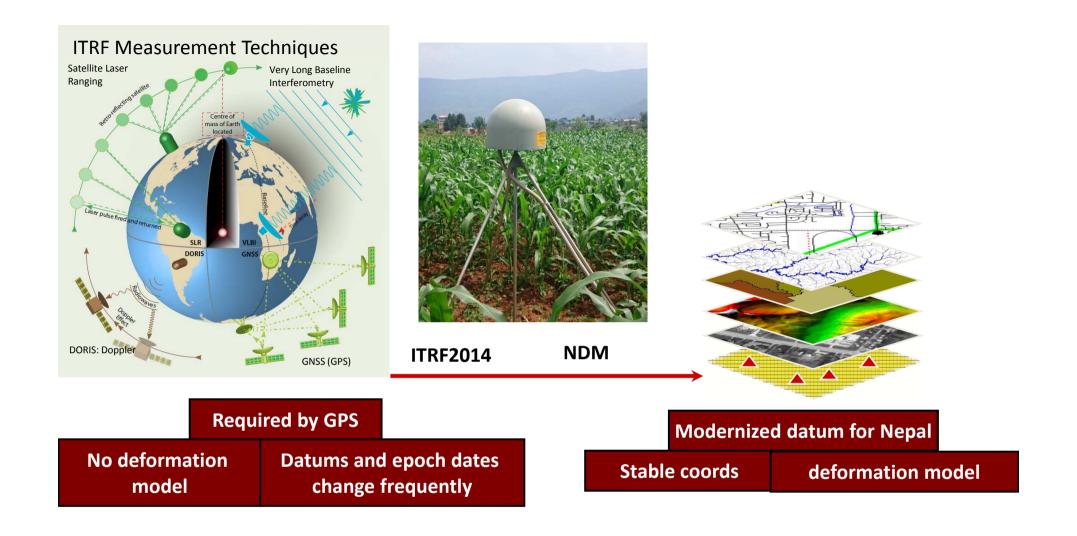




Recent progress towards a modernized geodetic datum for Nepal

Chris Pearson Niraj Manandhar

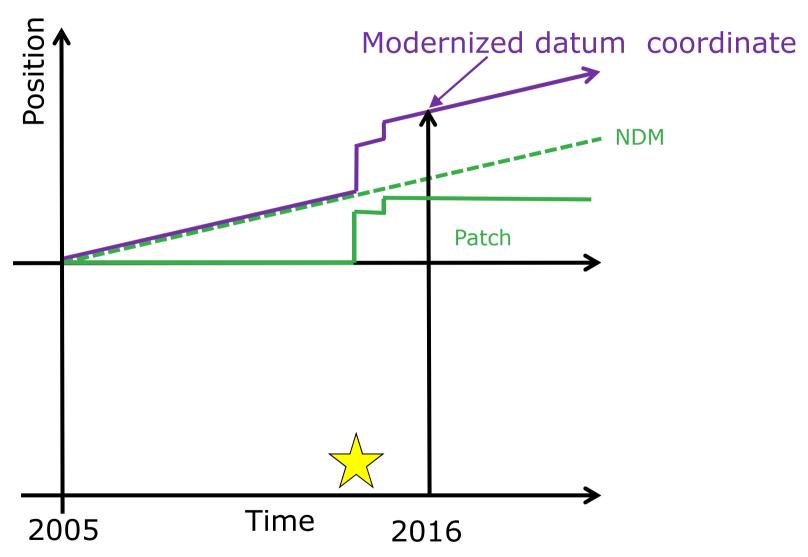


Modernized geodetic datum aligned with ITRF2014 Coordinates transformed to 1 Jan 2016 using the a national deformation model



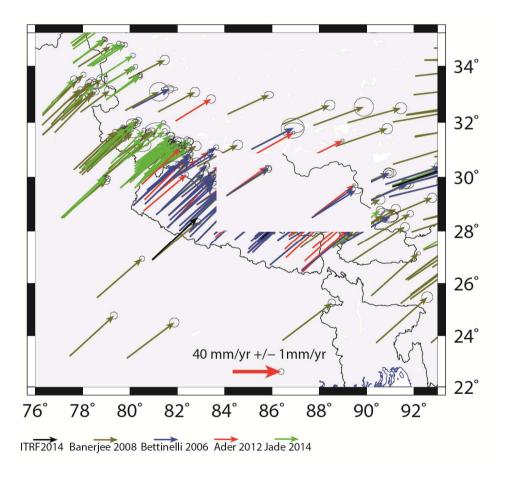
### **How the NDM works**

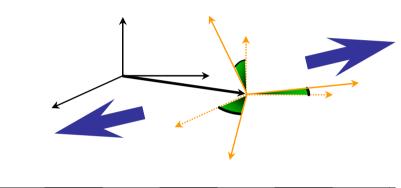


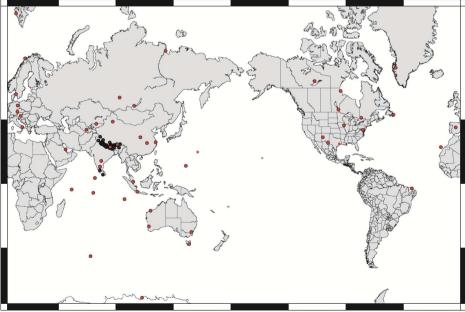


# **Secular velocity field**

Velocity from four recent studies were aligned with the ITRF2014 velocities

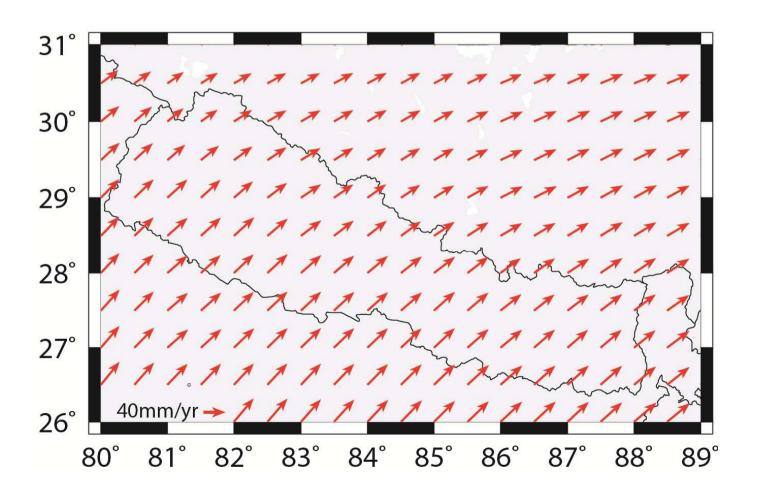




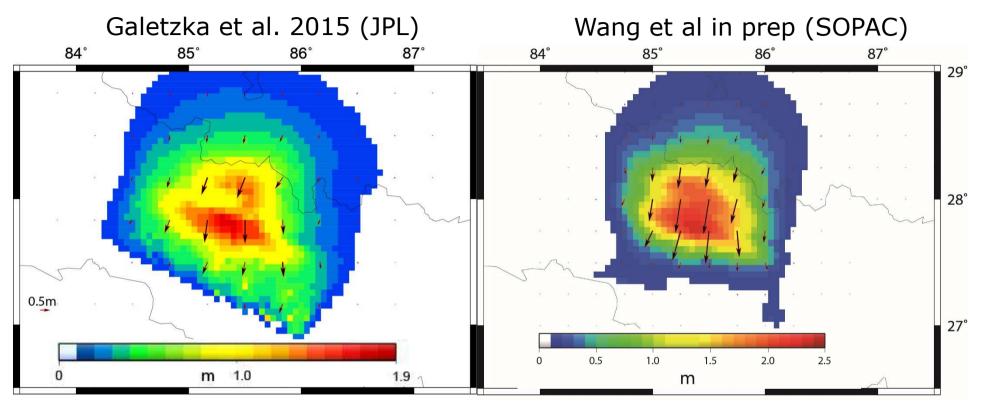


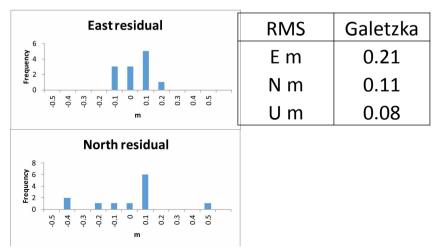
### velocity model

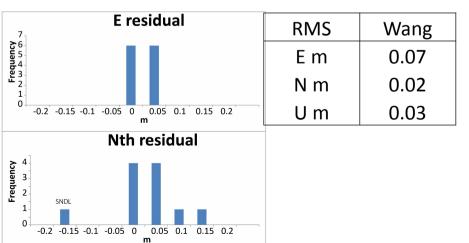
 The combined velocity field was used to produce a grid file with a density of 20 points/degree



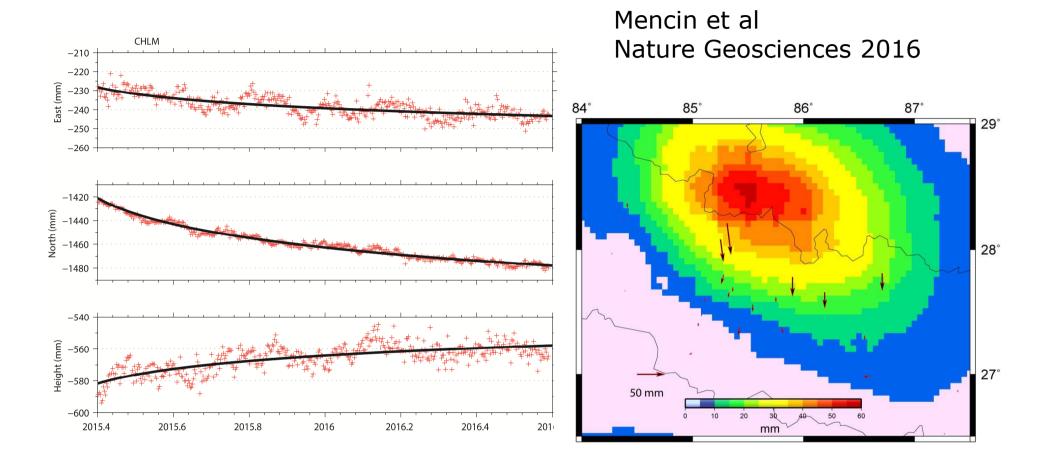
### Two possible models for Gorka Earthquake





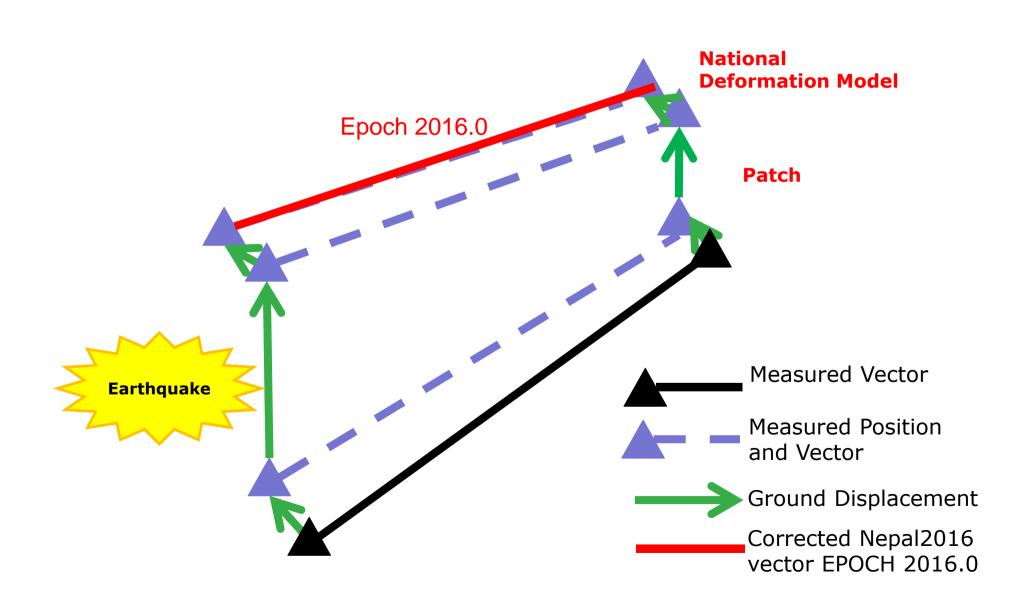


#### Post seismic relexation

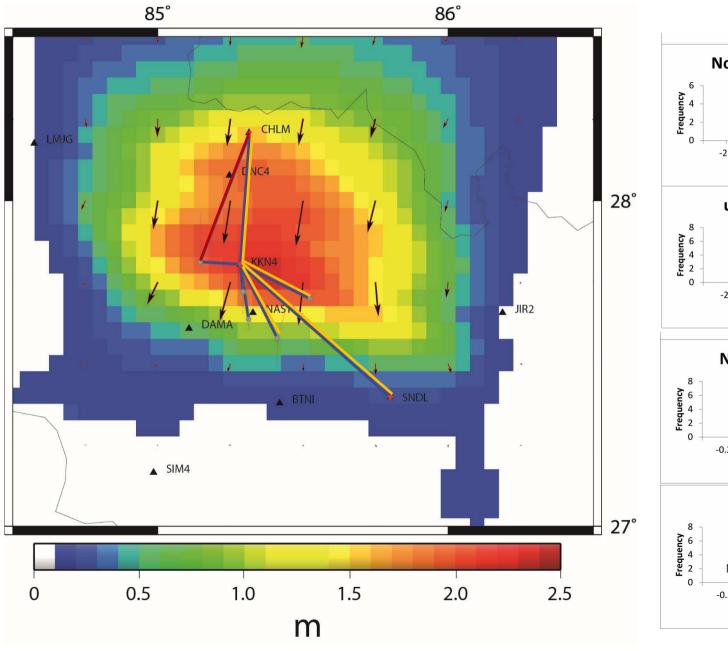


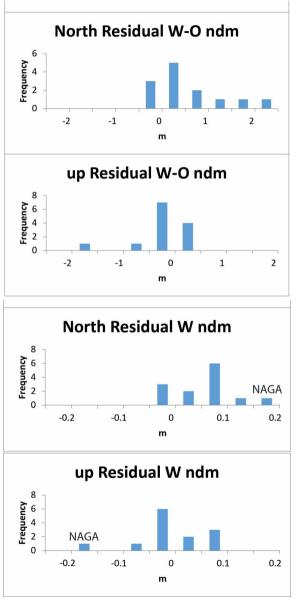
$$m_k(t) = v_k t + E_k H(t - t_i) + P_k H(t - t_i) (1 - e^{(t - t_i)/43})$$

# Deformation models in survey adjustments Example: Patch for an Earthquake



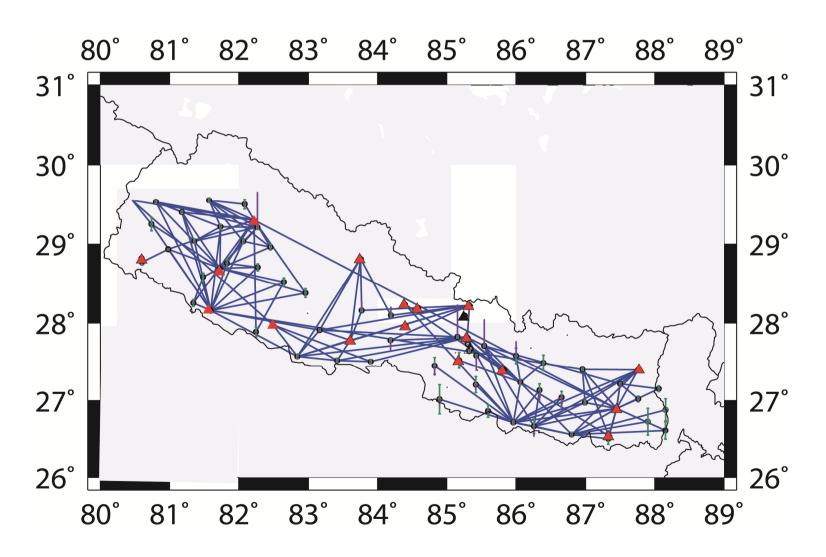
## Adjustment of GPS before and after the Gorkha Earthquake





## **First Order adjustment Preliminary results**

- SUE of constrained adjustment 1.25
- RMS Residuals E=0.01,n=0.01,u=0.05



- datum aligned to a realization of the ITRF
- common reference epoch after the recent sequence of earthquakes
- deformation model
  - Velocity model
  - Earthquake displacements
- Control
  - Top level control CORS network
  - Establish lower order control relative to the CORS
    - New marks surveyed with GPS
    - Readjust existing measurements
- correction grids to transform GIS coordinates from Nepal Everest into the new system.
- Support in commercial software

DONE -

\_TO DO\_\_