaches of ionospheric correction to improve the accuracy of the GPS positioning over Malaysia

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Introduction

- The ionosphere is a shell of electrons and electrically charged atoms and molecules that surround the Earth, stretching from a height of about 50 km to more than 1,000 km.
- The ionosphere varies to several factors such as diurnal variation, seasonal variation, solar cycle, geomagnetic effect, etc.→ geographical location
- The propagation of radio signals in the Earth's atmosphere is dominantly affected by the ionosphere due to its dispersive nature.
- Global positioning system (GPS) data provides relevant information that leads to the derivation of total electron content (TEC).
- The TEC is one of the most important parameters that describe the ionospheric state & structure.





Motivation

- Ionosphere is the main error source for the GPS signal
- Klobuchar model can only reduce 50% of the ionospheric error
- The study of the ionospheric delay forecasting is beneficial to improve and develop the ionospheric models.
- It is important to select the suitable prediction model that can correct the ionospheric delay errors to further improve the accuracy performance of GPS positioning

Objective

- **1**. To analyse the short-term forecasting ionospheric delay using statistical Holt-Winter method
- 2. To Compare Holt-Winter method with IRI-2012

Methodology

- **GPS** Ionospheric Scintillation and TEC Monitor (GISTM), model GSV4004B by **GPS Silicon Valley**
- NovAtel Euro-3M dual-freq. receiver
- Measure amplitude and phase scintillation • from the L1 frequency GPS signals
- TEC from the L1 and L2 frequency GPS signals.

TEC = [9.483 * (PRL2 - PRL1 - C/A-P, PRN) +TECRX + TECCAL] TECU

PRL2 is the L2 pseudo-range in meters, PRL1 is the L1 pseudorange in meters, C/A-P,PRN is the input bias between SV C/Aand P-code code chip transitions in meters, TECRX is the TEC result due to internal receiver L1/L2 delay, TECCAL is the user defined TEC offset



- NovAtel GSV 4004B GPS receiver 1. 2.
 - **GPS** Antenna
- 3,4,5,6. **Connection cable (30 m maximum)**
 - PC processing data,
 - UPS

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• GISTM provide slant TEC that can be converted to Vertical TEC

 $VTEC = STEC \cos \chi'$

• Delay between the L1 and L2 signal

$$I_k^p = 40.3 \text{VTEC}\left(\frac{1}{f_2^2} - \frac{1}{f_1^2}\right)$$

• Percentage deviation between the model and GPS-TEC

$$\% PD = \frac{VTEC_{\text{model}} - VTEC_{\text{GPS-TEC}}}{VTEC_{\text{GPS-TEC}}} \times 100$$





- **Holt-winter** is statistical method that can be used to forecast the ionospheric delay, producing short-term forecasting by employing level, trend and seasonal components at each period of the time-series.
- $F_{t+m} = (L_t + b_t m) S_{t-s+m}$

 L_t , is the level; b_t , is the trend; S_t , is the seasonal; Y_t , is the VTEC, while t is the time period for the component of L_t, b_t , S_t and Y_t . F_t , is the forecasting value of a period ahead; F_{t+m} , is the forecasting time period. m, is the forecast period and s is the seasonal duration.

• Mean Absolute Percentage Error (MAPE) to measure the suitability and accuracy of a forecasting method

$$PE_{t} = \left(\frac{Y_{t} - F_{t}}{Y_{t}}\right) \times 100 \qquad \text{MAPE} = \frac{1}{n} \sum_{t=1}^{n} \left| PE_{t} \right|$$

PE is the percentage of error, Y_t , is the VTEC

Ref:. Suwantragul, S., Rakariyatham, P., Komolmis, T. and Sang-In, A., 2003. A modeling of ionospheric delay over Chiang Mai Province. Proc *IEEE Int Symp Circuits Syst.* 25(2), 340-343.

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Data processing

- Use GISTM data located at:
 - Langkawi (6.19°N, 99.51°E)
 - UKM, Bangi (2.92° N, 101.78°)

- Period:
 - January to December 2011, 2014



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Results

Comparison of

- 1. GPS TEC variations with Holt-Winter method and
- 2. With IRI-2012
- Diurnal
- Monthly
- Seasonal

Diurnal variation of the actual and forecast ionospheric delay using the Holt-Winter method over UKM station during 7 April 2011



Monthly variation of the actual and forecast ionospheric delay using the Holt-Winter method during 2011 over UKM station



Actual — Forecasting

Month to month variation of the actual and forecast ionospheric delay using the Holt-Winter method



Seasonal variation over UKM and Langkawi station during 2011

Winter (January, February, November, December), Summer (May, June, July, August) Equinox (March, April, September, October)



Comparison of the Holt-Winter method with IRI-2012 over Langkawi station in 2014



Comparison of the seasonal VTEC from GPS-TEC with IRI-2012 topside options and Holt-Winter method and their %Dev



Closer inspection to illustrate the %Dev of the Holt-Winter method during the time period from 10:00 to 19:00 LT.



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Accuracy of prediction model



• That can be conclude that the Holt-Winter method indicates high performance and better estimate of the VTEC prediction

Conclusion

- Holt-Winter can be used to forecast ionospheric delay and show higher accuracy compare to the IRI-2012 model
- Help to mitigate ionospheric error in GPS positioning for better accuracy

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